# Series 5E electromechanical axis 

Sizes 50, 65, 80<br>Available versions: standard axis, support axis, reinforced axis



Series 5E axes are mechanical linear actuators in which the rotary movement generated by a motor is converted into a linear movement by means of a toothed belt.
The Series $\mathbf{5 E}$, available in 3 sizes, $\mathbf{5 0 , 6 5}$ and 80 , is realized by means of a special self-supporting square profile, in which the components have been completely integrated, assuring compactness and light weight.
The presence of a recirculating ball guide grants high stiffness and resistance to external loads.

To protect the internal elements from potential contaminants from the external environment, the profile has been closed with a stainless steel plate. The axis is equipped with a magnet that makes it possible to use external proximity switches (Series CSH), allowing operations like homing or extra-stroke readings to be performed. Moreover, these actuators also have accessories in order to be used with inductive sensors. The Series 5E is equipped with specific interface kits making it possibleto connect the motor on 4 sides. The use with high dynamics and the possibility to realize multi-axis systems, make the Series 5E particularly suitable for the packaging and assembly sectors.
» Multiposition system with transmission of the movement with toothed belt
"Suitable for high dynamics
» Possibility to connect the motor on 4 sides

Large range of motor interfaces
» Possibility to use magnetic proximity switches and/ or inductive sensors
» IP 40
» Max stroke 6 meters
» Plates to realize multiaxis systems
» Presence of internal channels for re-lubrication

Large range of axis mounting accessories
»Sliders available: standard, long, double
»Supplied with protection plugs for end caps and slider's centering bushings
» Greasing nipples included

## GENERAL DATA

| Construction | electromechanical axis with toothed belt |
| :--- | :--- |
| Design | open profile with protection plate |
| Operation | multi-position actuator |
| Sizes | $50,65,80$ |
| Strokes | $50 \div 4000$ mm for size $50 ; 50 \div 6000$ mm for sizes 65 and 80 |
| Type of guide | internal, with recirculating balls (cage type) |
| Fixing | by means of slots on the profile and special clamps |
| Mounting motor | on all 4 sides |
| Operating temperature | $-10^{\circ} \mathrm{C} \div+50^{\circ} \mathrm{C}$ |
| Storage temperature | $-20^{\circ} \mathrm{C} \div+80^{\circ} \mathrm{C}$ |
| Protection class | IP 40 (available for versions A and D only) |
| Lubrication | centralized lubrification by means of internal channels |
| Repeatability | $\pm 0.05$ mm |
| Duty cycle | $100 \%$ |
| Use with external sensors | Series CSH magnetic switches in special slots or inductives by means of supports |

CODING EXAMPLE


## MECHANICAL CHARACTERISTICS

|  |  | Size 50 | Size 50 | Size 50 | Size 65 | Size 65 | Size 65 | Size 65 | Size 80 | Size 80 | Size 80 | Size 80 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| RECIRCULATING BALL GUIDE (CAGE TYPE) |  |  |  |  |  |  |  |  |  |  |  |  |
| Version |  | A | A | D | A | A | D | H | A | A | D | H |
| Type of slider |  | S | L | S | S | L | S | S | S | L | S | S |
| Number of guides |  | 1 | 1 | 1 | 1 | 1 | 1 | 2 | 1 | 1 | 1 | 2 |
| Number of RDS blocks | pcs | 2 | 3 | 2 | 2 | 3 | 2 | 4 | 2 | 3 | 2 | 4 |
| Fy , eq ${ }^{(A)}$ | N | 3400 | 5100 | 3400 | 8300 | 12450 | 8300 | 16600 | 13000 | 19500 | 13000 | 26000 |
| $\mathrm{Fz}, \mathrm{eq}{ }^{(\mathrm{A})}$ | $N$ | 3400 | 5100 | 3400 | 8300 | 12450 | 8300 | 16600 | 13000 | 19500 | 13000 | 26000 |
| Mx, eq ${ }^{\left({ }^{(1)}\right.}$ | Nm | 19.4 | 29 | 19.4 | 47.7 | 71.6 | 47.7 | 234.7 | 106 | 160 | 106 | 454 |
| My, eq ${ }^{(A)}$ | Nm | 91.7 | 183.5 | 91.7 | 283.2 | 564.7 | 282.3 | 564.7 | 626 | 1252 | 626 | 1252 |
| $\mathrm{Mz}, \mathrm{eq}^{(A)}$ | Nm | 91.7 | 183.5 | 91.7 | 283.2 | 564.7 | 282.3 | 564.7 | 626 | 1252 | 626 | 1252 |
| Max linear speed of mechanics ( $\mathrm{V}_{\text {max }}$ ) ${ }_{\text {a }}$ ( | $\mathrm{m} / \mathrm{s}$ | 5 | $2.5{ }^{\text {(8) }}$ | 5 | 5 | $2.5{ }^{(8)}$ | 5 | $2.5{ }^{(8)}$ | 5 | $2.5{ }^{\text {(B) }}$ | 5 | $2.5{ }^{\text {(8) }}$ |
| Max linear acceleration of mechanics ( $\mathrm{a}_{\max }$ ) | $\mathrm{m} / \mathrm{s}^{2}$ | 50 | $20^{(8)}$ | 50 | 50 | $20^{(8)}$ | 50 | $2.5{ }^{(8)}$ | 50 | $20^{(8)}$ | 50 | $20^{\text {(8) }}$ |
| PROFILE |  |  |  |  |  |  |  |  |  |  |  |  |
| Moment of surface inertia $\mathrm{I}_{\mathrm{y}}$ | $\mathrm{mm}^{4}$ | $1.89 \cdot 105$ | 1.89•105 | $1.89 \cdot 105$ | 4.94-105 | 4.94-105 | 4.94-105 | 4.94-105 | $1.23 \cdot 106$ | $1.23 \cdot 106$ | $1.23 \cdot 106$ | $1.23 \cdot 106$ |
| Moment of surface inertia $\mathrm{I}_{2}$ | $\mathrm{mm}^{4}$ | $2.48 \cdot 105$ | $2.48 \cdot 105$ | $2.48 \cdot 105$ | $6.97 \cdot 105$ | $6.97 \cdot 105$ | $6.97 \cdot 105$ | $6.97 \cdot 105$ | $1.68 \cdot 106$ | $1.68 \cdot 106$ | $1.68 \cdot 106$ | $1.68 \cdot 106$ |
| TOOTHED BELT |  |  |  |  |  |  |  |  |  |  |  |  |
| Type |  | 20 AT 5 HP | 20 AT 5 HP | - | 32 AT 5 HP | 32 AT 5 HP | - | 32 AT 5 HP | 32 AT 5 HP | 32 AT 5 HP | - | 32 AT 5 HP |
| Pitch | mm | 5 | 5 | - | 5 | 5 | - | 5 | $10$ | 10 | - | 10 |
| Max transmittable load | N | See the diagram | See the diagram | - | See the diagram | See the diagram | - | See the diagram | See the diagram | See the diagram | - | See the diagram |
| PULLEY |  |  |  |  |  |  |  |  |  |  |  |  |
| Effective diameter of the pulley | mm | 31.83 | 31.83 | - | 47.75 | 47.75 | - | 47.75 | 63.66 | 63.66 | - | 63.66 |
| Number of teeth | z | 20 | 20 | - | 30 | 30 | - | 30 | 20 | 20 | - | 20 |
| Linear movement per pulley round | mm/round | 100 | 100 | - | 150 | 150 | - | 150 | 200 | 200 | - | 200 |

## NOTES:

1. Check the nominal admissible torque
of the used motion transmission devices.
2. Details about directions of loads
and moments can be found in the
"EQUIVALENT LOAD" section.
${ }^{(A)}$ Value refers to a covered distance of 2000 Km with fully supported system.
${ }^{(8)}$ The "suggested" speed is not the mechanical limit of the unit but represents the best compromise between high load applied and high dynamics. In case of particular requirements, please contact our technical assistance (service@camozzi.com).

## SERIES 5E STROKE

## LEGEND：

C＝Stroke
SE＝Standard extra－stroke［5ES050．．$=30 \mathrm{~mm}$ ］
［5ES065．．$=30 \mathrm{~mm}$ ］
［5ES080．．$=30 \mathrm{~mm}$ ］
NOTES：
－Should an additional extra－stroke be required，it must be foreseen by the client．
－The slider should never work in stop on the header．


## SERIES 5E MATERIALS



| COMPONENTS | MATERIALS |
| :--- | ---: |
| 1．End cap | Aluminium alloy |
| 2．Pulley | Steel |
| 3．End cap bumper | Technopolymer |
| 4．Protection plate | Steel |
| 5．Slider | Aluminium alloy |
| 6．Bumper | Technopolymer |
| 7． Toothed belt | PU＋Steel |
| 8．Recirculating ball guide | Steel |
| Products designed for industrial applications．  <br> General terms and conditions for sale are available on www．camozzi．com．  |  |

## HOW TO CALCULATE THE LIFE OF SERIES 5E AXIS

The correct dimensioning of the Series 5E axis, used individually or in a cartesian system with several axes, you need to consider some facts, both static and dynamic.

## CALCULATION OF LIFE [km]

$\mathrm{L}_{\mathrm{eq}}=$ Life of the axis [km]
$\mathrm{f}_{\mathrm{l}}=$ load coefficient
$f_{w}=$ safety coefficient according to the working conditions

The loads acting on the actuator (Fy, Fz, Mx, My and Mz) that appear in the fl calculation are the average ones on the cycle. These are calculated by averaging the loads of each single phase as indicated in the equation of $P$.
$l_{s}=$ stroke $s_{1}=$ acc. phase; $s_{2}=$ constant speed phase; $s_{3}=$ deceleration phase
$\mathrm{P}=\mathrm{Mx} / \mathrm{My} / \mathrm{Mz} / \mathrm{Fy} / \mathrm{Fz}$
$f_{l}=\frac{|F y|}{F y, e q}+\frac{|F z|}{F z, e q}+\frac{|M x|}{M x, e q}+\frac{|M y|}{M y, e q}+\frac{|M z|}{M z, e q}$
$L_{e q}=\left(\frac{1}{f_{l} \cdot f_{w}}\right)^{3} \cdot 2000$


$$
P=\sqrt[3]{\frac{1}{l s} \cdot \sum_{i=1}^{n}\left(P_{i}^{3} \cdot s_{i}\right)}
$$

$$
P=\sqrt[3]{\frac{1}{l s} \cdot\left(P_{1}^{3} \cdot s_{1}+P_{2}^{3} \cdot s_{2}+P_{3}^{3} \cdot s_{3}\right)}
$$

## EQUIVALENT LOAD

$\mathrm{Fy}=$ Force acting along the Y -axis [ N ]
$\mathrm{Fz}=$ Force acting along the Z-axis [N]
$\mathrm{h}=$ fixed distance for 5 E axis [mm]
$\mathrm{Mx}=$ Moment along X -axis [ Nm ]
$\mathrm{My}=$ Moment along Y -axis [ Nm ]
$\mathrm{Mz}=$ Moment along Z -axis Z [ Nm ]
Here you can find the " $h$ " values, valid for version $A$ :

- h = 45.5 mm (5ES050)
- $\mathrm{h}=56.0 \mathrm{~mm}$ (5ES065)
-h = 69.5 mm (5ES080)
Here you can find the "A" and "B" values, valid for version $H$ :
"A" = 56.0 mm "B" 32.9 mm (5ES050)
"A" = 57.0 mm "B" 45.0 mm (5ES065)
"A" = 71.6 mm "B" 51.6 mm (5ES080)


GRAPH OF THE SERVICE LIFE


## HOW TO CALCULATE THE SERVICE LIFE OF 5ES050TBL0500AS1 - HORIZONTAL MOUNTING


$\mathrm{acc}=\mathrm{dec}=6 \mathrm{~m} / \mathrm{s}^{2} \quad \mathrm{~V}=0.6 \mathrm{~m} / \mathrm{s}$
$\mathrm{s}_{1}=\mathrm{s}_{3}=30 \mathrm{~mm}$
$\mathrm{M}=15 \mathrm{~kg}$
$\mathrm{s}=500 \mathrm{~mm}$
bM = 86 mm
$\mathrm{f}_{\mathrm{w}}=1$

## CALCULATION OF APPLIED LOADS

$F_{y}=0$
$F_{z}=M \cdot g=15 \cdot 9.81=147 \mathrm{~N}$
$M_{x_{1 ; 2 ; 3}}=F_{z} \cdot b_{M}=147 \cdot 0.086=12.7 \mathrm{Nm}$
$M_{y_{1 ; 3}}=F_{x} \cdot\left(h_{M}+h\right)=M \cdot a \cdot\left(h_{M}+h\right)=$
$=15 \cdot 6 \cdot(0.05+0.045)=8.55 \mathrm{Nm}$
$M_{y_{2}}=F_{x} \cdot\left(h_{M}+h\right)=M \cdot a \cdot\left(h_{M}+h\right)=$
$=15 \cdot 0 \cdot(0.05+0.045)=0 \mathrm{Nm}$
$M_{z_{1 ; 3}}=F_{x} \cdot b_{M}=M \cdot a \cdot b_{M}=$
$=15 \cdot 6 \cdot 0.086=7.74 \mathrm{Nm}$
$M_{z_{2}}=F_{x} \cdot b_{M}=M \cdot a \cdot b_{M}=$
$=15 \cdot 0 \cdot 0.086=0 \mathrm{Nm}$
$M_{y}=\sqrt[3]{\frac{1}{l s} \cdot\left(M y_{1}{ }^{3} \cdot s 1+M y_{2}{ }^{3} \cdot s 2+M y_{3}{ }^{3} \cdot s 3+\cdots+M y_{n}{ }^{3} \cdot s n\right)}=$
$=\sqrt[3]{\frac{1}{500} \cdot\left(8.55^{3} \cdot 30+0 \cdot 440+8.55^{3} \cdot 30\right)}=4.22 \mathrm{Nm}$
$M_{Z}=\sqrt[3]{\frac{1}{500} \cdot\left(7.74^{3} \cdot 30+0 \cdot 440+7.743 \cdot 30\right)}=3.82 \mathrm{Nm}$
$f l=\frac{|F y|}{F y, e q}+\frac{|F z|}{F z, e q}+\frac{|M x|}{M x, e q}+\frac{|M y|}{M y, e q}+\frac{|M z|}{M z, e q}=$
$=\frac{0}{3400}+\frac{147}{3400}+\frac{12.7}{19.4}+\frac{4.22}{91.7}+\frac{3.82}{91.7}=0.785$

## HOW TO CALCULATE THE SERVICE LIFE

Once the fl value has been calculated, the service life value can be obtained from the graph or by using the formula:


## HOW TO CALCULATE THE SERVICE LIFE OF 5ES065TBL0750AS1 - VERTICAL MOUNTING


$\mathrm{acc}=\mathrm{dec}=10 \mathrm{~m} / \mathrm{s}^{2} \quad \mathrm{v}=0.8 \mathrm{~m} / \mathrm{s}$
$\mathrm{s}_{1}=\mathrm{s}_{3}=32 \mathrm{~mm}$
$\mathrm{ls}=750 \mathrm{~mm}$
$\mathrm{f}_{\mathrm{w}}=1.5$

## CALCULATION OF APPLIED LOADS

$$
\begin{aligned}
& F_{y}=0 \mathrm{~N} \\
& F_{z}=0 \mathrm{~N} \\
& M_{x_{12: 2}}=0 \mathrm{Nm} \\
& M_{y_{1}}=F_{x} \cdot\left(h_{M}+h\right)=M \cdot(g+a) \cdot\left(h_{M}+h\right)= \\
& =50 \cdot(9.81+10) \cdot(0.056+0.0795)=134.2 \mathrm{Nm} \\
& M_{y_{2}}=F_{x} \cdot\left(h_{M}+h\right)=M \cdot(g+a) \cdot\left(h_{M}+h\right)= \\
& =50 \cdot(9.81+0) \cdot(0.056+0.0795)=66.5 \mathrm{Nm} \\
& M_{y_{3}}=F_{x} \cdot\left(h_{M}+h\right)=M \cdot(g+a) \cdot\left(h_{M}+h\right)= \\
& =50 \cdot(9.81-10) \cdot(0.056+0.0795)=1.3 \mathrm{Nm}^{*}
\end{aligned}
$$

$$
\begin{aligned}
& M_{z_{1}}=F_{x} \cdot b_{M}=M \cdot(g+a) \cdot b_{M}= \\
& =50 \cdot(9.81+10) \cdot 0.12=118.9 \mathrm{Nm} \\
& M_{z_{2}}=F_{x} \cdot b_{M}=M \cdot(g+a) \cdot b_{M}= \\
& =50 \cdot(9.81+0) \cdot 0.12=58.9 \mathrm{Nm} \\
& M_{z_{3}}=F_{x} \cdot b_{M}=M \cdot(g+a) \cdot b_{M}= \\
& =50 \cdot(9.81-10) \cdot 0.12=1.14 \mathrm{Nm}^{*} \\
& M_{y}=\sqrt[3]{\frac{1}{750} \cdot\left(134.2^{3} \cdot 32+66.5^{3} \cdot 686+1.3^{3} \cdot 32\right)}=71.9 \mathrm{Nm} \\
& M_{z}=\sqrt[3]{\frac{1}{750} \cdot\left(118.9^{3} \cdot 32+58.9^{3} \cdot 686+1.14^{3} \cdot 32\right)}=63.7 \mathrm{Nm} \\
& f l=\frac{|F y|}{F y, e q}+\frac{|F z|}{F z, e q}+\frac{|M x|}{M x, e q}+\frac{|M y|}{M y, e q}+\frac{|M z|}{M z, e q}= \\
& =\frac{0}{8300}+\frac{0}{8300}+\frac{71.9}{324}+\frac{63.7}{324}+\frac{0}{55}=0.42
\end{aligned}
$$

*N.B: Positive sign because for each phase, the values are considered in absolute value.

## HOW TO CALCULATE THE SERVICE LIFE

Once the fl value has been calculated, the service life value can be obtained from the graph or by using the formula:

$$
L e q=\left(\frac{1}{f l \cdot f w}\right)^{3} \times 2000=\left(\frac{1}{0.42 \cdot 1.5}\right)^{3} \times 2000=8013 \mathrm{~km}
$$



## HOW TO CALCULATE THE DRIVING TORQUE [Nm]

$\mathrm{F}_{\mathrm{A}}=$ Total force acting from outside [N]
$F_{E}=$ Force to be applied externally [ N ]
$\mathrm{g}=$ Gravitational acceleration $\left(9.81 \mathrm{~m} / \mathrm{s}^{2}\right)$
$\mathrm{m}_{\mathrm{E}}=$ Mass of the body to move [kg]

$$
C_{T O T}=C_{M 1}+C_{M 2}+C_{M 3}
$$

$$
F_{A}=F_{E}+m_{E} \cdot a
$$

$$
C_{M 1}=\frac{F_{A} \cdot D_{P}}{2}
$$

$\mathrm{J}_{\text {Tor }}=$ Moment of inertia of rotating components [ $\mathrm{kg} \cdot \mathrm{m}^{2}$ ]
$\dot{\omega}=$ Angular acceleration [rad $/ \mathrm{s}^{2}$ ]
$a=$ Axis linear acceleration [m/s ${ }^{2}$ ]
$\mathrm{C}_{\mathrm{M} 2}=$ Driving torque due to rotating components [ Nm ]

$$
\dot{\omega}=\frac{2 \cdot a}{D_{P}}
$$

$$
C_{M 2}=J_{T O T} \cdot \dot{\omega}
$$

$\mathrm{F}_{\mathrm{T}}=$ Force needed to move translating components [ N ]
$F_{T F}=$ Force needed to move fixed-length translating components [ N ]
$\mathrm{F}_{\mathrm{TV}}=$ Force needed to move variable-length translating components [ N ]
$m_{c 1}=$ Mass of fixed-length translating components [kg]
$\mathrm{K}_{\mathrm{TV}}=$ Mass coefficient of variable-length
translating components [kg/mm]
$\mathrm{C}_{\mathrm{M} 3}=$ Driving torque due to translating components [Nm]
$\mathrm{K}_{\mathrm{TI}}=$ Mass coefficient of variable-length ..... components with the interaxis [kg/mm]
C = Stroke [mm]
I = Interaxis [mm]

$$
\begin{gathered}
F_{T T}=F_{T F}+F_{T V} \\
F_{T F}=m_{C 1} \cdot a \\
F_{T V}=K_{T V} \cdot C \cdot a \\
C_{M 3}=\frac{F_{T T} \cdot D_{P}}{2}
\end{gathered}
$$

| Mod. | $\mathrm{J}_{\text {TOT }}\left[\mathrm{Kg} \cdot \mathrm{mm}^{2}\right.$ ] | $\mathrm{m}_{\mathrm{c} 1}[\mathrm{~kg}]$ | $\mathrm{K}_{\mathrm{TV}}[\mathrm{Kg} \cdot \mathrm{m}]$ | $\mathrm{K}_{\mathrm{tI}}[\mathrm{Kg} / \mathrm{m}]$ |
| :---: | :---: | :---: | :---: | :---: |
| 5E050...AS1 | 48.76 | 0.51 | 0.14 | 0.00 |
| 5E050...AL1 | 48.76 | 0.80 | 0.14 | 0.00 |
| 5E050...AS2 | 48.76 | 1.01 | 0.14 | 0.38 |
| 5E050...DS1 | 0.00 | 0.40 | 0.00 | 0.00 |
| 5E050...DS2 | 0.00 | 0.87 | 0.00 | 0.31 |
| 5E065...AS1 | 372.07 | 1.27 | 0.21 | 0.00 |
| 5E065...AL1 | 372.07 | 1.83 | 0.21 | 0.00 |
| 5E065...AS2 | 372.07 | 2.53 | 0.21 | 0.41 |
| 5E065...DS1 | 0.00 | 1.01 | 0.00 | 0.00 |
| 5E065...HS1 | 372.07 | 2.84 | 0.21 | 0.00 |
| 5E065...DS2 | 0.00 | 2.1 | 0.00 | 0.31 |
| 5E080...AS1 | 1130.28 | 2.69 | 0.34 | 0.00 |
| 5E080...AL1 | 1130.28 | 3.84 | 0.34 | 0.00 |
| 5E080...AS2 | 1130.28 | 5.38 | 0.34 | 0.48 |
| 5E080...DS1 | 0.00 | 2.15 | 0.00 | 0.00 |
| 5E080...HS1 | 1130.28 | 5.61 | 0.34 | 0.00 |
| 5E080...DS2 | 0.00 | 4.41 | 0.00 | 0.31 |

TRANSMISSIBLE FORCE

According to the size of the axis and the selected speed, the transmissible force of the toothed belt has the following limits.


HOW TO CALCULATE MAX DEFLECTION AND VERIFY DISTANCE BETWEEN SUPPORTS

The electromechanical axis 5E is a self-supporting system and can also be used between 2 or more supports without the need of a continuous contact surface.
The maximum value of the deflection generated by the deformation of the system must never exceed the following calculation:
$\mathrm{f}_{\text {max }}=$ Maximum admissible deflection [mm]
$C_{\text {max }}=$ Maximum stroke of axis 5 E [mm]

$$
f_{\max }=c_{\max } \cdot 5 \cdot 10^{-4}
$$

NOTE: for a quicker choice, please see the graphs on the following pages.

|  |  |  |  |
| :---: | :---: | :---: | :---: |
| APPLICATION | ACCELERATION $\left[\mathrm{m} / \mathrm{s}^{2}\right]$ | SPEED $[\mathrm{m} / \mathrm{s}]$ | $\mathrm{f}_{\mathrm{w}}$ |
| light | $<10$ | $<1.5$ | $1 \div 1.25$ |
| normal | $10 \div 25$ | $1.5 \div 2.5$ | $1.25 \div 1.5$ |
| heavy | $>25$ | $>2.5$ | $1.5 \div 3$ |

## Deflection according to the distance of the supports - version A




Size 050
$\mathrm{f}=$ deflection generated between the supports [mm] d = distance between the supports [mm]


Size 065
$\mathrm{f}=$ deflection generated between the supports [mm] $d=$ distance between the supports [mm]


Size 080
$\mathrm{f}=$ deflection generated between the supports [mm] $d=$ distance between the supports [mm]

## Deflection according to the distance of the supports - version H




Size 065
$\mathrm{f}=$ deflection generated between the supports [mm] $d=$ distance between the supports [mm]


Size 050
$f=$ deflection generated between the supports [mm] $d=$ distance between the supports [mm]


Size 080
$\mathrm{f}=$ deflection generated between the supports [mm]
$d$ = distance between the supports [mm]

## ACCESSORIES FOR SERIES 5E



Side clamping bracket Mod. BGS


Interface plate - Series 6E cylinder on slider


Kit to fix the inductive sensor

## 4

Parallel connection kit


Perforated side clamping bracket Mod. BGA


Interface plate - profile side on slider, left pos.


Kit to connect the gearbox GB Mod. FR


Interface plate - slider on slider


Interf. plate - profile side on slider, right pos.


Kit to connect the gearbox, enhanced series


Interface plate - profile on slider


Fixed interface plate


Kit to connect the gearbox, enhanced series (size 80)


5E/5V connection flange


Centering ring Mod. TR-CG


Interface plate - profile on slider - long arm


Interface plateGuide S. 45 / Cyl. S. 6E


All accessories are supplied separately from the axis.

Electromechanical axis Mod．5E．．．AS1


NOTE：
＊We recommend a coupling with a shaft of tolerance h8．
20imension T2 in size 50 is not indicated because there is only one slot．
？Dimension Y indicates the hole for centralized lubrication by means of grease．

Taglia $A$




|  |  |  |
| :--- | :---: | :---: |
| Size | WEIGHT STROKE ZERO［kg］ | STROKE WEIGHT PER METER［kg／m］ |
| $\mathbf{5 0}$ | 2.15 | 3.35 |
| 65 | 4.6 | 5.4 |
| 80 | 8.9 | 5.9 |



NOTE:
*We recommend a coupling with a shaft of tolerance h8.
D Dimension T 2 in size 50 is not indicated because there is only one slot.

- Dimension Y indicates the hole for centralized lubrication by means of grease

| Taglia | A | B | E | E1 | F | ${ }_{0} \mathrm{Gl}$ | G2 | H | L1 | L2 | M1 | M2 | M3 | N | P1 | P2 | K1 | J1 | K2 | J2 | T1 | T2 | T3 | Y | W | Z1 | Z2 | S1 | S2 | S3 | S4 | V1 | V2 | V3 | V4 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 50 | 32.5 | 15 | 8.5 | 100 | 50 | 6 | 2 | 60 | 354 | 238 | 200 | 200 | 48 | 5 | 30 | 40 | M4 | 7 | M3 | 5 | 20 | [ | 10 | [ | 230 | 8 | 4 | 5,4 | 6,8 | 3,65 | 5 | 6 | 12 | 4 | 5.5 |
| 65 | 35 | 20 | 8.5 | 125 | 65 | 8 | 3 | 75 | 438 | 288 | 250 | 250 | 63 | 5 | 40 | 53 | M5 | 8 | M3 | 6 | 23.5 | 18 | 10 | [ | 280 | 8 | 4 | 5,4 | 6,8 | 3,65 | 5 | 6 | 12 | 4 | 5.5 |
| 80 | 35 | 30 | 11.5 | 165 | 80 | 10 | 3 | 95 | 548 | 368 | 330 | 330 | 78 | 8 | 55 | 64 | M6 | 12 | M4 | 8.5 | 25 | 25 | 10 | [ | 360 | 8 | 4 | 5,4 | 6,8 | 3,65 | 5 | 8 | 16.5 | 6.8 | 9 |


| Size | WEIGHT STROKE ZERO [kg] | STROKE WEIGHT PER METER [kg/m] |
| :--- | :---: | :---: |
| $\mathbf{5 0}$ | 1.81 | 3.00 |
| $\mathbf{6 5}$ | 3.58 | 4.88 |
| 80 | 7.05 | 5.31 |

Electromechanical axis Mod. 5E...HS1


NOTE:
*We recommend a coupling with a shaft of tolerance h8.
[0] Dimension Y indicates the hole for centralized lubrication by means of grease.

 80353068686.538630 .560 .526 .51658011039554836833011911523165643133 .5 M5 12M48.5 M5 10 252510 回46840.5360 $8 \quad 45.46 .83 .655816 .56 .89$

|  |  |  |
| :--- | :---: | :---: |
| Size | WEIGHT STROKE ZERO [kg] | STROKE WEIGHT PER METER [kg/m] |
| 65 | 7.08 | 6.86 |
| 80 | 14.86 | 8.34 |

Electromechanical axis Mod. 5E...AL1

E...ALI

NOTE:
*We recommend a coupling with a shaft of tolerance h8.
0 Dimension T2 in size 50 is not indicated because there is only one slot.
[0] Dimension Y indicates the hole for centralized lubrication by means of grease.





| Size | WEIGHT STROKE ZERO [kg] | STROKE WEIGHT PER METER [kg/m] |
| :--- | :---: | :---: |
| $\mathbf{5 0}$ | 2.58 | 3.35 |
| $\mathbf{6 5}$ | 5.56 | 5.4 |
| $\mathbf{8 0}$ | 11.10 | 5.9 |

Electromechanical axis Mod. 5E...AS2


NOTE:
*We recommend a coupling with a shaft of tolerance h8.
2Dimension T2 in size 50 is not indicated because there is only one slot.
目Dimension Y indicates the hole for centralized lubrication by means of grease.





| Size | CL min | CL max | Max applicable stroke | WEIGHT STROKE ZERO [kg] | WEIGHT PER METER [kg/m] (valid for stroke and interaxis increases) |
| :--- | :---: | :---: | :---: | :---: | :---: |
| $\mathbf{5 0}$ | 250 | 2000 | Smax $=4262-\mathrm{CL}$ | 3.49 |  |
| $\mathbf{6 5}$ | 300 | 2000 | Smax $=6212-\mathrm{CL}$ | 7.35 | 5.4 |
| 80 | 400 | 2000 | Smax $=6132-\mathrm{CL}$ | 14.68 | 5.9 |

## Side clamping bracket Mod. BGS

Material: Aluminium


Supplied with:
2x clamps
TABLE NOTE:

* according to the span (max admissible deflection) recommended value 500 mm


| Mod. | Size | A | B | C1 | C2 | ${ }_{9}$ D1 | ${ }_{6} \mathrm{D} 2$ | E1 | E2 | H1 | H2 | P | Weight (g) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| BGS-5E-M5 | 50 | 25 | 66 | 68 | * | 5.5 | 9 | 82 | 45 | 6.4 | 6 | 10 | 45 |
| BGS-5E-M5 | 65 | 25 | 81 | 85 | * | 5.5 | 9 | 97 | 45 | 6.4 | 6 | 10 | 45 |
| BGS-5E-M5 | 80 | 25 | 96 | 100 | * | 5.5 | 9 | 112 | 45 | 6.4 | 6 | 10 | 45 |
| BGS-5E-M6 | 50 | 25 | 66 | 68 | * | 6.5 | 10.5 | 82 | 45 | 5.4 | 7 | 10 | 40 |
| BGS-5E-M6 | 65 | 25 | 81 | 85 | * | 6.5 | 10.5 | 97 | 45 | 5.4 | 7 | 10 | 40 |
| BGS-5E-M6 | 80 | 25 | 96 | 100 | * | 6.5 | 10.5 | 112 | 45 | 5.4 | 7 | 10 | 40 |

Perforated side clamping bracket Mod. BGA
Material: Aluminium


Supplied with:
$2 x$ clamps with perforation
TABLE NOTE:

* according to the span
(max admissible deflection) recommended value 500 mm


| Mod. | Size | A1 | A2 | B | C1 | C2 | ${ }_{9}$ D1 | ${ }_{0}$ D2 | E1 | E2 | H1 | H2 | P | Weight (g) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| BGA-5E-M5 | 50 | 40 | 50 | 66 | 68 | * | 5.5 | 9 | 82 | 65 | 6.4 | 6 | 7.5 | 60 |
| BGA-5E-M5 | 65 | 40 | 50 | 81 | 85 | * | 5.5 | 9 | 97 | 65 | 6.4 | 6 | 7.5 | 60 |
| BGA-5E-M5 | 80 | 40 | 50 | 96 | 100 | * | 5.5 | 9 | 112 | 65 | 6.4 | 6 | 7.5 | 60 |
| BGA-5E-M6 | 50 | 40 | 50 | 66 | 68 | * | 6.5 | 10.5 | 82 | 65 | 5.4 | 7 | 7.5 | 55 |
| BGA-5E-M6 | 65 | 40 | 50 | 81 | 85 | * | 6.5 | 10.5 | 97 | 65 | 5.4 | 7 | 7.5 | 55 |
| BGA-5E-M6 | 80 | 40 | 50 | 96 | 100 | * | 6.5 | 10.5 | 112 | 65 | 5.4 | 7 | 7.5 | 55 |

Interface plate - slider on slider


The kit includes:
$1 x$ interface plate
$8 \times$ screws $+8 \times$ lock washers to connect the plate on the slider of the main axis
$4 x$ screws $+4 x$ lock washers to connect the plate on the slider of the secondary axis


| Mod. | Size | A1 | A2 | D | E | S |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| XY-S65-S50 | 65 | 150 | 150 | 55 | 70 | 12 |
| XY-S80-S50 | 80 | 190 | 150 | 55 | 85 | 12 |
| XY-S80-S65 | 80 | 190 | 150 | 70 | 85 | 12 |

Interface plate - profile on slider


The kit includes:
1x interface plate
$8 \times$ screws $+8 \times$ lock washers
to connect the plate on the
slider of the main axis
4x clamps
8 x screws +8 x lock washers
to connect the secondary
axis on the plate by means of clamps


|  |  |  |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Mod. | Size | A1 | A2 | D | E |  |  |
| XY-S65-P50 | 65 | 150 | 162 | 85 | 70 | Weight (g) |  |
| XY-S80-P50 | 80 | 190 | 182 | 85 | 85 | 12 |  |
| XY-S80-P65 | 80 | 190 | 185 | 100 | 85 | 12 |  |

Interface plate－profile on slider－long arm

The kit includes：
$1 x$ interface plate
$8 x$ screws $+8 x$ lock washers to connect plate on the slider of the main axis
4x clamps
$8 x$ screws $+8 x$ lock washers to connect plate on the slider of the secondary axis by means of clamps


| Mod． | Size | A1 | A2 | D | E | S | Weight（g） |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| XY－S50－P50－T | 50 | 162 | 130 | 50 | 85 | 12 | 600 |
| XY－S65－P50－T | 65 | 170 | 150 | 65 | 85 | 12 | 750 |
| XY－S65－P65－T | 65 | 185 | 170 | 65 | 100 | 12 | 800 |
| XY－S80－P50－T | 80 | 185 | 190 | 85 | 85 | 12 | 960 |
| XY－580－P65－T | 80 | 185 | 190 | 85 | 100 | 12 | 1010 |
| XY－S80－P80－T | 80 | 200 | 190 | 85 | 120 | 12 | 1100 |

Interface plate－Series 6E cylinder on slider


The kit includes：
$1 x$ interface plate
$4 \times$ screws＋4x lock washers
to connect the plate on the
slider of the axis
$2 x$ clamps
$4 \times$ screws $+4 x$ lock washers
to fix the Series 6E cylinder by means of clamps


| Mod． | Size | A1 | A2 | Weight（g） |
| :--- | :---: | :---: | :---: | :---: |
| XY S50－6E32 | 50 | 72 | 101 | 11 |
| XY－S65－6E32 | 65 | 72 | 101 | 11 |
| XY－S65－6E40 | 65 | 85 | 101 | 11 |
| XY S65－6E50 | 65 | 95 | 110 | 12 |
| XY－S80－6E32 | 80 | 75 | 101 | 12 |
| $X Y-S 80-6 E 40$ | 80 | 85 | 101 | 12 |
| $X Y-S 80-6 E 50$ | 80 | 95 | 110 | 12 |
| $X Y$ S80－6E63 | 80 | 106 | 110 | 12 |

Interface plate - profile side on slider - left position


The kit includes: $1 x$ interface plate 8 x screws +8 x lock washers to connect the plate on the slider of the main axis, screws and nuts for slot to connect the plate on the slider of the secondary axis


| Mod. | Size | A1 | A2 | D | E | S | Nr of holes | Weight (g) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| XY-S50-LL50 | 50 | 130 | 145 | 50 | 55 | 11 | 4 | 450 |
| XY-S65-LL50 | 65 | 160 | 160 | 50 | 70 | 11 | 4 | 500 |
| XY-S65-LL65 | 65 | 170 | 180 | 65 | 70 | 12 | 8 | 550 |
| XY-S80-LL50 | 80 | 200 | 175 | 50 | 85 | 12 | 4 | 750 |
| XY-S80-LL65 | 80 | 210 | 195 | 65 | 85 | 12 | 8 | 870 |
| XY-S80-LL80 | 80 | 210 | 195 | 80 | 85 | 12 | 8 | 900 |

Interface plate - profile side on slider - right position


| Mod. | Size | A1 | A2 | D | E | S | Nr of holes | Weight (g) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| XY-S50-LR50 | 50 | 130 | 145 | 50 | 55 | 11 | 4 | 450 |
| XY-S65-LR50 | 65 | 160 | 160 | 50 | 70 | 11 | 4 | 500 |
| XY-S65-LR65 | 65 | 170 | 180 | 65 | 70 | 12 | 8 | 550 |
| XY-S80-LR50 | 80 | 200 | 175 | 50 | 85 | 12 | 4 | 750 |
| XY-S80-LR65 | 80 | 210 | 195 | 65 | 85 | 12 | 8 | 870 |
| XY-S80-LR80 | 80 | 210 | 195 | 80 | 85 | 12 | 8 | 900 |

Interface plate - Anti-rotation guides S. 45 / Cylinders S. 6E on slider


The kit includes:
$1 x$ interface plate
$8 \times$ screws $+8 \times$ lock washers to connect the plate on the slider
4x screws to connect the cylinder


| Mod. | Size | A1 | A2 | D | E | S | ${ }_{0} \mathrm{M}^{(H 10)}$ | Y | Weight (g) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| XY-S50-45N32 | 50 | 124 | 130 | 50 | 49 | 12 | 30 | 75 | 350 |
| XY-S65-45N32 | 65 | 139 | 170 | 65 | 49 | 12 | 30 | 82.5 | 480 |
| XY-S65-45N40 | 65 | 147.5 | 170 | 65 | 55 | 12 | 35 | 87 | 500 |
| XY-S65-45N50 | 65 | 157 | 170 | 65 | 66.5 | 12 | 40 | 91.5 | 530 |
| XY-580-45N40 | 80 | 167.5 | 190 | 85 | 55 | 12 | 35 | 97 | 660 |
| XY-580-45N50 | 80 | 177 | 190 | 85 | 65 | 12 | 40 | 101.5 | 690 |
| XY-580-45N63 | 80 | 190.5 | 190 | 85 | 75 | 12 | 45 | 110 | 740 |

Fixed interface plate


The kit includes:
$1 x$ interface plate
4x interfas
$8 \times$ clamps clamps on the plate


| Mod. | Size | A1 | A2 | ${ }_{0} \mathrm{D} 1$ | ${ }_{0}$ D2 | H | 11 | 12 | 5 | Weight (g) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| X-P50 | 50 | 95 | 140 | 9 | 5.5 | 6 | 45 | 80 | 8 | 275 |
| X-P65 | 65 | 120 | 140 | 10.5 | 6.5 | 7 | 50 | 100 | 10 | 430 |
| X-P80 | 80 | 120 | 160 | 13.5 | 8.5 | 9 | 50 | 100 | 12 | 570 |

5E/5V connection flange


| Mod. | Size | X1 | X2 | X3 | X4 | X5 | A1 | A2 | E | D | S | Weight (g) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| YZ-50-5V50 | 50 | 105 | 121 | 147 | 79 | - | 81 | 130 | 64.5 | 63 | 13 | 335 |
| YZ-65-5V50 | 65 | 112.5 | 136.5 | 16 | 87 | 124.5 | 99.5 | 140 | 64.5 | 76.5 | 13 | 445 |
| YZ-65-5V65 | 65 | 130 | 154 | 179.5 | 104.5 | - | 101.5 | 140 | 84.5 | 76.5 | 13 | 460 |
| YZ-80-5V50 | 80 | 120.5 | 146.5 | 185.5 | 81.5 | 133.5 | 118 | 190 | 64.5 | 78 | 13 | 635 |
| YZ-80-5V65 | 80 | 137.5 | 163.5 | 202.5 | 98.5 | 150.5 | 118 | 190 | 84.5 | 78 | 15 | 770 |
| YZ-80-5V80 | 80 | 141 | 183.5 | 222.5 | 118.5 | - | 120 | 190 | 99.5 | 78 | 15 | 825 |

## Centering ring Mod．TR－CG

Supplied with：
$2 x$ centering rings in steel


| Mod． | M（h8） | N | P |
| :--- | :---: | :---: | :---: |
| TR－CG－04 | $\emptyset 4$ | $\emptyset 2.6$ | 2.5 |
| TR－CG－05 | $\emptyset 5$ | $\emptyset 3.1$ | 3 |
| TR－CG－06 | $\emptyset 6$ | $\emptyset 4.1$ | 4 |
| TR－CG－08 | $\emptyset 8$ | $\emptyset 5.1$ | 5 |
| TR－CG－10 | $\emptyset 10$ | $\emptyset 6.1$ | 6 |
| TR－CG－12 | $\emptyset 12$ | $\emptyset 8.1$ | 6 |

Kit to fix the inductive sensor


The kit includes：
$1 \times$ sensor dog
$2 x$ screws to fix the sensor dog
$1 x$ sensor supporting plate $2 x$ screws to connect the sensor supporting plate $2 x$ nuts for the slot


$$
a^{\prime}=\frac{0}{5}-i
$$

| Mod． | Size | A | C | D | E | H1 | H2 | 1 | L | M | N1 | N2 | ${ }_{0} 0$ | P | Q | R | S | Weight（g） |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| SIS－M5－50／65 | 50－65 | 27 | 10 | 20 | 3.5 | 13 | 8.5 | 5.5 | 22 | 12 | 14.5 | 21 | 5.5 | 8 | 14 | 26 | 10 | 10 |
| SIS－M8－65 | 65 | 27 | 10 | 20 | 3.5 | 13 | 8.5 | 5.5 | 25 | 15 | 10.5 | 24 | 8.5 | 10 | 18.5 | 30 | 15 | 10 |
| SIS－M5－80 | 80 | 45 | 15 | 20 | 4.5 | 16 | 10.5 | 5.5 | 22 | 12 | 14.5 | 21 | 5.5 | 8 | 14 | 26 | 10 | 15 |
| SIS－M8－80 | 80 | 45 | 15 | 20 | 4.5 | 16 | 10.5 | 5.5 | 25 | 15 | 10.5 | 24 | 8.5 | 10 | 18.5 | 30 | 15 | 15 |

Kit to connect the Series FR gearbox


The kit includes:
$1 x$ connection flange $4 \times$ screws $+4 \times$ lock washers to connect the flange
$1 \times$ locking set
$4 x$ screws $+4 x$ lock washers to connect the gearbox

| Mod. | Size | Gearbox | E1 | E2 | 5 | ${ }_{0}$ D1 | ${ }_{\otimes} \mathrm{D2}^{(\mathrm{H7})}$ | LT | BCD | T1 | T2 | M | B | (A) | $\mathrm{J}\left(\mathrm{Kgmm}{ }^{2}\right)$ | Weight (g) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FR-5E-50 | 50 | GB-040 | 48 | 43 | 6 | 10 | 26 | 26 | 34 | 10 | 10 | 4 | 5.5 | 14 | 1.50 | 85 |
| FR-5E-65 | 65 | GB-060 | 63 | 60 | 7 | 14 | 40 | 40 | 52 | 11 | 11 | 5 | 7.4 | 30 | 5.49 | 140 |
| FR-5E-80 | 80 | GB-080 | 80 | 80 | 11 | 20 | 60 | 60 | 70 | 17 | 4 | 6 | 8.4 | 125 | 31.20 | 325 |

${ }^{(A)}$ value refers to ideal mounting and operating conditions. For further details, please contact service@camozzi.com

Kit to connect the gearbox - enhanced series (sizes 50, 65)


| DIMENSIONS |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Mod. | Size | Gearbox | ${ }_{0} \mathrm{D} 1$ | ${ }_{0} \mathrm{D} 2^{(H 7)}$ | A | LS | ${ }_{\bullet}{ }^{\text {BCD }}$ | B | C | E | M | K | (A) | (B) | $\mathrm{J}\left(\mathrm{Kgmm}{ }^{2}\right)$ | Weight (g) |
| FRH-5E-50 | 50 | GB-060 | 14 | 40 | 4 | 35.3 | 52 | 8 | 51 | 50 | 5 | 7.4 | 12.5 | 25 | 13 | 170 |
| FRH-5E-65 | 65 | GB-080 | 20 | 60 | 4 | 40.3 | 70 | 10 | 59 | 65 | 6 | 9.4 | 17 | 34 | 50 | 530 |

${ }^{(A)}$ Continuously applicable torque, under ideal mounting and operating conditions. For further details, please contact service@camozzi. com
${ }^{(8)}$ Torque applicable for short intervals, under ideal mounting and operating conditions. For further details, please contact service@ camozzi.com

The kit includes：
$2 x$ connection flanges
$4 x$ screws $+4 x$ lock washers
$1 x$ expansion coupling
$4 x$ screws $+4 x$ lock washers
to fix the axis
$4 x$ screws $+4 x$ lock washers to fix the profile $4 x$ nuts $+4 x$ screws to fix the gearbox


| Mod． | Size | Gearbox | ${ }_{6} \mathrm{D1}^{(\mathrm{H} 7)}$ | ${ }_{0} \mathrm{D} 2$ | A | LS | ${ }_{0}{ }^{\text {BCD }}$ | B | C | ${ }_{6} \mathrm{E}$ | K | G | （A） | （B） | $\mathrm{J}\left(\mathrm{Kgmm}{ }^{2}\right)$ | Weight（g） |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FRH－5E－80 | 80 | GB－120 | 20 | 80 | 5 | 47.8 | 100 | 10 | 68 | 115 | 12 | 100 | 60 | 120 | 140 | 1000 |

${ }^{(A)}$ Continuously applicable torque，under ideal mounting and operating conditions．For further details，please contact service＠camozzi． com
${ }^{(B)}$ Torque applicable for short intervals，under ideal mounting and operating conditions．For further details，please contact service＠ camozzi．com

Direct connection kit for Stepper motor


The kit includes： 1x MTS－24 connection flange 4x screws＋ 4 lock washers 1x expansion coupling $1 x$ bushing（not present in FS－5E－50－0024）


| Mod． | Size | Motor | ${ }_{0} \mathrm{D} 1$ | A | B | F1 | F2 | E | LS | TG | K | ${ }_{6} \mathrm{M}$ | H | N | （A） | （B） | $\mathrm{J}\left(\mathrm{Kgmm}{ }^{2}\right)$ | Weight（g） |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FS－5E－50－0024 | 50 | MTS－24－．．． | 8 | 4 | 37 | 47 | 45 | 60.5 | 21.3 | 47.1 | M4 | 38.1 | 2.5 | 2.5 | 12.5 | 25 | 13 | 125 |
| FS－5E－65－0024 | 65 | MTS－24－．．． | 8 | 4 | 36 | 65 | 60 | 60.5 | 22.8 | 47.1 | M4 | 38.1 | 2.5 | 2.5 | 12.5 | 25 | 13 | 200 |

${ }^{(A)}$ Continuously applicable torque，under ideal mounting and operating conditions．For further details，please contact service＠camozzi． com
${ }^{(8)}$ Torque applicable for short intervals，under ideal mounting and operating conditions．For further details，please contact service＠ camozzi．com

## Slot nut for sensor



Supplied with:
2x nuts


|  |  |  |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Size | M | N | 0 | S | T |
| PCV-5E-CS-M3 | $50-65-80$ | M3 | 10.3 | 6.1 | 2.5 | 3.5 |
| PCV-5E-CS-M4 | $50-65-80$ | M4 | 10.3 | 6.1 | 2.5 | 3.5 |

Slot nut 6 - rectangular type


| Mod. |  | M | N | 0 | S |
| :--- | :---: | :---: | :---: | :---: | :---: |
| PCV-5E-C6-M4Q | $50-65$ | M4 | 8 | 7 | 2 |

Slot nut 6 for front insertion


| Mod. | Size | M | N | 0 | S | T |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| PCV-5E-C6-M4R | $50-65$ | M4 | 12 | 6 | 3 | 4.5 |

Slot nut 8 with flexible flap


| Mod. | Size | M | N | 0 | S | T |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| PCV-5E-C8-M5 | 80 | M5 | 16 | 11.5 | 3.5 | 4.5 |
| PCV-5E-C8-M6 | 80 | M6 | 16 | 11.5 | 3.5 | 4.5 |

## Parallel connection kit

The kit includes:
1x parallel shaft
$2 x$ expansion couplings

## EXAMPLE:

PS-5E-65-1400 corresponds to a parallel connection for axes positioned at interaxis $\mathrm{I}=1400 \mathrm{~mm}$




INTERAXIS ACCORDING TO THE MAXIMUM ADMISSIBLE TORQUE


Size 50x50
$C_{\text {max }}=$ max applicable torque
$i=$ interaxis between the two 5 E axes
$01=$ lag error 0.1 mm
$02=$ lag error 0.2 mm
$03=$ lag error 0.3 mm


Size $65 \times 65$
$C_{\text {max }}=$ max applicable torque
$\mathrm{i}=\mathrm{in}$ teraxis between the two 5E axes
$01=\operatorname{lag}$ error 0.1 mm
$02=\operatorname{lag}$ error 0.2 mm
$03=\operatorname{lag}$ error 0.3 mm


Size $80 \times 80$
$C_{\text {max }}=$ max applicable torque
$i=i n t e r a x i s ~ b e t w e e n ~ t h e ~ t w o ~ 5 E ~ a x e s ~$
$01=\operatorname{lag}$ error 0.1 mm
$02=\operatorname{lag}$ error 0.2 mm $03=\operatorname{lag}$ error 0.3 mm

