# Automation

SERIES RPGA SPRUE GRIPPERS

## Sprue grippers - Size 20 Series RPGA

Angular, not self-centering, single-acting, Normally Open Models available: Flat Finger, Curved Finger, Short Finger, Flat Finger with sensor slot, Curved Finger with sensor slot



Thanks to a piston with a size of 20mm and to the direct transfer of the force from the piston to the fingers, Series RPGA guarantees a strong and a safe grip. Their technical features ensure a high gripping force and make these grippers particularly suitable in the removal of injection molded items. The surface treatments on each metallic part make this series very wear resistant.

D and E models are provided with a finger having a slot for the installation of an inductive sensor.

## **GENERAL DATA**

Operation	single-acting, Normally Open		
Materials	anodized aluminium body and fingers, PU seals		
Working pressure	2.5 bar ÷ 8 bar		
Working temperature	0°C ÷ 60°C		
Max frequency	2.5 Hz		
Lubrication	Not necessary		
Air ports	G1/8		
Media	Filtered air, without lubrication		
Size	20 mm		
Weights	120 g (models A and B); 125 g (models C, D, E)		
Gripping torque at 6 bar	310 Ncm		
Opening torque at 6 bar	25 Ncm		
Gripping force at 6 bar	90 N		
Closing time without load	20 ms		

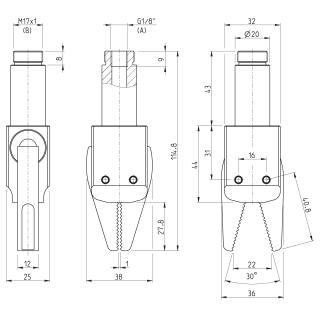
### **CODING EXAMPLE**

RPGA	-	20	-	Α		
RPGA	SERIES					
20	SIZE: 20					
Α	TYPE OF CONSTRUCTION: A = Flat finger B = Curved finger C = Short finger with mounting holes for extensions D = Flat finger for sensor E = Curved finger for sensor					

## Flat finger gripper Mod. RPGA-20-A - dimensions







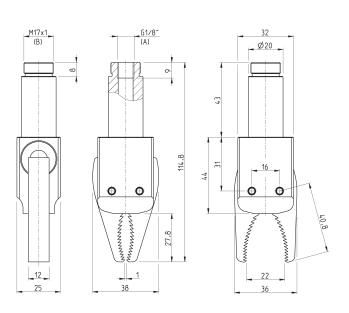
A = connection port B = fixing thread

Mod. RPGA-20-A

## Curved finger gripper Mod. RPGA-20-B - dimensions







A = connection port B = fixing thread

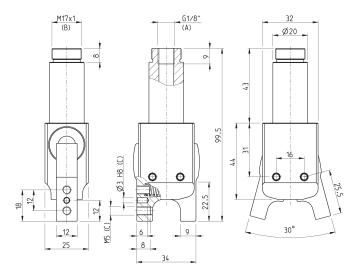
A = connection port B = fixing thread C = fixing holes

Mod. RPGA-20-B

## Short finger gripper Mod. RPGA-20-C - dimensions











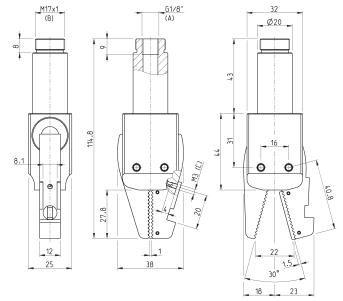
## Flat finger gripper with sensor slot Mod. RPGA-20-D - dimensions



Note: the sensor is not supplied with the gripper

ME

PNZ4



A = connection port B = fixing thread C = sensor fixing hole

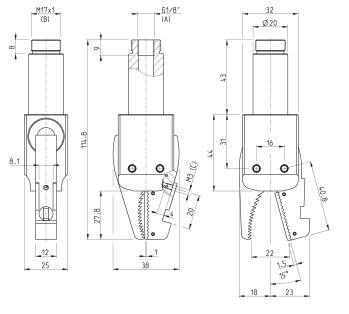
### Curved finger gripper with sensor slot Mod. RPGA-20-E - dimensions



Mod. RPGA-20-D

Note: the sensor is not supplied with the gripper





A = connection port B = fixing thread C = sensor fixing hole

