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The undersigned, representative of the following manufacturer

<b>Camozzi Automation S.p.A.</b>	
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herewith declares that the products:

<b>INTEGRATED FIELD-ORIENTED CONTROL DRIVE SERIES DRVI</b>  <i>versions reported on the last page</i>
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The object of the declaration described above is in conformity with the relevant Union harmonisation legislation:

2014/30/EU	DIRECTIVE 2014/30/EU OF THE EUROPEAN PARLIAMENT AND OF THE COUNCIL of 26 February 2014 on the harmonisation of the laws of the Member States relating to electromagnetic compatibility
2011/65/EU	DIRECTIVE 2011/65/EU OF THE EUROPEAN PARLIAMENT AND OF THE COUNCIL of 8 June 2011 on the restriction of the use of certain hazardous substances in electrical and electronic equipment

and that all the standards and/or technical specifications indicated on page 2 are applied.

This declaration of conformity is issued under the sole responsibility of the manufacturer

Brescia, Italy 22/10/2024

**Camozzi Automation SPA**  
**Product Certification Manager**  
**Guerrini Fabrizio**


Declaration in accordance with ISO / IEC 17050-1

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Reference relative to the standards and/or technical specifications, or parts of them, used for the present declaration of compliance

Reference Number	Date of issue	Title
CEI EN IEC 61800-3	2022	Adjustable speed electrical power drive systems - Part 3: EMC requirements and specific test methods for PDS and machine tools

Camozzi Spa declares that the "homogeneous materials" used in the products are in compliance with directive

**2011/65/EU (RoHS II)**

Particularly some materials used for components of this product line are included in 2011/65/UE-Annex III-Application exempted from the restriction in Article 4 (1)

- Exemption:

**6(c)** Copper alloy containing up to 4 % lead by weight

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Series DRVI : Sample of coding

DRVI	-	23	ST	012	-	0	E	-	PN	
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DRVI	SERIES
23	MOTOR FLANGE 23 = Nema 23 24 = Nema 24
ST	MOTOR TYPE ST = stepper EC = brushless DC
012	MOTOR TORQUE 012 = 1,2 Nm (Nema 23) 022 = 2,2 Nm (Nema 24) 125 = 125 W (solo per EC)
0	MOTOR BRAKE 0 = without brake B =with brake
E	MOTOR FEEDBACK E = absolute single turn encoder
PN	COMMUNICATION PROTOCOL PN = Profinet CO = CanOpen EC = EtherCAT EI = EtherNet/IP
	SAFETY FUNCTION = Standard