



USE AND MAINTENANCE MANUAL

Series D Valve Island Fieldbus and Series CX4 EtherNet/IP



Made in Italy

The products are in compliance with the requirements stated in the following directives:

- 2004/108/EC

The products comply either fully, or for the applicable parts, with the following standards:

- IEC EN 61131-2

The EC Compliance Declarations can be downloaded from www.camozzi.it

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1 General recommendations

Please comply with the recommendations for safe use described in this document:

- Some hazards can only be associated with the product after it has been installed on the machine/equipment. It is the responsibility of the end user to identify these hazards and reduce the risks associated with them.
- For information regarding the reliability of the components, contact Camozzi Automation.
- Read the information in this document carefully before using the product.
- Keep this document in a safe place and close at hand for the whole of the product's life cycle.
- Pass this document on to any subsequent owner or user.
- The instructions in this manual must be observed in conjunction with the instructions and additional information concerning the product in this manual, available from the following reference links:
 - Website <http://www.camozzi.com>
 - Camozzi general catalogue
 - Technical assistance service
- Assembly and commissioning must be performed exclusively by qualified and authorised personnel on the basis of these instructions.
- It is the responsibility of the system/machine designer to ensure the correct selection of the most suitable pneumatic component according to the intended application.
- Use of appropriate personal protective equipment is recommended to minimise the risk of physical injury.
- For all situations not contemplated in this manual and in situations in which there is the risk of potential damage to property, or injury to persons or animals, contact Camozzi for advice.
- Do not make unauthorised modifications to the product. In this case, any damage or injury to property, persons or animals will be the responsibility of the user.
- It is recommended to comply with all safety regulations that apply to the product.
- Never intervene on the machine/system until you have verified that all working conditions are safe.
- Before installation or maintenance, ensure that the required safety locks are active, and then disconnect the electrical mains (if necessary) and system pressure supply, discharging all residual compressed air from the circuit and deactivating residual energy stored in springs, condensers, recipients and gravity.
- After installation or maintenance, the system pressure and electrical power supply (if necessary) must be reconnected, and the regular operation and sealing of the product must be checked. In the event of leaks or malfunction, the product must not be used.
- The product may only be used in observance of the specifications provided; if these requirements are not met, the product may only be used upon authorisation by Camozzi.
- Avoid covering the equipment with paint or other substances that may reduce heat dissipation.

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1.1 Product storage and transport

- Adopt all measures possible to avoid accidental damage to the product during transport, and when available use the original packaging.
- Observe the specified storage temperature range of $-10 \div 50$ °C.

1.2 Use

- Make sure that the distribution network voltage and all operating conditions are within the permissible values.
- The product may only be used in observance of the specifications provided; if these requirements are not met, the product may only be used upon authorisation by Camozzi.
- Follow the indications shown on the identification plate.

1.3 Limitations of use

- Do not exceed the technical specifications given in paragraph 2 (General characteristics and conditions of use) and in the Camozzi general catalogue.
- Do not install the product in environments where the air itself may cause hazards.
- With the exception of specific intended uses, do not use the product in environments where direct contact with corrosive gases, chemicals, salt water, water or steam may occur.


1.4 Maintenance

- Incorrectly performed maintenance operations can compromise the good working order of the product and harm surrounding persons.
- Check conditions to prevent sudden release of parts, then suspend the power supply and allow residual stresses to discharge before taking action.
- Assess the possibility of having the product serviced by a technical service centre.
- Never disassemble a live unit.
- Isolate the product electrically before maintenance.
- Always remove accessories before maintenance.
- Always wear the correct personal protective equipment as envisaged by local authorities and in compliance with current legislation.
- In the event of maintenance, or replacement of worn parts, exclusively use the original Camozzi kits and ensure that operations are performed by specialised and authorised personnel. Otherwise product approval will be rendered invalid.

1.5 Ecological Information


- At the end of the product's life cycle, it is recommended to separate the materials for recycling.
- Follow the waste disposal regulations in force in your country.
- The product and relative parts all comply with the ROHS and REACH standards.


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2 General characteristics and conditions of use

PNEUMATIC SECTION					
Versions		D1	D2	D4	D5
Valve construction		Spool with seals			
Valve functions		5/2 monostable and bistable 2x3/2 NC 2x3/2 NO 5/3 CC - CP - CO 1X3/2 NC+1X3/2 NO			
Materials	Body	Aluminium			
	Spool	Aluminium			
	Sub-base	Technopolymer	Technopolymer	Aluminium	Technopolymer
	End cover	Technopolymer			
	Seal	HNBR			
Connections		Uses 2 and 4 Thread (only D4) or bushings, tube size variable according to the pitch			
Temperature		0 ÷ 50 °C			
Air feature		Compressed air filtered and not lubricated in class 7.4.4 according to ISO 8573-1: 2010. If lubrication is required, use only oils with max. viscosity. 32 Cst and the version with external servo drive. The servo drive air quality must be in class 7.4.4 according to ISO 8573-1: 2010 (do not lubricate).			
Valve pitch		10.5 mm	16 mm	25 mm	10.5 e 16 mm
Working pressure		-0.9 ÷ 10 bar			
Drive pressure		2.5 ÷ 7 bar 4.5 ÷ 7 bar (with working pressure higher than 6 bar for the 2x3/2 version)			
Flow rate		250 NL/min (10.5 mm)	950 NL/min (16 mm)	2000 NL/min (25 mm)	250 NL/min (10.5 mm) / 950 NL/min (16 mm)
Assembly position		Any			
Degree of protection		IP65			

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ELECTRICAL SECTION	
Power and bus connection type	M12 – 5 poli
Supply voltage Logic	24 V DC +/-25%
Supply voltage Power	24 V DC +/-10%
Valve maximum absorption	2.5 A
Maximum no. valve positions	64 (128 coils)
Coil power	1W (reduction to 0.5W after 100ms)
Maximum cable length	20 m
Protocol	EtherNet/IP 

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3 General description of the system

The CX4 EtherNet/IP module is a device for driving valves and/or managing digital and/or analogue I/O by connecting it to a EtherNet/IP network. The CX4 consists of power connectors, input and output connectors for the EtherNet/IP field bus and LEDs for system diagnostics. It is possible to connect the Series D coil valves on the right side of the CX4, while on the left side it is possible to connect the digital and analogue I/O modules.

Nomenclature

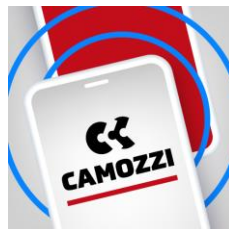
*The CX4 module can be used by just connecting the input and output modules; in this case the device will take the name of **Series CX4 Stand Alone** module. If coil valves (with or without I/O modules) are connected to the CX4 on the pneumatic side, the device becomes a valve island and is called **Series D Valve Island Fieldbus**.*

The CX4 module, both in Series CXA and Series D valve island fieldbus configurations, is a solution dedicated to Industry 4.0 because it is a SMART device capable of connecting to other devices or networks (ex. WiFi, USB, NFC) for information exchange. The system can transmit data of the main variables, the diagnostics of all the components of which the island is made. In addition, the system can configure the island and each connected module. The smart interfaces with the system are:


- Camozzi UVIX (Universal visual interface), a software that can be installed on a PC/server/gateway used by USB or included in a company network and accessible from other PCs (ch. **Error! Reference source not found.**).



- NFCamApp (NFC Camozzi Application), smartphone application for Android and iOS (ch. **Error! Reference source not found.**).



NOTE. In addition, in the Series D Serial valve island configuration, the system has **COILVISION** technology which monitors the correct operation of the coil valve. Each actuation of the coil, in different cyclic configurations and environmental conditions, is analysed to acquire information which, when processed by software algorithms, allows the health of the component to be diagnosed and predicted (par. 8.1.2).

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4 Recipients

The manual is intended exclusively for qualified experts in control and automation technologies who have experience in the installation, commissioning, programming and diagnostics of programmable logic controllers (PLCs) and fieldbus systems.

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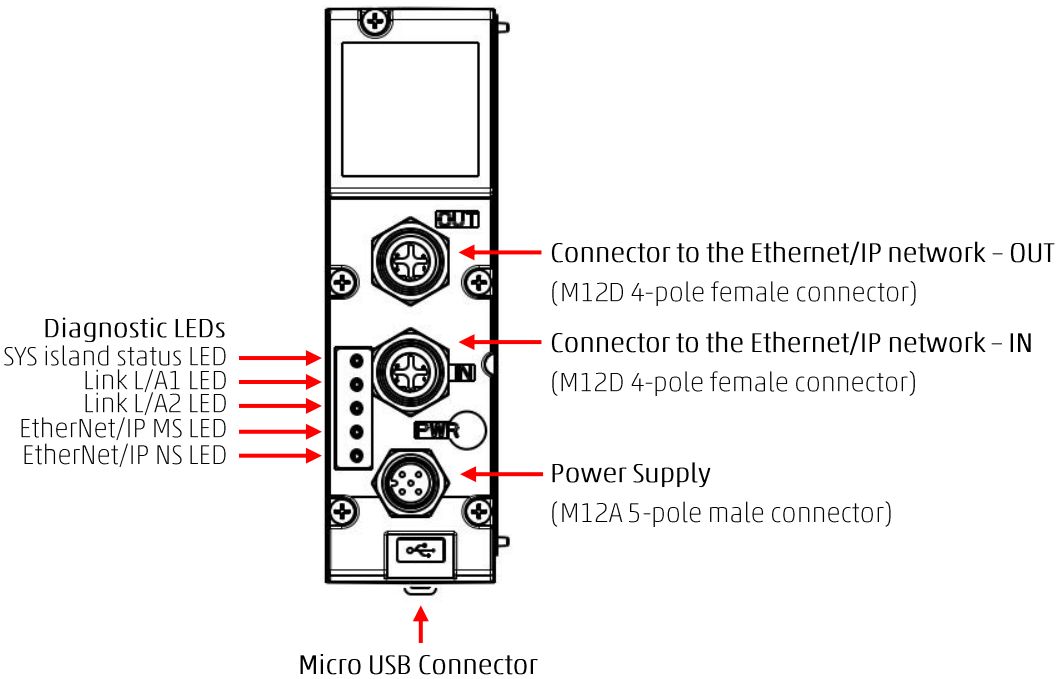
5 Installation

5.1 General installation instructions

For reasons of operator safety and to prevent functional damage to the system, before starting any installation or maintenance operation, disconnect:

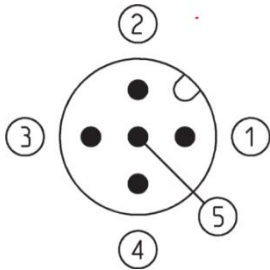
- The air supply.
- The power supply of the control electronics and outputs/coil valves.


5.2 Connecting and warning components



5.2.1 Power Supply Connector

The Power Supply connector is a 5-pole M12A male.

Pin	Signal	Description	Symbol
1	L24V	24 Vdc power supply (logic, digital inputs, analogue I/O): connect to the positive pole of the 24 Vdc power supply (referred to GND).	
2	P24V	24 Vdc power supply (digital outputs and valves): connect to the positive pole of the 24 Vdc power supply (referred to GND).	
3	GND	Common (reference pin 1 and 2): connect to the negative pole of the 24 Vdc power supply (compulsory).	
4	EARTH	Earth connection	
5	NC	Not Connected	

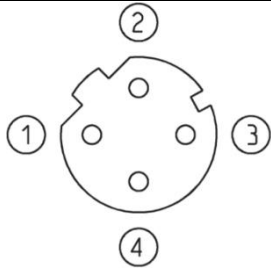
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NOTE. To connect the system to the mains it is recommended to use the connectors from the Camozzi catalogue:

- CS-LF04HB, straight connector for power supply.

5.2.2 Connector to the EtherNet/IP network

The connectors for the EtherNet/IP network (IN and OUT) are M12D 4-pole female.

Pin	Signal	Description	Symbol
1	TD+	Transmission data (+)	
2	RD+	Reception data (+)	
3	TD-	Transmission data (-)	
4	RD-	Reception data (-)	

NOTE. To avoid malfunctions due to faulty wiring, it is recommended to connect the system to the EtherNet/IP network using the pre-wired cables from the Camozzi catalogue:

- CS-SB04HB-D100, co-moulded cable with straight M12D connector, length 1m.
- CS-SB04HB-D500, co-moulded cable with straight M12D connector, length 5m.
- CS-SB04HB-DA00, co-moulded cable with straight M12D connector, length 10m.

To connect to the controller, the following cable from the Camozzi catalogue can be used:


- CS-SE04HB-F500, co-moulded cable with RJ45 – M12D connector.

5.2.3 USB Connector

The USB communication connector is a standard micro version. The connector allows the CX4 to be connected to the UVIX interface for monitoring or configuration.

NOTE. The dedicated USB connector can be found in the Camozzi catalogue:

- G11W-G12W-2, standard cable with micro-USB connector length 2m.

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5.3 Power supply

The power supply is separated into *logic* (L24V), which allows the communication buses, the sub-bases of the pneumatic part and the I/O modules to be powered, and into *power* (P24V), which powers the valves and digital outputs. Therefore, for the system to work, it is essential to connect the *logic* power supply, otherwise the CX4 remains off. The two separate power supplies make it possible, if necessary, to disconnect the power supply to the valves while the bus power line remains active. The lack of *power* supply is signalled by the flashing red SYS island status LED. This problem is also signalled through a message via the network to provide for proper alarm management.

If the loads or inputs connected to the initial node require tighter tolerances of the supply voltage value, the node power supply voltage must respect these.

NOTE. The nominal power supply voltage of the CPU module is 24 Vdc \pm 10%.

5.3.1 Voltage drop in the valve island (rules for activating the coils)

In normal standard operation, the coil valves are activated, for 100 ms, with a power of 1 W (@ 24 V the absorbed current is therefore 41.6 mA). Subsequently, the coil valves are kept activated by reducing the absorbed power to 50% of the initial value, by means of a PWM control technique.

The permitted power supply voltage for the series D valve island is 24 Vdc \pm 10%, therefore the useful range is 21.6 Vdc \div 26.4 Vdc. The currents absorbed by the coil valve coils corresponding to the power supply range are 39 mA \div 48 mA (in typical conditions) in the first 100 ms of activation and subsequently 19.5 mA \div 24 mA in the power reduction phase due to the use of PWM.

The continuous operation of the valve island is guaranteed for a maximum absorption of 2.5 A.


In the worst conditions (maximum current absorption for 26.4 Vdc power supply) it is possible to activate up to 50 coils simultaneously with all the valves of the island off. Subsequently, it is possible to proceed by using the following formula:

$$\text{No. of coils to be controlled simultaneously} = 50 - (0.6 \times \text{No. active coils})$$

Example

- If 10 coils are already active, 44 coils can be activated simultaneously.
- If 20 coils are already active, 38 coils can be activated simultaneously.

NOTE. The maximum number of simultaneously active coils is 80. Each subsequent activation with respect to the previous group of coils must happen after 150 ms.


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5.4 Connectable accessories

Series D pneumatic coil valves or I/O modules can be connected to the CX4 module.

Here is the complete list of devices that can be connected to the CX4, with the respective references to the technical details in the manual.

- Series D sub-bases and coil valves in three different sizes (par. 8.1)
- 8- or 16-channel digital input modules (par. 8.2).
- 8- or 16-channel digital output modules (par. Error! Reference source not found.).
- Analog input modules (par. Error! Reference source not found.):
 - RTD modules (par. 8.4.4).
 - Thermocouple modules (par. 8.4.5).
 - Bridge modules (par. 8.4.6).
 - Voltage/Current modules (par. 8.4.7).
- Analog output modules (par. 8.5).

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5.5 Assembly

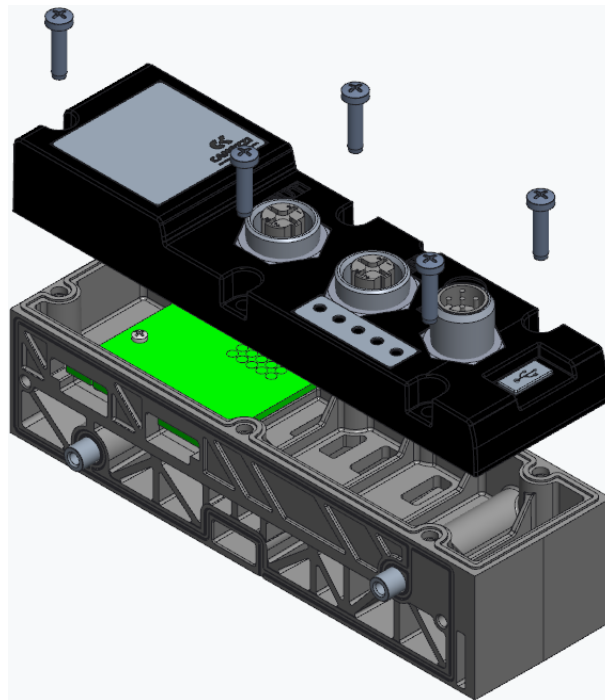
5.5.1 Dismantling and fitting CX4 module

Dismantle the CX4 module as follows:

1. Switch off the power supply of the CX4 module to avoid problems for the device or user.
2. Loosen the 5 screws.
3. Pull the cover of the CX4 module carefully and without tilting from the manifold base.

Fit the CX4 module as follows:

1. Switch off the operating voltage supply of the CX4 module to avoid problems for the device or user.
2. Make sure that the gaskets are tight and not damaged.
3. Push the cover of the CX4 module carefully and without tilting as far as possible into the manifold base.
4. Tighten the 5 screws (Torque max 0.6 Nm).

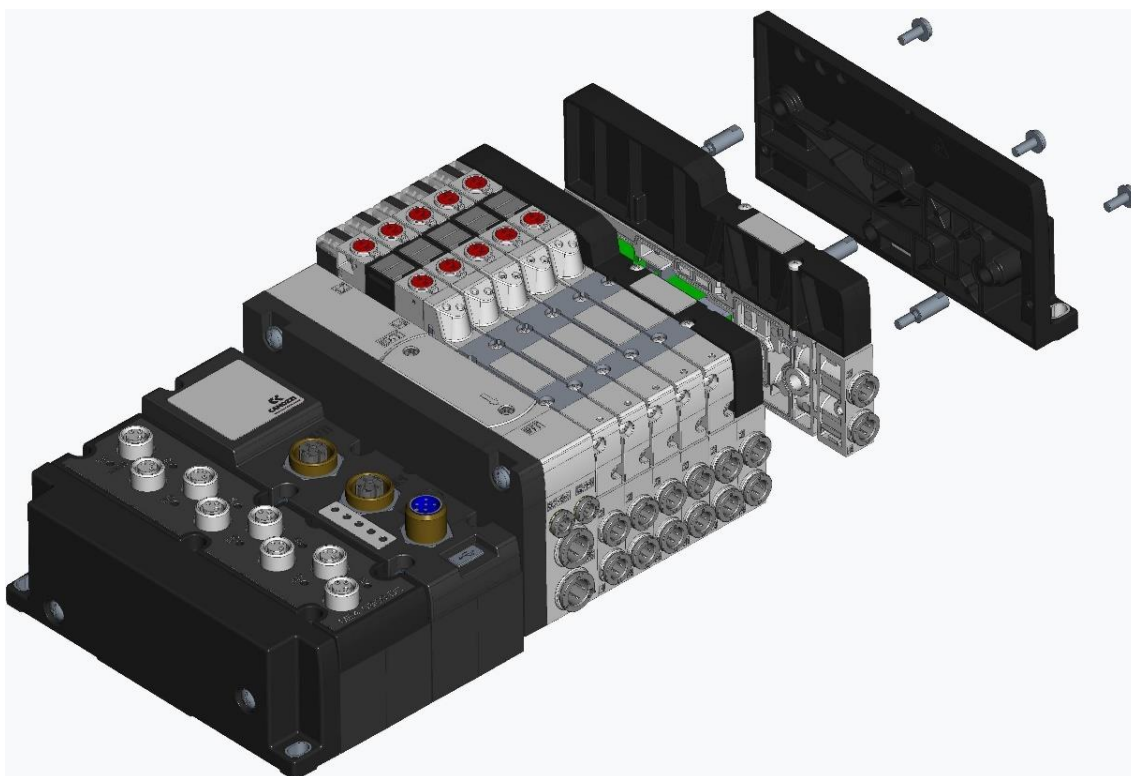


NOTE. After an island modification, the mapping procedure is required (par. 0).

5.5.2 Series D subbases assembly

Dismantle and fit the Series D subbases as follows:

1. Switch off the power supply of the CX4 module to avoid problems for the device or user.
2. Unscrew the 3 screws to the cover at the end of the island and open the valves subbases pack.
3. Remove the valves subbases from the tie-rods and replace with the new modules.
4. Push the valves subbases as far as possible to allow a correct electrical contact.
5. Mount the cover at the end of the island and tighten the 3 screws (Torque max 0.9 Nm)



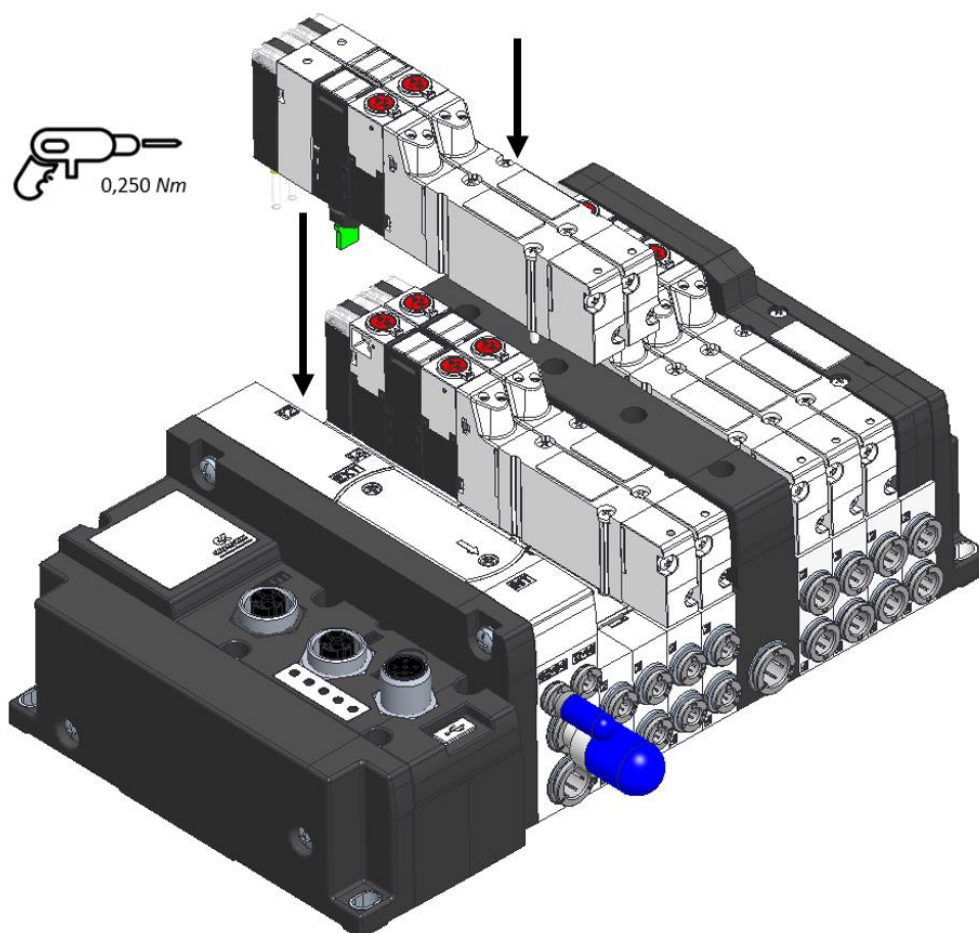
* Example for Series D1 Valve Island.

NOTE. The mapping procedure must be carried out in all those cases in which the I/O modules are added, removed, or moved (par. 0).


5.5.3 Dismantling and fitting Serie D coil valves

Dismantle and fit the Serie D coil valves on the same size sub-bases as follows:

- 1- Unscrew the 2 screws above the Serie D coil valves.
- 2- Pull the valves carefully and without tilting from the sub-base to avoid damages.
- 3- Add the new valves carefully and without tilting to the sub-base to avoid damages.
- 4- Tighten the 2 screws (Torque max 0.25 Nm (D1/D5), 0.5 Nm (D2), 2.0 Nm (D4)).
- 5- Reset the sub-base information from UVIX interface or controller/PLC.



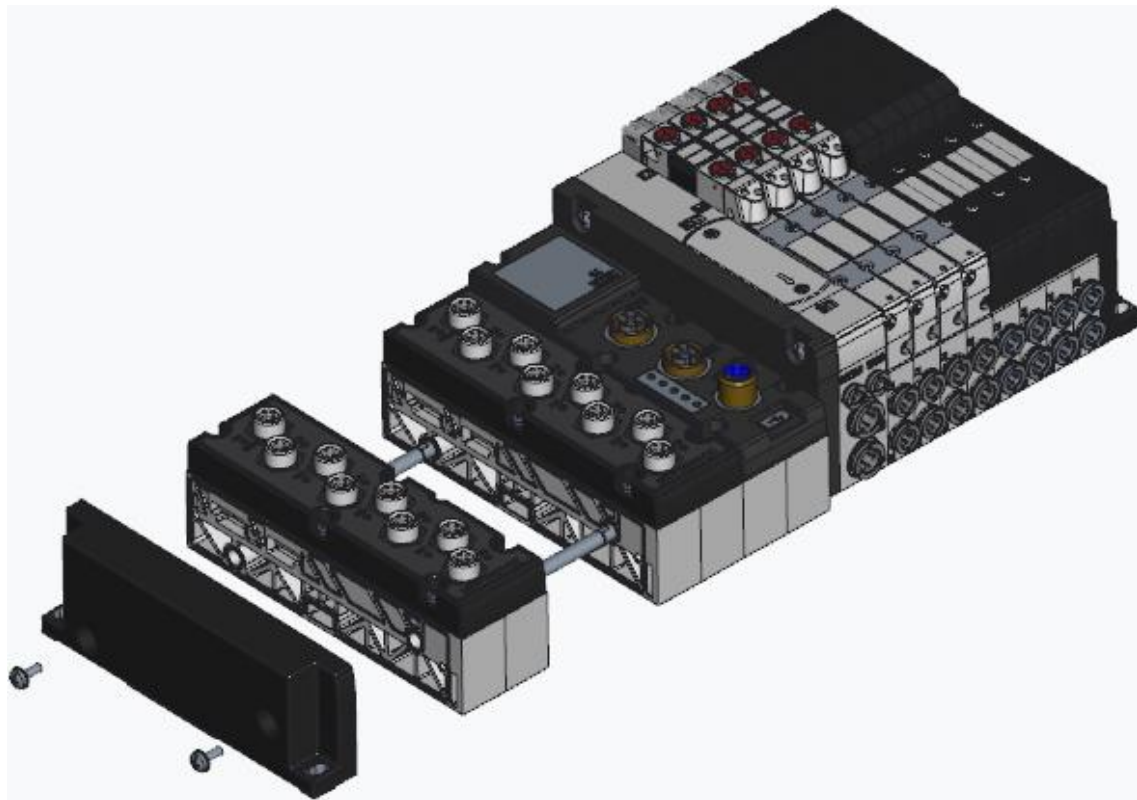
* Example for Series D1 Valve Island.

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5.5.4 I/O modules assembly

Dismantle and fit the I/O modules as follows:

1. Switch off the power supply of the CX4 module to avoid problems for the device or user.
2. Unscrew the 2 screws to the cover at the end of the island and open the I/O pack.
3. Remove the I/O modules from the tie-rods and replace with the new modules.
4. Push the I/O modules as far as possible to allow a correct electrical contact.
5. Mount the cover at the end of the island and tighten the 2 screws (Torque max 0.9 Nm)



* Example for Series D1 Valve Island.

NOTE. The mapping procedure must be carried out in all those cases in which the I/O modules are added, removed, or moved (par. 0).

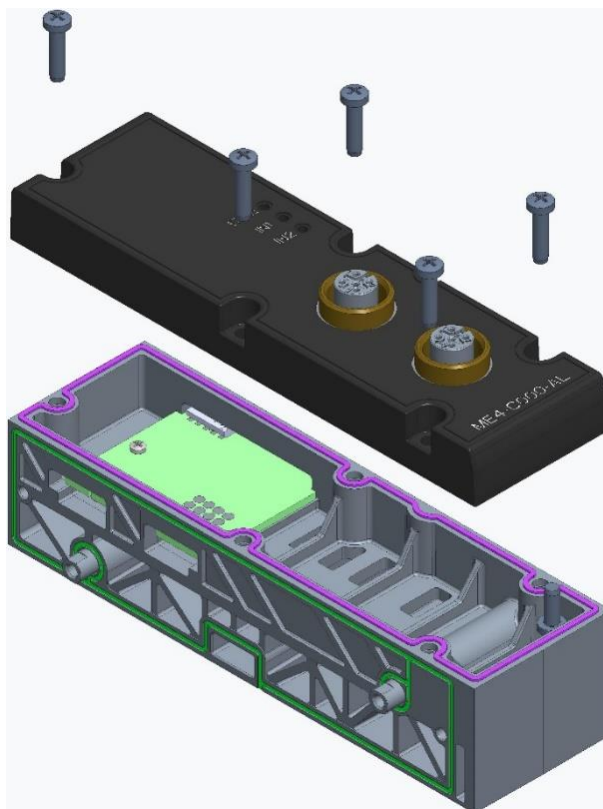
5.5.1 Dismantling and fitting I/O modules

Dismantle the cover of the I/O module as follows:


1. Switch off the power supply of the CX4 module to avoid problems for the device or user.
2. Loosen the 5 screws.
3. Pull the cover of the I/O module carefully and without tilting from the manifold base.

Fit the cover of the I/O module as follows:

1. Switch off the operating voltage supply of the CX4 module to avoid problems for the device or user.
2. Make sure that the gaskets are tight and not damaged.
3. Push the cover of the I/O module carefully and without tilting as far as possible into the manifold base.
4. Tighten the 5 screws (Torque max 0.6 Nm).



NOTE. After an island modification, the mapping procedure is required (par. 0).

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6 Commissioning

6.1 Electrical connections

The following steps are recommended for the correct electrical connection of the system:

- Connect the IN connector to the EtherNet/IP network coming from the controller (or PLC).
- Connect the OUT connector to the next device in the EtherNet/IP network. If this connector is not used, close with the appropriate cap to ensure IP65 protection.
- Connect the power supply connector.

NOTE. The dedicated caps for IP65 protection of our connectors (for digital and analogue input/output modules and subnet) can be found in the Camozzi catalogue:

- CS-DFTP, M8 connector cover cap.
- CS-LFTP, M12 connector cover cap.


6.2 Start-up operation

The CX4 module performs a system-wide configuration check at start-up. This is called *mapping*. Specifically, the system configuration is determined by the type and position of the coil valve sub-bases and connected I/O modules. The system mapping is saved in the CX4 module's internal memory. If the mapping has never been stored or the configuration of the system has been modified, a new mapping request must be made (par. 0). During the mapping operation, the general diagnostic LEDs of each connected accessory device light up in sequence, first on the coil valve side and then on the I/O module side.

- If the mapping finishes successfully, the CX4 moves on to the next stage. Furthermore, the diagnostic LEDs of each recognized module are switched off.
- If the mapping is not completed correctly, a diagnostic alarm will be triggered (par. 0) and the CX4 module will not proceed with any other operations.

The second step at system start-up is the configuration of parameters. The CX4 will wait for a maximum of 1 minute for any parameters from the controller/PLC, otherwise the parameters saved in internal memory or the default parameters will be loaded. While waiting for the configuration parameters, the LEDs of the I/O modules flash until this operation is complete (The type of flashing is defined for each individual accessory module in chapter **Error! Reference source not found.**).

At the end of this second start-up phase, the system, managed by the CX4 module, switches into normal operation mode and is ready to perform the required operations.

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6.3 Mapping procedure

The CX4 module, in CX4 Series serial module or Series D serial valve island configuration, is extremely flexible and its configuration can be modified by removing, replacing or changing the positions of the coil valve sub-bases and/or I/O modules. Each time a change is made, the mapping procedure must be carried again out to correctly configure the entire system. The CX4 module must be aware of the composition of the entire island: number, type and location of coil valve sub-bases and I/O modules.

The mapping operation can be performed with the use of software, by sending a request for new mapping, without having to physically work with the island. A new mapping can be requested in the following ways:

- Camozzi UVIX as Gateway-USB (par. 9.7.3).
- NFCamApp, smartphone app (par. Error! Reference source not found.).

NOTE. Once the mapping request has been made, the CX4 module must be restarted.

6.4 Addressing EtherNet/IP network

As an Ethernet fieldbus device, the CX4 EtherNet/IP module must have a unique assigned address (IP ADDRESS) in order to be identified correctly on the EtherNet/IP network.


The default settings for our system are as follows:

- Station name: "" (not used)
- IP address: 192.168.10.2
- Network mask: 255.255.255.0
- Gateway: 0.0.0.0

There are several ways to edit the default information:

- Camozzi UVIX as Gateway-USB (par. Error! Reference source not found.)
- NFCamApp, smartphone app (par. Error! Reference source not found.).
- Controller / PLC programming software.

NOTE. If EtherNet/IP communication between the CX4 and the controller/PLC is not established, the problem is signalled by the bus diagnostic LEDs.

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6.5 Configuration via EDS file


To configure the valve island on the EtherNet/IP network, the EDS file must be imported to the programming software used for the controller. The configuration file describes the characteristics of the EtherNet/IP valve island and allows the Inputs/Outputs to be configured correctly. There are three EDS files, one that allows you to configure the analogue outputs, one without analogue outputs and one with analogue outputs and six modules of voltage/current analogue inputs. The EDS files are available on the Camozzi website at: <http://catalogue.camozzi.com/Downloads>

6.6 Address assignment

The volume of addresses of the Series D valve island in the EtherNet/IP network is limited as shown in the following tables.


6.6.1 EDS version without analogue outputs

Modules	Number of channels	Bytes per single module	Number of modules that can be connected	Assigned address volume	Maximum number of I/Os
Valve sub-bases	2	2 bit per valve	64	16 bytes	128 coils
8-channel digital input modules	8	1 byte	8	8 bytes	64 digital inputs
16-channel digital input modules	16	2 bytes	6	12 bytes	96 digital inputs
8-channel digital output modules	8	1 byte	8	8 bytes	64 digital outputs
16-channel digital output modules	16	2 bytes	6	12 bytes	96 digital outputs
Analogue input modules for RTD	2	4 bytes	2	8 bytes	4 analogue inputs for RTD
Analogue input modules for Thermocouples	2	4 bytes	2	8 bytes	4 analogue inputs for Thermocouples
Analogue input modules for BRIDGE	2	8 bytes	2	16 bytes	4 analogue inputs for BRIDGE
Analogue input modules for Voltage/Current	2	4 bytes	2	8 bytes	4 analogue inputs for Voltage/Current
Analogue output modules for Voltage / Current*	2	4 bytes	6	24 bytes	12 analogue outputs for Voltage/Current

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6.6.2 EDS version with analogue outputs

Modules	Number of channels	Bytes per single module	Number of modules that can be connected	Assigned address volume	Maximum number of I/Os
Valve sub-bases	2	2 bit per valve	64	16 bytes	128 coils
8-channel digital input modules	8	1 byte	8	8 bytes	64 digital inputs
16-channel digital input modules	16	2 bytes	4	8 bytes	64 digital inputs
8-channel digital output modules	8	1 byte	8	8 bytes	64 digital outputs
16-channel digital output modules	16	2 bytes	4	8 bytes	64 digital outputs
Analogue input modules for RTD	2	4 bytes	2	8 bytes	4 analogue inputs for RTD
Analogue input modules for Thermocouples	2	4 bytes	2	8 bytes	4 analogue inputs for Thermocouples
Analogue input modules for BRIDGE	2	8 bytes	2	16 bytes	4 analogue inputs for BRIDGE
Analogue input modules for Voltage/Current	2	4 bytes	2	8 bytes	4 analogue inputs for Voltage/Current
Analogue output modules for Voltage / Current*	2	4 bytes	6	24 bytes	12 analogue outputs for Voltage/Current

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6.6.3 EDS version with analogue outputs and only voltage/current analogue inputs

Modules	Number of channels	Bytes per single module	Number of modules that can be connected	Assigned address volume	Maximum number of I/Os
Valve sub-bases	2	2 bit per valve	64	16 bytes	128 coils
8-channel digital input modules	8	1 byte	8	8 bytes	64 digital inputs
16-channel digital input modules	16	2 bytes	4	8 bytes	64 digital inputs
8-channel digital output modules	8	1 byte	8	8 bytes	64 digital outputs
16-channel digital output modules	16	2 bytes	4	8 bytes	64 digital outputs
Analogue input modules for Voltage/Current	2	4 bytes	6	24 bytes	12 analogue inputs for Voltage/Current
Analogue output modules for Voltage / Current*	2	4 bytes	6	24 bytes	12 analogue outputs for Voltage/Current

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6.7 Cyclical data

The data exchanged in cyclic mode between the CX4 module and the controller/PLC represent the input and output streams of real-time Ethernet/IP communication.


The first byte of the input stream is the diagnostic byte of general functioning of the island, see the chapter on malfunction identification (par. 0); this is followed by Digital Input and Analog Input module data. For the output stream, on the other hand, we find in sequence the Valve data and the Digital Output module data.

The mapping of I/O data is static: the bytes used for the inputs and outputs depends on the EDS file version. This mapping is shown in the following tables: it shows, among other things, the offset associated with each slave group. This parameter identifies the initial position of the specific group of devices within the relative data stream.

The assemblies for cyclic data exchange are defined in the EDS file: Assembly 100 (O2T, output stream) and Assembly 101 (T2O, input stream).

6.7.1 Cyclical data without analogue outputs

Device	Offset	Dimension	Total modules	Total channels	Direction
Valves	0	16 bytes	64	128	Output
8 Channels Digital Output	16	8 bytes	8	64	Output
16 Channels Digital Output	24	12 bytes	6	96	Output
Diagnostic	0	1 byte	1		Input
8 Channels Digital Input	1	8 bytes	8	64	Input
16 Channels Digital Input	9	12 bytes	6	96	Input
Analog Input RTD	21	8 bytes	2	4	Input
Analog Input Thermocouples	29	8 bytes	2	4	Input
Analog Input Voltage/Current	37	8 bytes	2	4	Input
Analog Input BRIDGE	45	16 bytes	2	4	Input


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6.7.2 Cyclical data with analogue outputs

Device	Offset	Dimension	Total modules	Total channels	Direction
Valves	0	16 bytes	64	128	Output
8 Channels Digital Output	16	8 bytes	8	64	Output
16 Channels Digital Output	24	8 byte	4	64	Output
Analog Output Voltage/Current	36	24 bytes	6	12	Output
Diagnostic	0	1 byte	1		Input
8 Channels Digital Input	1	8 bytes	8	64	Input
16 Channels Digital Input	9	8 byte	4	64	Input
Analog Input RTD	21	8 bytes	2	4	Input
Analog Input Thermocouples	29	8 bytes	2	4	Input
Analog Input Voltage/Current	37	8 bytes	2	4	Input
Analog Input BRIDGE	45	16 bytes	2	4	Input

6.7.3 Cyclical data with analogue outputs and only voltage/current analogue inputs

Device	Offset	Dimension	Total modules	Total channels	Direction
Valves	0	16 bytes	64	128	Output
8 Channels Digital Output	16	8 bytes	8	64	Output
16 Channels Digital Output	24	8 byte	4	64	Output
Analog Output Voltage/Current	36	24 bytes	6	12	Output
Diagnostic	0	1 byte	1		Input
8 Channels Digital Input	1	8 bytes	8	64	Input
16 Channels Digital Input	9	8 byte	4	64	Input
Analog Input Voltage/Current	37	24 bytes	6	12	Input

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6.8 Acyclic data

You can use acyclic packages to retrieve certain information on the functioning of the island and set certain specific application parameters at start-up, or to send appropriate commands.

6.8.1 Read parameters


The following information can be retrieved using *Unconnected Explicit Messaging* (UCMM), i.e. acyclic read commands for CIP objects, specifying the *Service*, *Class*, *Instance* and *Attribute*.

Description	Service	Class	Instance	Attribute	Dimension	Value
Valve health status	0x0E	0x64	1	1	1 byte per coil	0÷100 %
Valve cycle counter	0x0E	0x64	1	2	4 bytes per coil	0÷2 ³² [No. of cycles]
Valve error counter	0x0E	0x64	1	3	4 bytes per coil	0÷2 ³² [No. of errors]
Generic variables CX4 module	0x0E	0x64	1	4	5 bytes	Byte 0-1: Power supply [dV] Byte 2-3: Logic supply [dV] Byte 4: Temperature [°C]
Firmware version CX4 module	0x0E	0x64	1	7	2 bytes	Byte 0 = Major version Byte 1 = Minor version

6.8.2 Commands

The following objects allow you to send commands to the application, via *Unconnected Explicit Messaging* (UCMM) packets.

Description	Service	Class	Instance	Attribute	Dimension	Value
Mapping request	0x10	0x64	1	6	0 byte	
Reset sub-base information	0x10	0x64	1	5	1 byte	1-64 (ID number of the sub-base to be reset)

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6.8.3 Module parameterisation


The module parameters can be configured on the controller/PLC side using acyclic write commands.

The parameters are described in the EDS file, in Assembly 102, and can be identified by a unique ID.

NOTE. For the application parameters to be effectively implemented, you must ensure the following conditions are met:

- The System Start head parameter must be set to 1 (*External*).
- The module does not already have to be in operation, as the parameters are only applied in the boot phase.


NOTE. The subbases parameters for Series D valves and I / O modules, which can be connected to the CX4 main module, can also be configured via the UVIX user interface (ch. **Error! Reference source not found.**).

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6.8.3.1 CX4 EtherNet/IP module

The *System Start* allows the CX4 head to work in two alternative modes: if left at the default value (0), all the application parameters described in the following paragraphs, although still transmitted, are ignored by the CX4 module software, which instead will apply the values already stored in its own non-volatile memory; this is because a CX4 module can normally be configured not only with a PLC, but also using UVIX, and because of this we wanted to add the option not to overwrite any pre-existing configuration. If, on the other hand, this parameter is set to 1, any parameterization carried out on the master tool will be applied by the head software at the end of the boot phase.

Description	Parameter	ID	Value	Note
Parameter use mode	System Start	11	1 = External 0 = Stored	1 = parameters set by PLC 0 = internal memory parameters

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6.8.3.2 Series D valve sub-bases


The sub-bases that control the Series D coil valves can be configured both in the management of the failsafe operation and in the management of piloting errors in the coil valves themselves.

Failsafe allows the sub-base, in the absence of communication with the CX4 module, to set the status of the commands that drive the coil valves in order to avoid harmful and dangerous situations for devices or users. The parameters that can be configured are the ability to enable failsafe (*Fail Safe Enable*), which is disabled by default, and the state you want to set the valve coils to (*Fail Safe Status*). By default, the coil is off.

Coil management error locking can also be enabled (*Error Enable*). By default it is disabled. If enabled, errors do not simply disappear with the deactivation of the coil but the whole sub-base and subsequently the whole system must be restarted.

NOTE. Possible errors on the coils are described in paragraph 8.1. Coil interrupt and coil over-current alarms can be configured as blocking.

Description	Parameter	ID	Nome	Value	Dimension and note
Failsafe enable	Valves Failsafe Enable	20	FSE Coils 1-8	0 - 0xFF	Bit mask, 1 bit per coil LSB → Coil 1 Disabled (0) = failsafe not enabled Enabled (1) = failsafe enabled
		...			
		35	FSE Coils 121-128	0 - 0xFF	LSB → Coil 121
Failsafe status	Valves Failsafe Status	40	FSS Coils 1-8	0 - 0xFF	Bit mask, 1 bit per coil LSB → Coil 1 Reset (0) = status not active Set (1) = active status in case of failsafe enabled
		...			
		55	FSS Coils 121-128	0 - 0xFF	LSB → Coil 121
Management of coil error recovery (interrupted or over-current)	Valves Error Enable	60	EE Subbases 1-8	0 - 0xFF	Bit mask, 1 bit per sub-base LSB → Subbase 1 Unlatched (0) = recovery error Latched (1) = non recovery error
		...			
		67	EE Subbases 57-64	0 - 0xFF	LSB → Subbase 57

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6.8.3.3 Digital inputs

The configuration parameters for the digital input modules make it possible to act on both the input reading logic and on the temporal characteristics of the signals read.

For signal logic, it is possible to choose the polarity of each channel, i.e. the activation mode: each channel can be active high or active low (*Activation Mode*). In the first case, the channel will assume a high logic state in the presence of input voltage and a low logic state in the absence of voltage; in the second case, the reverse will apply.

Regarding the temporal characteristics of the input signals, configuration does not take place on a channel-by-channel basis: the values associated with the parameters in question have an effect on all input channels of the module. In particular, it is possible to specify two parameters: the minimum activation time and the minimum input re-reading period. The first parameter (*Minimum Activation Time*) indicates the amplitude of the minimum time interval in which the input signal to a certain channel must maintain the same state in order for that channel to be associated with the corresponding logical state: the purpose of this procedure is to filter out signals with an unstable level (anti-bounce). The second parameter (*Extension Time*) takes over after the anti-bounce filter has accepted the input value and is described as follows.


- At time t_0 there is a variation in the inputs not filtered by the anti-bounce system.
- At time $t_1 > t_0$ there is a further variation. At this point, two conditions can occur:
 - $t_1 - t_0 \geq \text{Extension Time}$: the channel will assume the state determined by the value of the input signal at time t_1 .
 - $t_1 - t_0 < \text{Extension Time}$: the channel is placed in a waiting state for re-reading: at time $t_2 = t_0 + \text{Extension Time}$ the input is forcibly read and if the detected value differs from that acquired at time t_0 , the channel assumes the new state, associated with the current signal value. If this not the case (i.e. at time t_2 the input value has returned to the same value as at time t_0), the channel will not detect any change in the signal.

6.8.3.3.1 Digital Inputs 8 channels

Description	Parameter	ID	Nome	Value	Dimension and note
Polarity of a channel Minimum dwell time of the input level (anti-bounce filter)	DI8 Activation Mode	80	DI8 AM Chs 1-8 (Module 1)	0 - 0xFF	Bit mask, 1 bit per channel LSB → Channel 1 High (1) = high active input Low (0) = low active input
		...			
		87	DI8 AM Chs 57-64 (Module 8)	0 - 0xFF	LSB → Channel 57

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Polarity of a channel Minimum dwell time of the input level (anti-bounce filter)	DI8 Min. Activation Time	90	DI8 AT Module 1	0 - 255	Module 1 0 = filter disabled 1÷255 [ms]
		...			
		97	DI8 AT Module 8	0 - 255	Module 8
Polarity of a channel	DI8 Extension Time	100	DI8 ET Module 1	0 - 1023	Module 1 0 = filter disabled 1÷1023 [ms]
		...			
		107	DI8 ET Module 8	0 - 1023	Module 8

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6.8.3.3.2 Digital Inputs 16 channels

Description	Parameter	ID	Nome	Value	Dimension and note
Polarity of a channel Minimum dwell time of the input level (anti-bounce filter)	DI16 Activation Mode	200	DI16 AM Chs 1-8 (Module 1)	0 - 0xFF	LSB → Channel 1 High (1) = high active input Low (0) = low active input
		...			
		211	DI16 AM Chs 89-96 (Module 8)	0 - 0xFF	LSB → Channel 89
Polarity of a channel Minimum dwell time of the input level (anti-bounce filter)	DI16 Min. Activation Time	220	DI16 AT Module 1	0 - 255	Module 1 0 = filter disabled 1÷255 [ms]
		...			
		225	DI16 AT Module 6	0 - 255	Module 6
Polarity of a channel	DI16 Extension Time	230	DI16 ET Module 1	0 - 1023	Module 1 0 = filter disabled 1÷1023 [ms]
		...			
		235	DI16 ET Module 6	0 - 1023	Module 6
Power source *	DI16 Power Source	240	DI16 Power S. Module 1	0 - 1	Module 1 Internal (0) = power connected to internal source External (1) = power connected to external source
		...			
		245	DI16 Power S. Module 6	0 - 1	Module 6

* Parameter configurable only for 16-channel digital inputs.

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6.8.3.4 Digital outputs

The configuration parameters of the digital output modules can be divided into three categories: activation mode, safety management with failsafe and PWM signal generation.

The parameters belonging to the first category consist of bit masks with different meanings, which are described below.


- *Module settings*: the value of this parameter is used to activate or deactivate individual functions related to the behaviour of the entire module (not the individual channels). Currently, only the least significant bit is set, which enables (1) or disables (0) the detection of no load by the power driver when a channel is activated. If detection is activated and at least one output is activated without the presence of a load, the module detects the fault, which is then signalled by a specific alarm.
- Channel enabling (*Enable output channels*): the single bits that make up the parameter value describe the enabling (1) or disabling (0) of individual output channels. If a non-enabled channel is activated during normal operation, the output driver does not supply voltage to the channel.
- Channel type setting (*Output channels mode*): each bit constituting the parameter value describes how the individual channels are activated. Each channel can be configured to supply type P (1) or type N (0) loads.

Below are the parameters involved in the second category: here too, the values represent bit masks with different meanings in each case.

- Enabling the failsafe (*Fail safe enable*): the bits that make up the parameter value describe whether the failsafe is enabled (1) or disabled (0) on the relevant channel. The purpose is to ensure that the outputs assume a certain state if a communication alarm occurs: in the presence of such a fault, the channels with failsafe enabled will assume the value prescribed by the failsafe status parameter, while those with failsafe disabled will maintain the state they had at the time the communication alarm occurred.
- Failsafe status (*Fail safe status*): the bit mask representing the value of this parameter describes the status of the channels for which failsafe is enabled, should a communication alarm occur. In particular: 1 indicates that the corresponding channel should be activated, 0 that the corresponding channel should be deactivated.

Finally, the following are the parameters describing the operation of the output module as a PWM signal generator.

- PWM channel type setting (*Pwm channels*): the value of this parameter represents a bit mask indicating the mode of operation of individual channels. In particular: 1 indicates that the relevant channel should generate a PWM signal when activated, 0 indicates that the channel must instead operate in ON/OFF mode and therefore should generate a continuous signal when activated.
- PWM activation time (*Pwm activation time*): indicates the activation time for channels configured as PWM, in milliseconds (from 0 to 255). In particular, when a PWM channel is activated, it immediately assumes a duty cycle equal to 100% and maintains it until the specified time has


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elapsed: from that moment on, the PWM signal will be modulated with a duty cycle equal to the value of the *Duty cycle per channel* parameter (see below). The parameter has an effect on all of the module's channels.


- Duty cycle per channel (Pwm channels duty cycle): the value of this parameter describes the duty cycle to be applied to the individual PWM channels when they are activated, after the activation time has elapsed. It is expressed as a percentage (from 0 to 100) and is associated with the individual channel.

6.8.3.4.1 Digital Outputs 8 channels

Description	Parameter	ID	Nome	Value	Dimension and note
Module settings	D08 Modules Settings	120	D08 MS Module 1	0 - 1	Module 1 Bit 0 = Open Load Detection (1 = Enabled, 0 = Disabled)
		...			
		127	D08 MS Module 8	0 - 1	Module 8
Enable channels	D08 Enable Output Channels	130	D08 EC Chs 1-8 (Module 1)	0 - 0xFF	Module 1, channels 1-8 1 bit per channel LSB → Channel. 1 Disabled (0) = channel disabled Enabled (1) = channel enabled
		...			
		137	D08 EC Chs 57-64 (Module 8)	0 - 0xFF	Module 8 LSB → Channel. 57
Channel Type Setting (N/P)	D08 Out Channels Mode	140	D08 CM Chs 1-8 (Module 1)	0 - 0xFF	Module 1, channels 1-8 1 bit per channel LSB → Channel. 1 Mode N (0) = type N channel Mode P (1) = type P channel
		...			
		147	D08 CM Chs 57-64 (Module 8)	0 - 0xFF	Module 8 LSB → Channel. 57
Fail safe enable	D08 Failsafe Enable	150	D08 FSE Chs 1-8 (Module 1)	0 - 0xFF	Module 1, channel 1-8 1 bit per channels LSB → Channel. 1 Disabled (0) = failsafe not enabled Enabled (1) = failsafe enabled on channel


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Description	Parameter	ID	Nome	Value	Dimension and note
		...			
		157	D08 FSE Chs 57-64 (Module 8)	0 - 0xFF	Module 8 LSB → Channel. 57
		...			
Fail safe status	D08 Failsafe Status	160	D08 FSS Chs 1-8 (Module 1)	0 - 0xFF	Module 1, channels 1-8 1 bit per channel LSB → Channel. 1 Reset (0) = status not active on channel Set (1) = active status on channel in case of failsafe enabled
		...			
		167	D08 FSS Chs 57-64 (Module 8)	0 - 0xFF	Module 8 LSB → Channel. 57
Channel Type Setting PWM	D08 Channel Type	170	D08 CHT Chs 1-8 (Module 1)	0 - 0xFF	Module 1, channels 1-8 1 bit per channel LSB → Channel. 1 ON/OFF (0) = channel on/off (no Pwm) PWM (1) = Pwm type channel
		...			
		177	D08 CHT Chs 57-64 (Module 8)	0 - 0xFF	Module 8 LSB → Channel. 57
PWM activation time	D08 PWM Activation Time	180	D08 ACT	0 - 255	For all channels and for all modules Value in ms
Duty cycle per channel (Configurable if in PWM mode)	D08 PWM Duty Cycle	190	D08 DTC	0 - 100	For all channels and for all modules Value in %


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6.8.3.4.2 Digital Outputs 16 channels

Description	Parameter	ID	Nome	Value	Dimension and note
Module settings	D016 Modules Settings	260	DO16 MS Module 1	0 - 1	Module 1 Bit 0 = Open Load Detection (1 = Enabled, 0 = Disabled)
		...			
		265	DO16 MS Module 6	0 - 1	Module 6
Enable channels	D016 Enable Output Channels	270	DO16 EC Chs 1-8 (Module 1)	0 - 0xFF	Module 1, channels 1-8 1 bit per channel LSB → Channel. 1 Disabled (0) = channel disabled Enabled (1) = channel enabled
		...			
		281	DO16 EC Chs 89-96 (Module 6)	0 - 0xFF	Module 6 LSB → Channel. 89
Channel Type Setting (N/P)	D016 Out Channels Mode	290	DO16 CM Chs 1-8 (Module 1)	0 - 0xFF	Module 1, channels 1-8 1 bit per channel LSB → Channel. 1 Mode N (0) = type N channel Mode P (1) = type P channel
		...			
		301	DO16 CM Chs 89-96 (Module 6)	0 - 0xFF	Module 6 LSB → Channel. 89
Failsafe enable	D016 Failsafe Enable	310	DO16 FSE Chs 1-8 (Module 1)	0 - 0xFF	Module 1, channel 1-8 1 bit per channels LSB → Channel. 1 Disabled (0) = failsafe not enabled Enabled (1) = failsafe enabled on channel
		...			
		321	DO16 FSE Chs 89-96 (Module 6)	0 - 0xFF	Module 8 LSB → Channel. 89

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Description	Parameter	ID	Nome	Value	Dimension and note
Fail safe status	D016 Failsafe Status	330	D016 FSS Chs 1-8 (Module 1)	0 - 0xFF	Module 1, channels 1-8 1 bit per channel LSB → Channel. 1 Reset (0) = status not active on channel Set (1) = active status on channel in case of failsafe enabled
		...			
		341	D016 FSS Chs 89-96 (Module 6)	0 - 0xFF	Module 6 LSB → Channel. 89
Channel Type Setting PWM	D016 Channel Type	350	D016 CHT Chs 1-8 (Module 1)	0 - 0xFF	Module 1, channels 1-8 1 bit per channel LSB → Channel. 1 ON/OFF (0) = channel on/off (no Pwm) PWM (1) = Pwm type channel
		...			
		361	D016 CHT Chs 89-96 (Module 6)	0 - 0xFF	Module 6 LSB → Channel. 89
PWM activation time	D016 PWM Activation Time	370	D016 ACT (all modules)	0 - 255	For all channels and for all modules Value in ms
Duty cycle per channel (Configurable if in PWM mode)	D016 PWM Duty Cycle	380	D016 DTC (all modules)	0 - 100	For all channels and for all modules Value in %

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6.8.3.5 Analogue inputs

The configurable parameters are the type of inputs, the transmission parameters and the filters to be applied to the inputs.

6.8.3.5.1 Input configuration

Each input must be appropriately configured, depending on the type of module used. For example, in the case of an RTD module, we could decide to have the following configuration:

- Channel 1: 4-wire PT100
- Channel 2: 2-wire PT1000

Or, for a Thermocouple module, the following configuration may be required:

- Channel 1: Type K thermocouple
- Channel 2: disabled

For a detailed description of the input configuration for the different analogue inputs, refer to the following paragraphs.

6.8.3.5.2 Transmission parameters configuration

The modules can transmit data to the head in two different ways: in frequency and threshold.

When the transmission is configured in frequency (*Sampling Threshold* and *Sampling Threshold Timeout* parameters disabled), it is possible to set a transmission frequency (*Sampling Rate*) with which the module regularly transmits the acquired data to the head.

NOTE. this parameter has nothing to do with the sampling frequency of the module inputs, which is fixed. To find out this frequency, refer to the Technical Data tables in this manual (par. 0).

When the transmission is configured as threshold (*Sampling Threshold* parameter other than zero), the module transmits the data to the head only if the current value is higher than the previous value of that set as threshold. If the input does not undergo changes beyond the threshold, the module still transmits the data when the timeout expires (*Sampling Threshold Timeout*). In the case of threshold operation, the *Sampling Frequency* parameter can be used to impose a limit on the frequency variation of the signal with respect to the threshold. In this way it is possible to reduce the shared bus occupation by the modules.



Example

Let's consider an RTD module with both channels enabled and with the following transmission configuration:

- *Sampling Frequency: 5 Hz*
- *Sampling Threshold: disabled*
- *Sampling Threshold Timeout: disabled*

the module sends the data acquired by the inputs and the related diagnostics to the PLC every 200 milliseconds.

If the configuration were instead:

- *Sampling Frequency: 1 Hz*

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- *Sampling Threshold: 0.2°C*
- *Sampling Threshold Timeout: 5 seconds*

The module transmits the data acquired by the inputs and the related diagnostics to the PLC in the following cases:


- *If the temperature measurement at the current time of either input exceeds the previous one by at least 0.2° C.*
- *If there is no temperature variation beyond the threshold for more than 5 seconds.*

In the first case, if the temperature variation frequency with respect to the threshold were higher than 1 Hz, the transmission would be limited to 1 Hz.




6.8.3.5.3 Filter configuration

Each input is equipped with a digital moving average filter. The maximum length of the filter impulse response is 128 samples. In the default configuration the filters are disabled.


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6.8.3.5.4 Analogue inputs – RTD

Description	Parameter	ID	Value	Note
RTD sensor type Module 1 Channel 1	AI RTD Sensor Type Ch. 1 (Module 1)	400	0÷8	0000 = not connected 0001 = PT100 (385) 0010 = PT200 (385) 0011 = PT500 (385) 0100 = PT1000 (385) 0101 = Ni100 (618) 0110 = Ni120 (672) 0111 = Ni1000 (618) 1000 = PT100 (3926)
RTD sensor type Module 1 Channel 2	AI RTD Sensor Type Ch. 2 (Module 1)	402		
RTD sensor type Module 2 Channel 1	AI RTD Sensor Type Ch. 3 (Module 2)	404		
RTD sensor type Module 2 Channel 2	AI RTD Sensor Type Ch. 4 (Module 2)	406		
RTD number of wires Module 1 Channel 1	AI RTD Wires Ch. 1 (Module 1)	401	0÷2	0= 2 wires 1= 3 wires 2= 4 wires
RTD number of wires Module 1 Channel 2	AI RTD Wires Ch. 2 (Module 1)	403		
RTD number of wires Module 2 Channel 1	AI RTD Wires Ch. 3 (Module 2)	405		
RTD number of wires Module 2 Channel 2	AI RTD Wires Ch. 4 (Module 2)	407		
Board transmission threshold in relative units 1 U = 0.1 °C Module 1	AI RTD Sampling Thr. Module 1	408	0÷15	0000 = disable 0001 = 1 U (0.1 °C) 0010 = 2 U 0011 = 3 U 0100 = 4 U 0101 = 5 U 0110 = 10 U 0111 = 20 U 1000 = 30 U 1001 = 40 U 1010 = 80 U 1011 = 100 U 1100 = 160 U 1101 = 500 U 1110 = 1000 U 1111 = 2000 U
Board transmission threshold in relative units 1 U = 0.1 °C Module 2	AI RTD Sampling Thr. Module 2	410		

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Description	Parameter	ID	Value	Note
Threshold transmission timeout Module 1	AI RTD Sampling Thr. Timeout Module 1	409	1÷15	Value in seconds
Threshold transmission timeout Module 2	AI RTD Sampling Thr. Timeout Module 2	411		
Transmission frequency to the master (timed mode) or upper frequency limit (threshold mode) Module 1	AI RTD Sampling Freq. Module 1	412	0÷10	0000 = disable 0001 = 1 Hz 0010 = 2 Hz 0011 = 5 Hz 0100 = 10 Hz 0101 = 25 Hz 0110 = 50 Hz 0111 = 100 Hz 1000 = 250 Hz 1001 = 500 Hz 1010 = 1000 Hz
Transmission frequency to the master (timed mode) or upper frequency limit (threshold mode) Module 2	AI RTD Sampling Freq. Module 2	413		
Moving Average Filter Length Module 1 Channel 1	AI RTD FIR Ch. 1 (Module 1)	414	0÷128	0÷1 = disable 2÷128 [no. of filter caps]
Moving Average Filter Length Module 1 Channel 2	AI RTD FIR Ch. 2 (Module 1)	415		
Moving Average Filter Length Module 2 Channel 1	AI RTD FIR Ch. 3 (Module 2)	416		
Moving Average Filter Length Module 2 Channel 2	AI RTD FIR Ch. 4 (Module 2)	417		


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6.8.3.5.5 Analogue inputs – Thermocouples

Description	Parameter	ID	Value	Note
TC sensor type Module 1 Channel 1	AI TH Sensor Type Ch. 1 (Module 1)	420	0÷8	0000 = not connected 0001 = B 0010 = E 0011 = J 0100 = K 0101 = N 0110 = R 0111 = S 1000 = T
TC sensor type Module 1 Channel 2	AI TH Sensor Type Ch. 2 (Module 1)	421		
TC sensor type Module 2 Channel 1	AI TH Sensor Type Ch. 3 (Module 2)	422		
TC sensor type Module 2 Channel 2	AI TH Sensor Type Ch. 4 (Module 2)	423		
Board transmission threshold in relative units 1 U = 0.1 °C Module 1	AI TH Sampling Thr. Module 1	424	0÷15	0000 = disable 0001 = 1 U (0.1 °C) 0010 = 2 U 0011 = 3 U 0100 = 4 U 0101 = 5 U 0110 = 10 U 0111 = 20 U 1000 = 30 U 1001 = 40 U 1010 = 80 U 1011 = 100 U 1100 = 160 U 1101 = 500 U 1110 = 1000 U 1111 = 2000 U
Board transmission threshold in relative units 1 U = 0.1 °C Module 2	AI TH Sampling Thr. Module 2	426		
Threshold transmission timeout Module 1	AI TH Sampling Thr. Timeout Module 1	425	1÷15	Value in seconds
Threshold transmission timeout Module 2	AI TH Sampling Thr. Timeout Module 2	427		


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Description	Parameter	ID	Value	Note
Transmission frequency to the master (timed mode) or upper frequency limit (threshold mode) Module 1	AI TH Sampling Freq. Module 1	428	0÷10	0000 = disable 0001 = 1 Hz 0010 = 2 Hz 0011 = 5 Hz 0100 = 10 Hz 0101 = 25 Hz 0110 = 50 Hz 0111 = 100 Hz 1000 = 250 Hz 1001 = 500 Hz 1010 = 1000 Hz
Transmission frequency to the master (timed mode) or upper frequency limit (threshold mode) Module 2	AI TH Sampling Freq. Module 2	429		
Moving Average Filter Length Module 1 Channel 1	AI TH FIR Ch. 1 (Module 1)	430	0÷128	0÷1 = disable 2÷128 [no. of filter caps]
Moving Average Filter Length Module 1 Channel 2	AI TH FIR Ch. 2 (Module 1)	431		
Moving Average Filter Length Module 2 Channel 1	AI TH FIR Ch. 3 (Module 2)	432		
Moving Average Filter Length Module 2 Channel 2	AI TH FIR Ch. 4 (Module 2)	433		


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6.8.3.5.6 Analogue inputs – Bridge

Description	Parameter	ID	Value	Note
BRIDGE sensor type Module 1 Channel 1	AI BRG Factor Ch. 1 (Module 1)	460	0÷255	0 = not connected 1-255 mV/Vdc
BRIDGE sensor type Module 1 Channel 2	AI BRG Factor Ch. 2 (Module 1)	461		
BRIDGE sensor type Module 2 Channel 1	AI BRG Factor Ch. 3 (Module 2)	462		
BRIDGE sensor type Module 2 Channel 2	AI BRG Factor Ch. 4 (Module 2)	463		
Board transmission threshold in relative units 1 U = 0.1 °C Module 1	AI BRG Sampling Thr. Module 1	464	0÷15	0000 = disable 0001 = 1 U (1 uV) 0010 = 2 U (2 uV) 0011 = 3 U 0100 = 4 U 0101 = 5 U 0110 = 10 U 0111 = 20 U 1000 = 30 U 1001 = 40 U 1010 = 80 U 1011 = 100 U 1100 = 160 U 1101 = 500 U 1110 = 1000 U 1111 = 2000 U
Board transmission threshold in relative units 1 U = 0.1 °C Module 2	AI BRG Sampling Thr. Module 2	466		
Threshold transmission timeout Module 1	AI BRG Sampling Thr. Timeout Module 1	465	1÷15	Value in seconds
Threshold transmission timeout Module 2	AI BRG Sampling Thr. Timeout Module 2	467		


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Description	Parameter	ID	Value	Note
Transmission frequency to the master (timed mode) or upper frequency limit (threshold mode) Module 1	AI BRG Sampling Freq. Module 1	468	0÷10	0000 = disable 0001 = 1 Hz 0010 = 2 Hz 0011 = 5 Hz 0100 = 10 Hz 0101 = 25 Hz 0110 = 50 Hz 0111 = 100 Hz 1000 = 250 Hz 1001 = 500 Hz 1010 = 1000 Hz
Transmission frequency to the master (timed mode) or upper frequency limit (threshold mode) Module 2	AI BRG Sampling Freq. Module 2	469		
Moving Average Filter Length Module 1 Channel 1	AI BRG FIR Ch. 1 (Module 1)	470	0÷128	0÷1 = disable 2÷128 [no. of filter caps]
Moving Average Filter Length Module 1 Channel 2	AI BRG FIR Ch. 2 (Module 1)	471		
Moving Average Filter Length Module 2 Channel 1	AI BRG FIR Ch. 3 (Module 2)	472		
Moving Average Filter Length Module 2 Channel 2	AI BRG FIR Ch. 4 (Module 2)	473		


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6.8.3.5.7 Analogue inputs - Voltage/Current

Description	Parameter	ID	Value	Note
V/C sensor type Module 1 Channel 1	AI V/C Sensor Type Ch. 1 (Module 1)	440	0÷5	000 = not connected 001 = 0÷10 V 010 = -10 ÷ +10 V 011 = 4÷20 mA 100 = 0÷20 mA 101 = -20 ÷ +20 mA
V/C sensor type Module 1 Channel 2	AI V/C Sensor Type Ch. 2 (Module 1)	441		
V/C sensor type Module 2 Channel 1	AI V/C Sensor Type Ch. 3 (Module 2)	442		
V/C sensor type Module 2 Channel 2	AI V/C Sensor Type Ch. 4 (Module 2)	443		
Board transmission threshold in relative units 1 U = 0.1 °C Module 1	AI V/C Sampling Thr. Module 1	444	0÷15	0000 = disable 0001 = 1U 0010 = 2U 0011 = 3U 0100 = 4U 0101 = 5U 0110 = 10U 0111 = 20U 1000 = 30U 1001 = 40U 1010 = 80U 1011 = 100U 1100 = 160U 1101 = 500 U 1110 = 1000 U 1111 = 2000 U
Board transmission threshold in relative units 1 U = 0.1 °C Module 2	AI V/C Sampling Thr. Module 2	446		
Threshold transmission timeout Module 1	AI V/C Sampling Thr. Timeout Module 1	445	1÷15	Value in seconds
Threshold transmission timeout Module 2	AI V/C Sampling Thr. Timeout Module 2	447		

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Description	Parameter	ID	Value	Note
Transmission frequency to the master (timed mode) or upper frequency limit (threshold mode) Module 1	AI V/C Sampling Freq. Module 1	448	0÷10	0000 = disable 0001 = 1 Hz 0010 = 2 Hz 0011 = 5 Hz 0100 = 10 Hz 0101 = 25 Hz 0110 = 50 Hz 0111 = 100 Hz 1000 = 250 Hz 1001 = 500 Hz 1010 = 1000 Hz
Transmission frequency to the master (timed mode) or upper frequency limit (threshold mode) Module 2	AI V/C Sampling Freq. Module 2	449		
Moving Average Filter Length Module 1 Channel 1	AI V/C FIR Ch. 1 (Module 1)	450	0÷128	0÷1 = disable 2÷128 [no. of filter caps]
Moving Average Filter Length Module 1 Channel 2	AI V/C FIR Ch. 2 (Module 1)	451		
Moving Average Filter Length Module 2 Channel 1	AI V/C FIR Ch. 3 (Module 2)	452		
Moving Average Filter Length Module 2 Channel 2	AI V/C FIR Ch. 4 (Module 2)	453		

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6.8.3.6 Analogue outputs

The configurable parameters are the type of outputs and the safety management with failsafe. In fact, each output must be suitably configured as a voltage or current channel. In case of loss of communication with the PLC, it is also possible to assign default values, both in voltage and in current, to the analogue outputs (failsafe). In particular, for each channel you can:

- assign the value it had before the communication failure (failsafe disabled).
- Assign a desired value, configurable in the master configuration tool (failsafe enabled).

Example

Considering an analogue outputs module with both channels enabled in voltage and failsafe enabled only on the second channel. In this case, the parameters configuration is as follows:


- Channel Configuration Channel 1: 1 (0 ÷ 10V)
- Channel Configuration Channel 2: 2 (0 ÷ 5V)
- Fail Safe Enable Channel 1: 0
- Fail Safe Enable Channel 2: 1
- Fail Safe Value Channel 1: 0
- Fail Safe Value Channel 2: 3500

In case of loss of communication with the PLC, the value of channel 1 is equal to the last data received from the PLC before the failure, while on channel 2 the value of 3500 mV is set as a consequence of enabling the failsafe and setting the failsafe value.

Description	Parameter	ID	Value	Note
Output type V/C Channel 1 Module	AO V/C Configuration Ch. 1 (Module 1)	500	1 byte	0 = disabled 1 = 0÷10 V 2 = 0÷5 V 3 = 4÷20 mA 4 = 0÷20 mA
Output type V/C Channel 2 Module 1	AO V/C Configuration Ch. 2 (Module 1)	501	1 byte	
Output type V/C Channel 3 Modulo 2	AO V/C Configuration Ch. 3 (Module 2)	502	1 byte	
Output type V/C Channel 4 Module 2	AO V/C Configuration Ch. 4 (Module 2)	503	1 byte	
Output type V/C Channel 5 Module 3	AO V/C Configuration Ch. 5 (Module 3)	504	1 byte	

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Description	Parameter	ID	Value	Note
Output type V/C Channel 6 Module 3	AO V/C Configuration Ch. 6 (Module 3)	505	1 byte	
Output type V/C Channel 7 Module 4	AO V/C Configuration Ch. 7 (Module 4)	506	1 byte	
Output type V/C Channel 8 Module 4	AO V/C Configuration Ch. 8 (Module 4)	507	1 byte	
Output type V/C Channel 9 Module 5	AO V/C Configuration Ch. 9 (Module 5)	508	1 byte	
Output type V/C Channel 1 Module 5	AO V/C Configuration Ch. 10 (Module 5)	509	1 byte	
Output type V/C Channel 11 Module 6	AO V/C Configuration Ch. 11 (Module 6)	510	1 byte	
Output type V/C Channel 12 Module 6	AO V/C Configuration Ch. 12 (Module 6)	511	1 byte	
Enable failsafe Channel 1-2 Module 1	AO V/C Failsafe Enable Ch. 1-2 (Module 1)	520	1 byte	0 = disabled 1 = channel enabled
Enable failsafe Channel 3-4 Module 2	AO V/C Failsafe Enable Ch. 3-4 (Module 2)	521	1 byte	
Enable failsafe Channel 5-6 Module 3	AO V/C Failsafe Enable Ch. 5-6 (Module 3)	522	1 byte	
Enable failsafe Channel 7-8 Module 4	AO V/C Failsafe Enable Ch. 7-8 (Module 4)	523	1 byte	
Enable failsafe Channel 9-10 Module 5	AO V/C Failsafe Enable Ch. 9-10 (Module 5)	524	1 byte	
Enable failsafe Channel 11-12 Module 6	AO V/C Failsafe Enable Ch. 11-12 (Module 6)	525	1 byte	




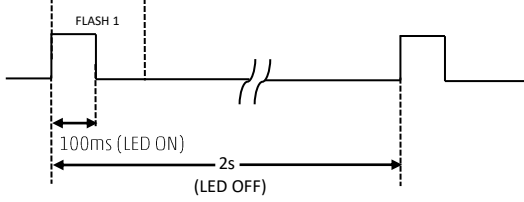
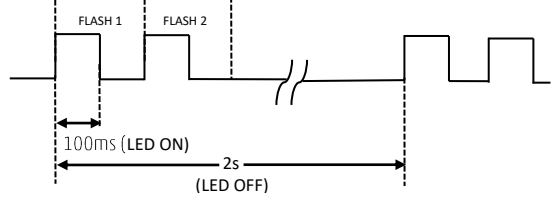
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Description	Parameter	ID	Value	Note
Failsafe value Channel 1	AO V/C Failsafe Value Channel 1 (Module 1)	530	2 bytes	In mV/uA: 0÷10000 if channel 0÷10 V 0÷5000 if channel 0÷5 V 4000÷20000 if channel 4÷20 mA 0÷20000 if channel 0÷20 mA
Failsafe value Channel 2 Module 1	AO V/C Failsafe Value Channel 2 (Module 1)	531	2 bytes	
Failsafe value Channel 3 Modulo 2	AO V/C Failsafe Value Channel 3 (Module 2)	532	2 bytes	
Failsafe value Channel 4 Module 2	AO V/C Failsafe Value Channel 4 (Module 2)	533	2 bytes	
Failsafe value Channel 5 Module 3	AO V/C Failsafe Value Channel 5 (Module 3)	534	2 bytes	
Failsafe value Channel 6 Module 3	AO V/C Failsafe Value Channel 6 (Module 3)	535	2 bytes	
Failsafe value Channel 7 Module 4	AO V/C Failsafe Value Channel 7 (Module 4)	536	2 bytes	
Failsafe value Channel 8 Module 4	AO V/C Failsafe Value Channel 8 (Module 4)	537	2 bytes	
Failsafe value Channel 9 Module 5	AO V/C Failsafe Value Channel 9 (Module 5)	538	2 bytes	
Failsafe value Channel 1 Module 5	AO V/C Failsafe Value Channel 10 (Module 5)	539	2 bytes	
Failsafe value Channel 11 Module 6	AO V/C Failsafe Value Channel 11 (Module 6)	540	2 bytes	
Failsafe value Channel 12 Module 6	AO V/C Failsafe Value Channel 12 (Module 6)	541	2 bytes	


7 Diagnostics

The diagnostics of the CX4 EtherNet/IP module, in Stand Alone configuration or as a Series D Serial valve island, is defined in three different ways.

- The status of the LEDs on the CX4 or on the individual modules connected to it (see details in the chapter 0). The following table provides the typical behaviour of the LEDs on our modules. The colour of the LEDs can be different for each module (the table refers to a red LED).

LED	Operation	Description
	RED OFF	Led is OFF
	RED ON	Led is ON
	FLASHING	<p>The led flashes with a specified sequence for each diagnostic state: @XX [ms/Hz] every YY [s]</p> <ul style="list-style-type: none"> ▪ XX is the ON time of a led flashing. <p>The flashing sequence is represented by an ON state and an OFF state of the same time.</p> <ul style="list-style-type: none"> ▪ YY is the time of the repeated flashing sequence. <p>-----</p> <p>Example: 1 flash @100 ms every 2 s</p>  <p>Example: 2 flashes @100 ms every 2 s</p>  <p>-----</p>









- Software messages are routed over the EtherNet/IP network.
- The UVIX user interface (Ch. 8)

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7.1 CX4 EtherNet/IP module


7.1.1 EtherNet/IP node

Diagnostics of the EtherNet/IP node are defined by the status of the link Ch0 LED, link Ch1 LED, MS LED (Module Status) and NS LED (Network Status).

LED	Operation	Description
MS (Module Status)	 GREEN ON	Device operational: If the device is operating correctly, the module status indicator shall be steady green.
	 Flashing GREEN	Standby: If the device has not been configured, the module status indicator shall be flashing green.
	 RED ON	Major fault: If the device has detected a non-recoverable major fault, the module status indicator shall be steady red.
	 Flashing RED	Minor fault: If the device has detected a recoverable minor fault, the module status indicator shall be flashing red. NOTE: An incorrect or inconsistent configuration would be considered a minor fault.
	 Flashing GREEN/RED	Self-test: While the device is performing its power up testing, the module status indicator shall be flashing green/red.
	 LED OFF	No power: If no power is supplied to the device, the module status indicator shall be steady off.
NS (Network Status)	 VERDE ON	Connected: If the device has at least one established connection (even to the Message Router), the network status indicator shall be steady green.
	 Lampeggiante VERDE	Connected: If the device has at least one established connection (even to the Message Router), the network status indicator shall be steady green.
	 ROSSO ON	No connections: If the device has no established connections, but has obtained an IP address, the network status indicator shall be flashing green.
	 Lampeggiante ROSSO	Duplicate IP: If the device has detected that its IP address is already in use, the network status indicator shall be steady red.

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LED	Operation	Description
	 Lampeggiante VERDE/ROSSO	Connection timeout: If one or more of the connections in which this device is the target has timed out, the network status indicator shall be flashing red. This shall be left only if all timed out connections are re-established or if the device is reset.
	 LED OFF	Not powered, no IP address: If the device does not have an IP address (or is powered off), the network status indicator shall be steady off.
Link (Ch0 e Ch1)	 VERDE ON	A connection to the Ethernet exists.
	 Lampeggiante VERDE	The device sends/receives EtherNet/IP frames.
	 LED OFF	The device has no connection to the Ethernet.





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7.1.2 CX4 system diagnostics

The diagnostics of the CX4 system is managed by the SYS diagnostic LED, by the messages transmitted to the controller in the EtherNet / IP protocol, by means of the appropriate value of the byte reserved for diagnostics in the input stream (byte 0), by the display on the UVIX interface.

Module status and alarms	Led SYS	Diagnostic Status (Byte 0 stream IN	UVIX
Normal operation	 1 flash GRREN @100 ms every 1 s	0x00	
I/O modules absent	 1 flash GRREN @100 ms every 1 s	0x01	I/O modules absent
Valves absent	 1 flash GRREN @100 ms every 1 s	0x02	Valves absent
Valves substitution	 1 flash GRREN @100 ms every 1 s	0x03	Valve Subbase Substitution
Fieldbus fatal error	(Alternated flashing)  1 flash GREEN @400 ms every 0.5 s  1 flash RED @400 ms every 0.5 s	0xF0	Fieldbus fatal error
Overheating CX4 module	 RED ON	0xFB	Overheating CX4 module
Undervoltage CX4 module	 RED ON	0xFC	Undervoltage CX4 module

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Module status and alarms	Led SYS	Diagnostic Status (Byte 0 stream IN)	UVIX
Alarm of mapping I/O modules error	 2 flashes RED @100 ms every 1 s	0xFD	Mapping I/O modules error
Alarm of mapping valves error	 2 flashes RED @100 ms every 1 s	0xFE	Mapping valves error
Alarm of mapping absent	 1 flash RED @100 ms every 1 s	0xFF	Mapping absent
Alarms of valve errors or I/O module errors	 3 flashes RED @100 ms every 1 s	NB. The diagnostic states and EtherNet/IP codes are specified for each single module in the following tables.	

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7.1.3 CX4 module diagnostic solutions

7.1.3.1 Replace solenoid valve

This warning indicates that the optimal performance of at least one solenoid valve has deteriorated and is no longer guaranteed.

Solution: replace the deteriorated solenoid valve.

N.B. To find out which solenoid valves on the island are in these conditions, you need to connect to the Camozzi user interface (UVIX) and check the health status of the individual solenoid valves (par. 9.2.2.1).

7.1.3.2 Fieldbus fatal error

This alarm can occur for two reasons.

- The fieldbus has been programmed incorrectly and the board has no MAC address.
- The fieldbus version loaded on the board is incorrect.

Solution: reprogram the board with the correct firmware (par. **Error! Reference source not found.****Error! Reference source not found.**). If the problem persists, contact Camozzi support.

7.1.3.3 Over-temperature alarm

The CX4 module has reached or exceeded the limit temperature over which the normal operation of the device is not guaranteed and, if the condition persists, this can lead to the failure of a component on the board.

Solution: restart the island; if the problem persists, contact Camozzi support.

7.1.3.4 Undervoltage alarm

The CX4 module is powered with a voltage lower than the minimum acceptable value; therefore, correct operation of the system is not guaranteed.

Solution: check that the wiring is correct and that the wires are properly inserted into the connector. Check that the logic supply (pins 1 and 3) and power supply (pins 2 and 5) are physically present on the connector. If the problem persists, contact Camozzi support.

7.1.3.5 Alarm - I/O module mapping error


During the mapping phase (par. 0), an error has occurred on the I/O modules. The mapping has failed at the first I/O module with the diagnostic LED off.

Solution: repeat the mapping procedure and replace where necessary the I/O module where the mapping ends (first I/O module with diagnostic LED off). If the problem persists, contact Camozzi support.

7.1.3.6 Alarm - Solenoid valve mapping error

During the mapping phase (par. 0), a solenoid valve error has occurred on the sub-base. The mapping has failed at the first sub-base with the diagnostic LED off.

Solution: repeat the mapping procedure and replace where necessary the sub-base where the mapping ends (first sub-base with diagnostic LED off). If the problem persists, contact Camozzi support.

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7.1.3.7 Alarm - No mapping

After requesting a new system mapping (par. 0), an error has occurred both on the I/O modules and on the solenoid valve sub-bases. The mapping ends at the first accessory module (I/O module or sub-base) with the diagnostic LED off.

Solution: repeat the mapping procedure and replace where necessary the sub-base where the mapping ends (first accessory module with diagnostic LED off). If the problem persists, contact Camozzi support.

7.1.3.8 Solenoid valve or I/O module alarms


These alarms are specific for each individual accessory module. The UVIX and PROFINET/IO messages are specified in the following tables, while the diagnostics via LEDs - found on each individual module - and the specific solutions are detailed in the accessories section (cap. **Error! Reference source not found.**).

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7.2 Series D valve sub-bases

The following table shows the diagnostic status of the Series D coil valves, with the respective EtherNet/IP messages and the display on the UVIX interface. The coil valves display a diagnostic signal through LED signalling directly on the sub-base where they are mounted. For details regarding LED diagnostics and possible solutions to any alarms, refer to the Accessories chapter (par. 0).


Module status and alarms	Diagnostic Status (Byte 0 stream IN	UVIX
Configuration parameters	0xE6	
Overheating subbase	0xE8	Overheating subbase
Overheating coil (Position 14/12)	0xE9	Overheating coil 14/12
Overcurrent coil (Position 14/12)	0xEA	Overcurrent coil 14/12
Interrupted coil (Position 14/12)	0xEB	Interrupted coil 14/12
Fault coil (Position 14/12)	0xEC	Fault coil 14/12
Communication alarm	0xEF	Communication alarm

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7.3 Digital Input Modules

The following table shows the diagnostic statuses of the digital inputs, with the respective EtherNet/IP messages and the display on the UVIX interface. The digital inputs also display a diagnostic signal via LED signalling directly on the module. Details on LED diagnostics and possible solutions to any alarms can be found in the chapter Accessories (par. 8.2.5).

Module status and alarms	Diagnostic Status (Byte 0 stream IN)	UVIX
Short circuit on the channel n	0xDD	Short circuit Group 0-3 Short circuit Group 4-7 Short circuit Group 8-11 Short circuit Group 12-15
Configuration parameters alarm	0xDE	Configuration alarm
Communication alarm	0xDF	Communication alarm

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7.4 Digital Output Modules

The following table shows the diagnostic statuses of the digital outputs, with the respective EtherNet/IP messages and the display on the UVIX interface. The digital outputs display a diagnostic signal via LED signalling directly on the module. Details on LED diagnostics and possible solutions to any alarms can be found in the chapter Accessories (par. 8.3.4).

NOTE. 16-channel digital output modules require an external power supply.

Module status and alarms	Diagnostic Status (Byte 0 stream IN)	UVIX
Short circuit on the channel n	0xCA	Short Circuit Channel n
Open circuit on the channel n	0xCB	Open Load Channel n
Undervoltage power line*	0xCC	Under Voltage Power Supply
No external power line*	0xCD	Zero Voltage Power Supply
Configuration parameters alarm	0xCE	Configuration alarm
Communication alarm	0xCF	Communication alarm

* Power supply alarms refer to the external power supply for 16-channel modules.

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7.5 Analogue Input Modules

7.5.1 Data format

Each channel restores the conversion of the corresponding input into a 16-bit or 32-bit word. The datum is represented in 2's complement and, depending on the module, corresponds to different values.

Module	Word transmitted	Data format	Size
RTD	16 bit	16 bit, 2's complement	°C/10
THERMOCOUPLES	16 bit	16 bit, 2's complement	°C/10
BRIDGE	32 bit	24 bit, 2's complement	uV
VOLTAGE/CURRENT	16 bit	16 bit, 2's complement	mV, uA

Each channel is also associated with a diagnostics byte which reports the errors indicated in the diagnostic. In case of correct operation, the diagnostics byte is equal to 0. Otherwise, it is possible to analyse the error by referring to the paragraph on the field bus.

If the diagnostics byte is different from 0, the bridge module will send data equal to 0x7FFFFF while all the others will transmit the value 0x7FFF.

The data format used by the CX4 for communication with the PLC is of the *little endian* type for the EtherNet/IP protocol.

Example

In the "little endian" format, the least significant byte (LSB) is sent first. For example, the value 100000 uV (0x186A0) received from a BRIDGE module will be sent as follows:


	LSB	MID	MSB
Address	0x00	0x01	0x02
Datum	0xA0	0x86	0x01

7.5.2 Diagnostic messages

The following table shows the diagnostic statuses of the analogue inputs, with the respective EtherNet/IP messages and the display on the UVIX interface. The analogue inputs display a diagnostic signal via LED signalling directly on the module. Details regarding LED diagnostics and possible solutions to any alarms can be found in the chapter Accessories (par. 8.4.3).

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Module status and alarms	Diagnostic Status (Byte 0 stream IN)	UVIX
Sensor fault on channel 1	0xB6	Sensor fault channel 1
Missing bridge on channel 1	0xB7	Missing bridge channel 1
ADC communication alarm	0xB8	ADC communication error
Alarm on the voltage reference 3.3V	0xB9	RESDCDC error
Sensor fault on channel 2	0xBA	Sensor fault channel 2
Missing bridge on channel 2	0xBB	Missing bridge channel 1
Configuration parameters alarm	0xBE	Configuration alarm
Communication alarm	0xBF	Communication alarm

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7.1 Analogue Output Modules

7.1.1 Data format

Each channel restores the conversion of the corresponding input into a 16-bit.

Module	Word transmitted	Data format	Size
VOLTAGE/CURRENT	16 bit	16 bit, 2's complement	mV, uA

The data format used by the CX4 for communication with the PLC is of the *little endian* type for the EtherNet/IP protocol.

Example

In the "little endian" format, the least significant byte (LSB) is sent first. For example, the value 5000 mV (0x1388) received from a V/C module will be sent as follows:

	LSB	MSB
Data	0x88	0x13

7.1.1 Diagnostic messages

The following table shows the diagnostic statuses of the analogue outputs, with the respective EtherNet/IP messages and the display on the UVIX interface. The analogue outputs display a diagnostic signal via LED signalling directly on the module. Details regarding LED diagnostics and possible solutions to any alarms can be found in the chapter Accessories (par. Error! Reference source not found.).

Module status and alarms	Diagnostic Status (Byte 0 stream IN)	UVIX
Internal error	0xA9	Internal Error
Open circuit on the channel n	0xAA	Channel n Open Load
Over Heating	0xAB	Board Over Heating
Power Supply Short Circuit	0xAC	Power Supply Short Circuit
Power Supply Under Voltage	0xAD	Power Supply Under Threshold
Configuration parameters alarm	0xAE	Configuration alarm
Communication alarm	0xAF	Communication alarm

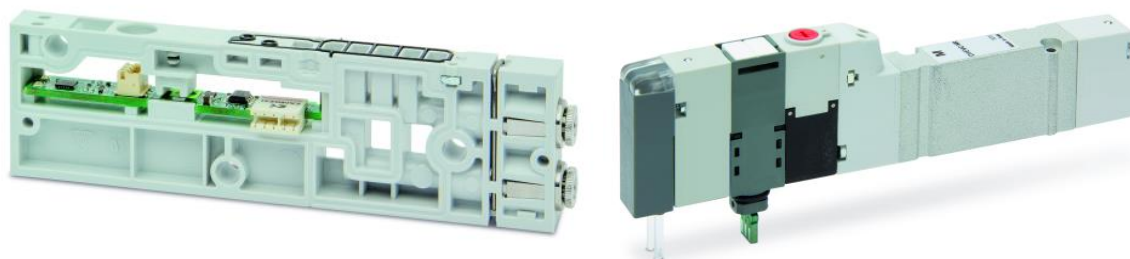
8 Accessories

8.1 Series D valve sub-bases

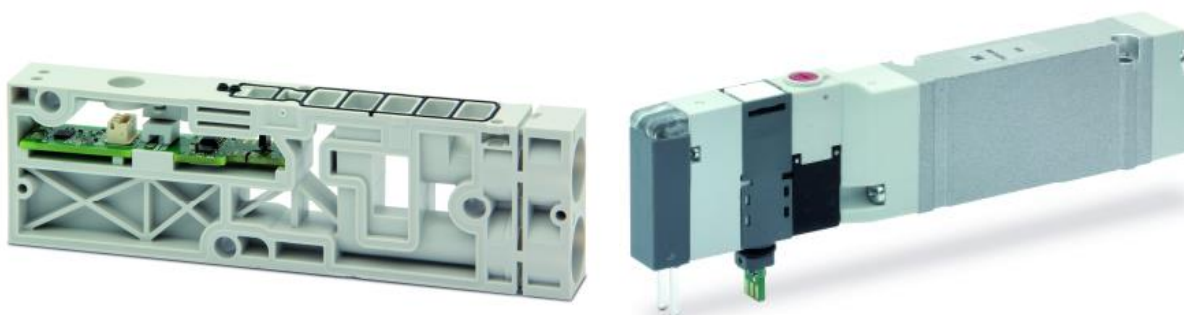
The CX4 can be used to create a Series D Serial valve island by connecting the sub-bases on the pneumatic side to allow the new Camozzi Series D coil valves to be connected.

Series D valves are available in three sizes depending on the pitch:

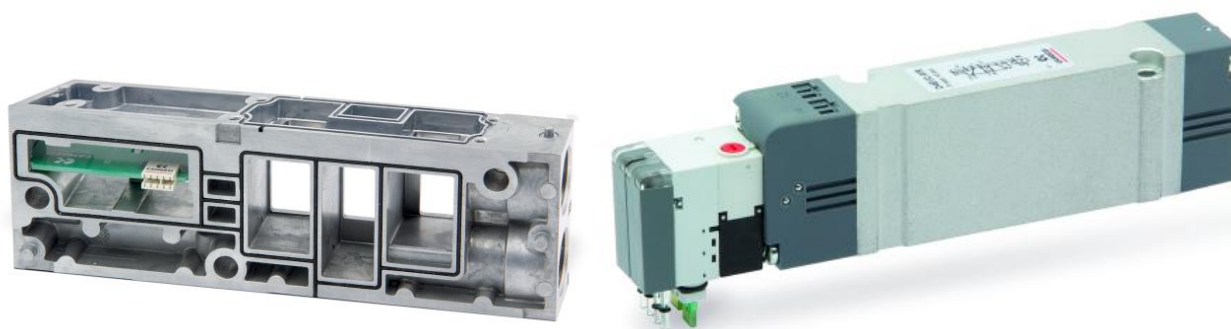
- Series D1 coil valves, 10.5 mm pitch




- Series D2 coil valves, 16 mm pitch



- Series D4 coil valves, 25 mm pitch



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8.1.1 Technical Data

Key feature	Value
Construction	Balanced spool
Valve functions	2x3/2 NC/NO/NC+NO; 5/2; 5/3 CC/CO/CP
Materials	body, spool= AL; bases, end cover = technopolymer; bases = AL only D4; seals = HNBR
Attachments	Variable Bushings Ø (D1-D2-D5) Thread G3/8 (D4)
Ambient temperature	0÷50 °C
Fluid	<ul style="list-style-type: none"> Compressed air filtered and not lubricated in class 7.4.4 according to ISO 8573-1: 2010. If lubrication is required, use only oils with max. viscosity. 32 Cst and the version with external servo drive. The servo drive air quality must be in class 7.4.4 according to ISO 8573-1:2010.
Voltage	24 Vdc
Voltage tolerance	± 10%
Absorption	1 W
Insulation class	class F


8.1.2 Coilvision








The sub-bases of Series D valves are equipped with **COILVISION** technology. This technology was developed to constantly monitor the functional parameters of the coil that drives the spool. Each actuation of the coil, in different cyclic configurations and environmental conditions, is analysed to acquire information which, when processed by software algorithms, allows the health of the component to be diagnosed and predicted.

The information on the health status of the solenoid valve is data supplied by the CX4 module to the PLC and via the UVIX browser interface in the form of a percentage and gauge indicator (par. 9.2.2.1). Via UVIX, you can also receive a replace solenoid valve warning when its performance has deteriorated (par. 9.2.2.2).


8.1.3 Sub-base diagnostics

The diagnostics of the sub-bases for the coil valves are defined by coded flashing of the yellow LED associated with the single coil (the sub-base D4 is associated to two yellow LEDs with the same behaviour for each single coil).

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Module status and alarms	LED status	Description of the status and solutions of the alarms
Normal operation without alarms	 YELLOW OFF	The valve is not controlled.
	 YELLOW ON	The valve has been operated correctly.
Fault coil (Position 14/12)	 1 flash YELLOW @100 ms every 1 s	The coil did not energise properly. Solution: the alarm is not blocking, so try operating the coil valve again. If the problem persists, replace the coil valve.
Interrupted coil (Position 14/12)	 2 flashes YELLOW @100 ms every 1 s	The coil is interrupted or missing. This alarm may be blocking (if configured as such) and therefore the island must be restarted. Solution: replace the coil valve.
Overcurrent coil (Position 14/12)	 3 flashes YELLOW @100 ms every 1 s	The current consumption of the coil is excessive and therefore the coil valve is automatically switched off. Solution: replace the coil valve.
Overheating coil (Position 14/12)	 3 flashes YELLOW @100 ms every 1 s	The coil temperature is too high. This alarm may be blocking (if configured as such) and therefore the island must be restarted. Solution: remove the ON control on the coil valve and allow the coil to cool down. If the problem persists, replace the coil valve.
Overheating subbase	 5 flashes YELLOW @100 ms every 1 s	The sub-base electronics temperature is too high. Solution: switch off the island and let the device cool down. If the problem persists, contact support and replace the sub-base.

NOTE. The interrupted coil and overcurrent alarms can block operation (configurable feature) and can only be reset by restarting the entire system.

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8.2 Digital Input Modules

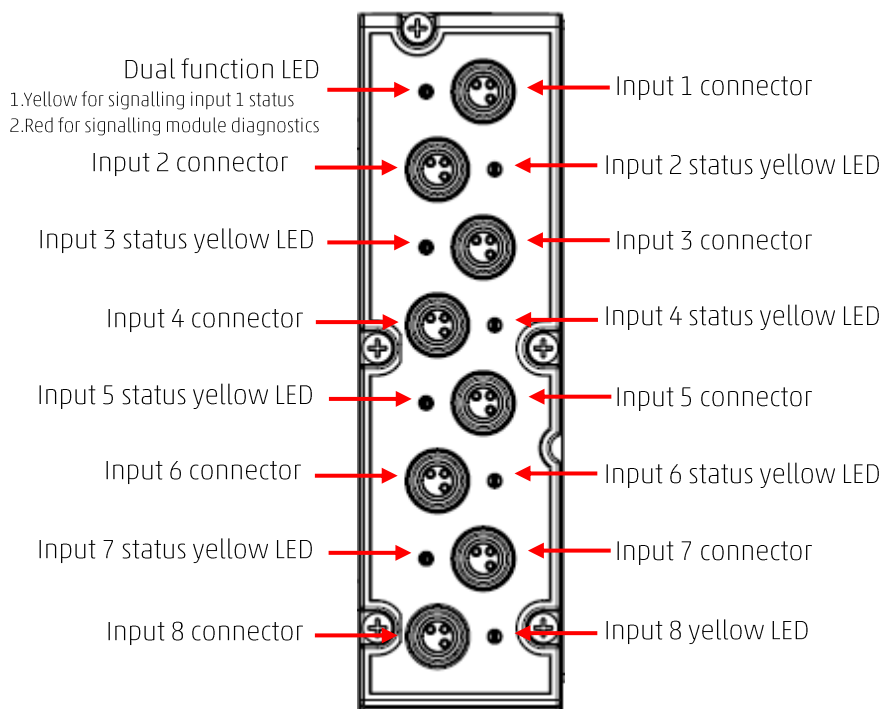
8.2.1 General operation

The digital input module allows 8 or 16 digital signals to be monitored. 2-wire or 3-wire digital sensors can be connected, with the option of powering the sensors directly through the module (24 V power supply).

After being connected to the CX4 module, the digital input module must be mapped from the island (par. Error! Reference source not found.). If the mapping procedure ends successfully, the digital input module waits to receive the configuration parameters from the CX4 module (maximum wait 1 minute). Upon receipt of these parameters, the module enters the normal operating state and the digital inputs can be read. Otherwise, if the mapping procedure is not completed successfully, the module remains in an error state, deactivating any operational function.

There is a dedicated diagnostic LED for each input, although the LED of the first channel is used for general diagnostics. (par. 8.2.5).

8.2.2 Connections and signals of the 8 digital input modules (M8 version)



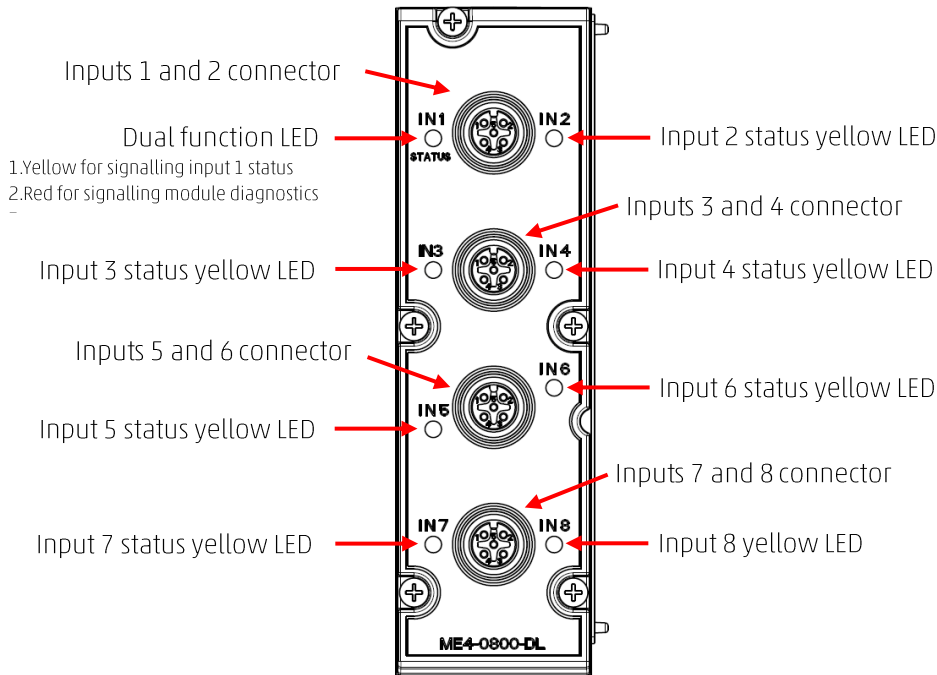
8.2.2.1 M8 connectors pinout

Pin	Signal	Description	Symbol
1	VCC	24 Vdc power supply supplied by the module to outside	
3	GND	Reference	
4	Input	Input (max 100 mA for each input)	


NOTE. For the digital input modules, the M8 3-pole male connector for wiring is available in the Camozzi catalogue (cod. CS-DM03HB)

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8.2.3 Connections and signals of the 8 digital input modules (M12 version)

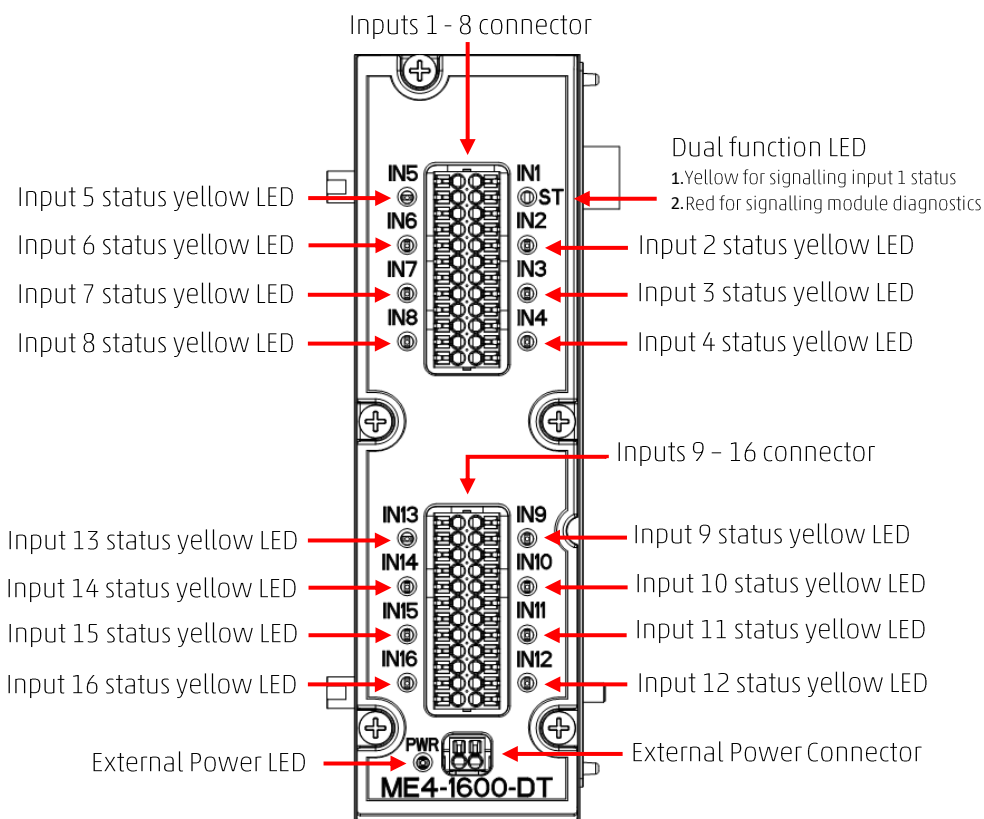


8.2.3.1 M12 connectors pinout

Pin	Signal	Description	Symbol
1	VCC	24 Vdc power supply supplied by the module to outside	
2	Input n+1	Input n+1 (max 100 mA for each input)	
3	GND	Reference	
4	Input n	Input n (max 100 mA for each input)	

NOTE. For the digital input modules, the M12 5-pole male connector for wiring (DUO version, with two possible cables to wire) is available in the Camozzi catalogue (code CS-LD05HF). Also, the M12 5-pole male connector for single wiring (CANopen Bus-Out) is available in the Camozzi catalogue (code CS-LM05HC).


8.2.4 Connections and signals of the 16 digital input modules



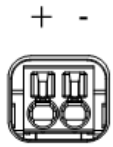
8.2.4.1 Input connectors pinout

The 16-channel connector is a RTB (DFMC and FMC series from Phoenix). The cables must have a cross-section of 0.5mm² and a 0.4x2 screwdriver can be used to remove the terminal block from the module as per the datasheet.

Pin	Signal	Description	Symbol
1	VCC	24 Vdc power supply supplied by the module to outside	<p> + 13 IN5 14 - 15 + 16 IN6 17 - 18 + 19 IN7 20 - 21 + 22 IN8 23 - 24 </p> <p> 1 + 2 IN1 3 - 4 + 5 IN2 6 - 7 + 8 IN3 9 - 10 + 11 IN4 12 - </p>
2	Input	Channel 1 input (max 50 mA for each input with internal power supply; 125 mA with external power supply)	
3	GND	Reference	

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8.2.4.2 External power supply connector pinout


Pin	Signal	Description	Symbol
1	+	Input 24Vdc	
2	-	GND reference	

8.2.5 Module diagnostics

8.2.5.1 General diagnostic LED



The signalling LED of the first channel has the dual function of indicating the module diagnostics, as well as the activation status of the channel itself. When the module experiences certain conditions, the LED behaves as described in the following table.

Module status and alarms	LED status	Description of the status and solutions of the alarms
Start-up End of the mapping or configuration phase	 RED OFF	The module enters this state upon power-up and at the end of the mapping phase or the reception of configuration parameters.
Mapped module	 RED ON	The LED is lit during the mapping phase and is turned off if this procedure is completed successfully.
Waiting for configuration parameters	 1 flash RED @100 ms every 2 s	The module is waiting for configuration parameters (maximum duration 1 minute).
Communication alarm	 2 flashes RED @100 ms every 2 s	The alarm indicates that there is no communication between the digital input module and the CX4 module. Solution: Try restarting the whole island and verifying that the physical connection to the digital input module is secure. If the problem persists, contact support and replace the digital input module.
Short circuit on digital input channels	 RED ON	At least one of the digital inputs is short-circuited. Solution: Remove the input sensor and check the connection. If the problem persists, replace the sensor.

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8.2.5.2 Inputs status LED





When the module is in normal operating mode (fully operational and with no particular critical issues), the LED of the first channel behaves like the signalling LEDs of the remaining channels (from 2 to 16), i.e. it is lit and yellow when the input is active and off when the input is inactive.

Input status	LED status	Description
Input n inactive	 YELLOW OFF	The LED indicates that the corresponding digital input is not active.
Input n activated	 YELLOW ON	The LED indicates that the corresponding digital input has activated successfully.

8.2.5.3 Diagnostic LED of the external power supply

In the 16-channel configuration, the digital input module is equipped with a connector for the external power supply with associated signalling LED.

NOTE. The external power supply can be enabled or disabled through the configuration parameters from the controller/PLC or from UVIX.

External power status	LED status	Description of the status and solutions of the alarms
Not configured	 LED OFF	Power for the digital inputs is supplied directly from the digital input module.
External power supply present	 GREEN ON	External power is present, and the digital inputs are externally powered. For this mode, the parameter for using the external power supply must be configured correctly.
No external power supply	 RED ON	The module is configured to receive an additional external power supply but this is not being detected by the module. Solution: Check that the power is reaching the module correctly and that the connection has been made correctly.
Configured (External power supply out of range)	 1 flash RED @100 ms very 1 s	The module is configured to receive an additional external power supply but this has a value of <21 Vdc or >27 Vdc. Solution: change the value of the power supply from the outside, bringing it within the proper operating range ($21 \text{ Vdc} \leq V_{cc} \leq 27 \text{ Vdc}$).

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8.3 Digital Output Modules

8.3.1 General operation

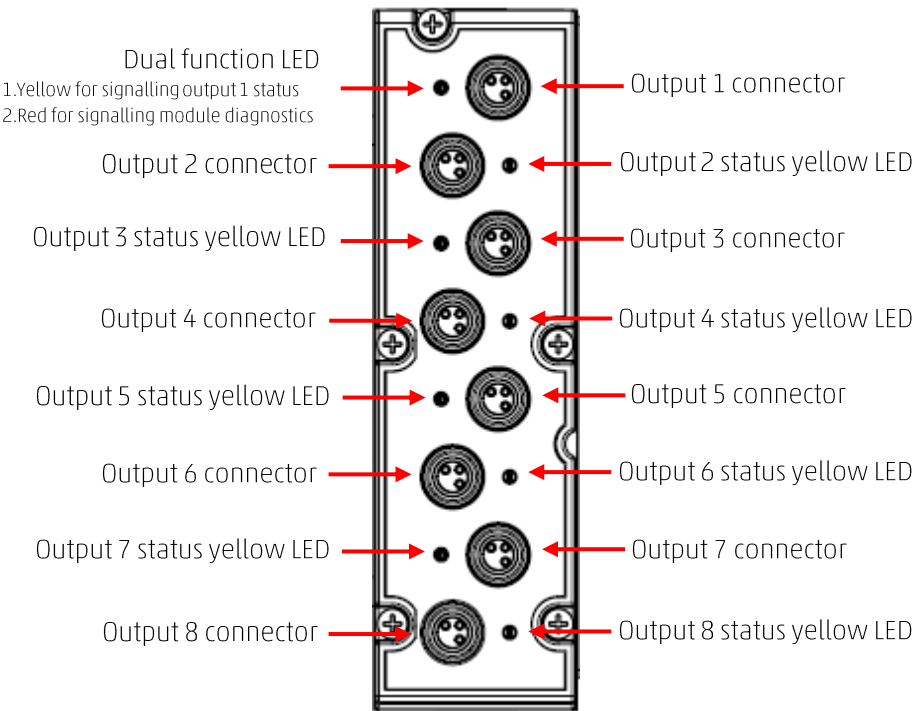
The digital output module allows 8 or 16 digital signals to be provided outside the system. 2-wire or 3-wire digital actuators, type P or N, can be connected.

NOTE. The 16-channel digital output module must be externally powered.

The digital output module, after being connected to the CX4 module, must be mapped by the island (par. Error! Reference source not found.). If the mapping procedure is completed successfully, the digital output module waits to receive the configuration parameters from the CX4 module (maximum wait 1 minute). Once these parameters have been received, the module enters the normal operational state and the digital outputs can be activated. Otherwise, if the mapping procedure is not end successfully, the module remains in an error state, deactivating any operational functionality.

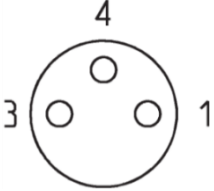
For each input there is a dedicated diagnostic LED, while for general diagnostics the LED of the first channel is used (par. 8.3.4).

8.3.2 Connections and signals of the 8 digital output modules



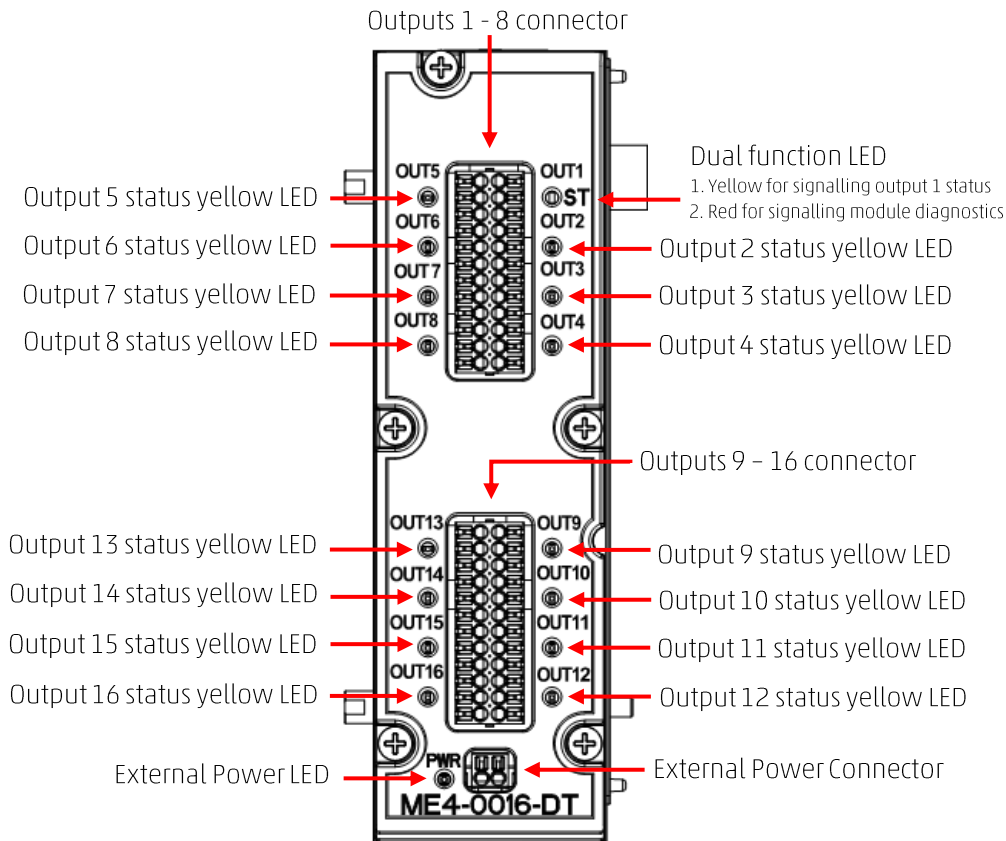
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8.3.2.1 M8 connectors pinout

Pin	Signal	Description	Symbol
1	VCC	24 Vdc power supply supplied by the module to outside	
3	GND	Reference	
4	Output	Output (max 125 mA for each output)	


NOTE. For the digital output modules, the M8 3-pole male connector for wiring is available in the Camozzi catalogue (cod. CS-DM03HB).

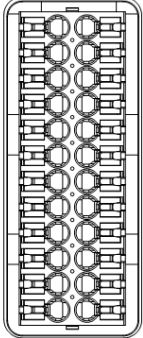
8.3.3 Connections and signals of the 16 digital output modules




8.3.3.1 Output connectors pinout

The 16-channel connector is a RTB (DFMC and FMC series from Phoenix). The cables must have a cross-section of 0.5 mm² and a 0.4x2 screwdriver can be used to remove the terminal block from the module as per the datasheet.

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Pin	Signal	Description	Symbol
1	VCC	24 Vdc power supply supplied by the module to outside	
2	Output	Output channel 1 (125 mA)	
3	GND	Reference	




8.3.3.2 External power supply connector pinout


Pin	Signal	Description	Symbol
1	+	Input 12÷32 Vdc	
2	-	GND reference	






8.3.4 Module diagnostics

8.3.4.1 General diagnostic LED

The signalling LED of the first channel has the dual function of indicating the module diagnostics, as well as the activation status of the channel itself. When the module experiences certain conditions, the LED behaves as described in the following table.

Module status and alarms	LED status	Description of the status and solutions of the alarms
Start-up End of the mapping or configuration phase	 RED OFF	The module enters this state when it is switched on, at the end of the mapping phase and when the configuration parameters are received.
Mapped module	 RED ON	The LED is lit during the mapping phase and is switched off if this procedure is completed successfully.
Waiting for configuration parameters	 1 flash RED @100 ms every 2 s	The module is waiting for configuration parameters (maximum duration 1 minute).



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Module status and alarms	LED status	Description of the status and solutions of the alarms
Short circuit on digital output channels	 RED ON	At least one of the digital outputs is short-circuited. Solution: check the connection and, if necessary, remove the output load and replace it.
Open circuit on digital output channels	 3 flashes RED @100 ms every 2 s	At least one output is not connected to the load and the open circuit is detected. Solution: check the load connection with the output connector.
Undervoltage voltage supply*	 4 flashes RED @100 ms every 2s	The supply voltage is less than 4.5 V. Solution: change the power supply value and return to the correct operating range (Vcc = 24 V).
No voltage supply*	 4 flashes RED @100 ms every 2 s	Circuit power is missing or shorted. Solution: check that the power reaches the module correctly and that the connection has been made correctly.
Communication alarm	 2 flashes RED @100 ms every 2 s	No response from the CX4 to output status and diagnostic signalling. Solution: contact support and replace the digital output module cover.

* Power supply alarms refer to external power supply for 16-channel modules.

8.3.4.2 Outputs status LED

When the module is in normal operating mode (fully operational and with no particular critical issues), this LED behaves like the signalling LEDs of the remaining channels (from 2 to 16), i.e. it is lit and yellow when the output is active and off when the output is inactive.



Output status	LED status	Description
Output n inactive	 YELLOW OFF	The LED indicates that the corresponding digital output is not active.
Output n activated	 YELLOW ON	The LED indicates that the corresponding digital output has activated successfully.


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8.3.4.3 Diagnostic LED of the external power supply

In the 16-channel configuration, the digital output module is equipped with a connector for the external power supply with associated signalling LED.

NOTE. It is mandatory for the external power supply to be connected.

External power status	LED status	Description of the status and solutions of the alarms
External power supply ok	 GREEN ON	The module is correctly receiving the additional external power supply.
No external power supply	 GREEN OFF	The module does not detect the additional power supply and therefore cannot work. Solution: verify that power is reaching the module properly. If the problem persists, contact support and replace the module.

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8.4 Analogue Input Modules

8.4.1 General operation

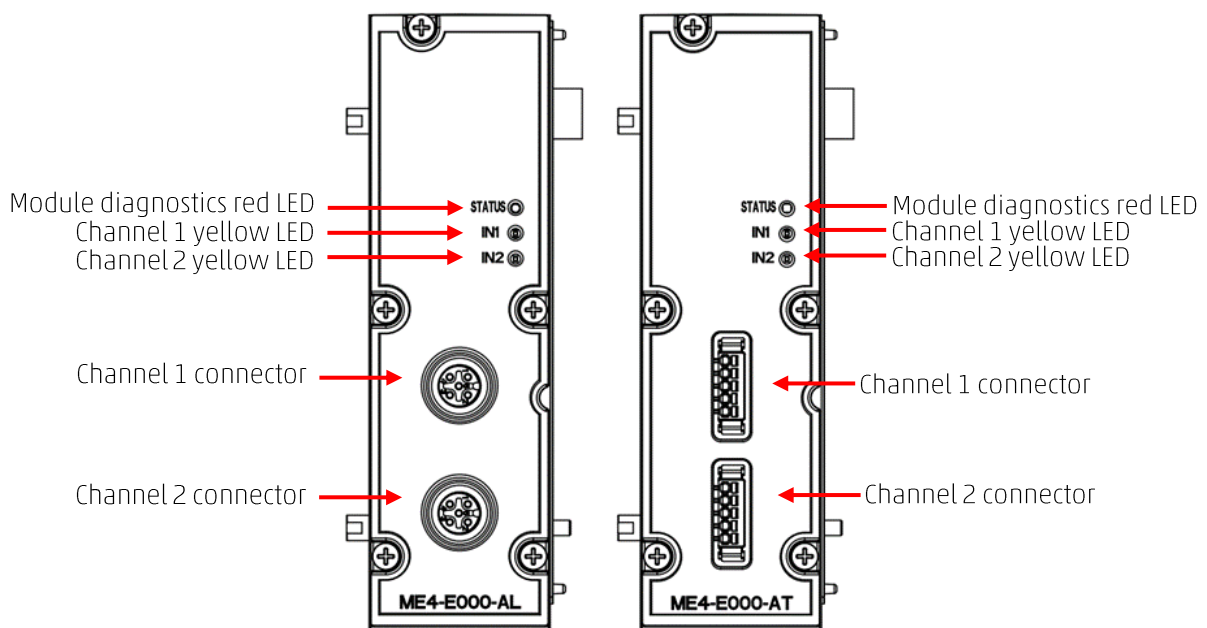
The analogue input module can monitor two analogue sensors simultaneously. The types of sensors that can be connected are:


- Resistance thermometers (RTD) for temperature measurement.
- Thermocouples for temperature measurement.
- Bridge for resistance measurement.
- Generic sensors with voltage or current outputs.

The analogue input module, after being connected to the CX4 module, must be mapped from the island (par. **Error! Reference source not found.**). If the mapping procedure is completed successfully, the module waits to receive the configuration parameters from the CX4 module. Upon receipt of these parameters, the module enters the normal operating state and the analogue inputs can be read out. Otherwise, if the mapping procedure is not completed successfully, the module remains in an error state, deactivating any operational function.



















8.4.2 Connections and signals of the modules


The analogue modules can have two types of connectors for connections with sensors. In the following figure, the left side shows an analogue module with 5-pole coded M12 A female connectors, while the right side shows an analogue module with 5-pole female TB connectors. The different types of analogue input modules have specific pinouts dedicated to their functionality. Visual indication of operation and diagnostics is via three LEDs.












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8.4.3 Module diagnostics

Module status and alarms	LED STATUS	LED IN1	LED IN2	Description of the status and solutions of the alarms
Waiting for configuration parameters	 1 flash RED @100 ms every 2 s	 YELLOW OFF	 YELLOW OFF	The module is waiting for configuration parameters (maximum duration 1 minute).
Sensor working on channel 1	 RED OFF	 YELLOW ON	 YELLOW OFF	The sensor connected to channel 1 is functioning correctly.
Sensor working on channel 2	 RED OFF	 YELLOW OFF	 YELLOW ON	The sensor connected to channel 2 is functioning correctly.
Sensor alarm on channel 1	 2 flashes RED @100 ms every 2 s	 2 flashes YELLOW @100 ms every 2 s	 YELLOW OFF	Sensor fault enabled and connected on channel 1. Solution: check the correct connection of the sensor and its power supply.
Bridge sensor missing on channel 1	 3 flashes RED @100 ms every 2 s	 3 flashes YELLOW @100ms every 2s	 YELLOW OFF	Bridge sensor missing or faulty when configuring the module on channel 1. (This error is only valid for bridge type modules and remains in place until the module is restarted) Solution: Check sensor connections and restart the module.
Sensor alarm on channel 2	 2 flashes RED @100 ms every 2 s	 YELLOW OFF	 2 flashes YELLOW @100 ms every 2 s	Sensor fault enabled and connected on channel 2 Solution: check that the sensor and its power supply are connected correctly.

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Module status and alarms	LED STATUS	LED IN1	LED IN2	Description of the status and solutions of the alarms
Bridge sensor missing on channel 2	 3 flashes RED @100 ms every 2 s	 YELLOW OFF	 3 flashes YELLOW @100 ms every 2 s	Bridge sensor missing or faulty when configuring the module on channel 2. (This error is only valid for bridge type modules and remains in place until the module is restarted) Solution: Check sensor connections and restart the module.
ADC communication error	 4 flashes RED @100 ms every 2 s	 YELLOW OFF	 YELLOW OFF	It occurs in the event of communication problems between the microcontroller and the ADC that measures the physical input quantity. Solution: Contact support and replace the module.
Reference voltage 3.3V error	 RED ON	 YELLOW OFF	 YELLOW OFF	Occurs when there is a problem with the logic voltage (3.3V). Solution: Contact support and replace the module.

NOTE. For a detailed description of the sensor faults, refer to the specific paragraphs of each module (RTD, thermocouples, bridge and V/C modules).

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8.4.4 RTD Module (Resistance Temperature Detector)

Resistance temperature detectors (RTDs) can be connected to these analogue modules for temperature measurement. It is possible to configure some parameters individually to take the measurements.

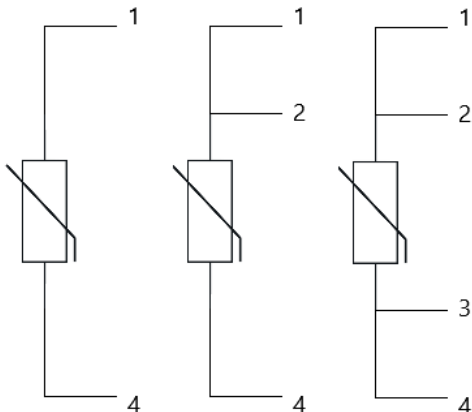

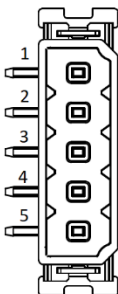
8.4.4.1 Technical Data

Key feature	Value		
Sensor types	Type	Temperature [°C]	
		Minimum	Maximum
	PT100 (385)	-200	850
	PT100 (3926)	-200	630
	PT200 (385)	-200	850
	PT500 (385)	-200	850
	PT1000 (385)	-200	850
	Ni100 (618)	-60	180
	Ni120 (672)	-80	260
	Ni1000 (618)	-60	250
Type of connections	2/3/4 wires		
Number of inputs	2		
Sensor connections	M12 A-coded 5 pole female connectors for each input TB 5 pole female connectors for each input		
Converter resolution	16 bit		
Reading resolution	0.1 °C		
Measurement error	< ±1 °C		
Sampling frequency	4 Hz for each input		
Digital filter	Moving average filter (configurable up to 128 samples) for each input		
Signalling and diagnostics	Board diagnostics red LED Yellow LED for each input		

8.4.4.2 Electrical connections

The RTD wiring diagram is different depending on the number of wires used:

- 2-wire RTDs must be connected between pin 1 and pin 4 of the connector.
- 3-wire RTDs must be connected between pin 2 and pin 4 of the connector, compensation wire to pin 1.
- 4-wire RTDs must be connected between pin 2 and pin 3 of the connector, compensation wires to pin 1 and 4.

Possible types of connections (2/3/4 wires)	M12A female connector 5 poles	TB female connector 5 poles
		

8.4.4.3 Faults

The module is able to detect the following faults:

- RTD sensor disconnected or broken.
- Sensor temperature range exceeded by more than $\pm 1^{\circ}\text{C}$.


NOTE. Detection of compensation wire disconnection (A4- input for 3-wire RTD, A1 + and/or A4 + inputs for 4-wire RTD) can take several seconds.

8.4.5 Thermocouple module

Thermocouples can be connected to these analogue modules for temperature measurement. It is possible to configure some parameters individually to take the measurements.

8.4.5.1 Technical Data


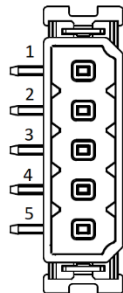
Key feature	Value		
Sensor types	Type	Temperature [$^{\circ}\text{C}$]	
		Minimum	Maximum
	B	250	1820
	E	-200	1000
	J	-210	1200
	K	-200	1372
	N	-200	1300
	R	-50	1768.1
	S	-50	1768.1
	T	-200	400
Number of inputs	2		
Sensor connections	M12 A-coded 5 pole female connectors for each input		

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Key feature	Value
	TB 5 pole female connectors for each input
Converter resolution	16 bit
Reading resolution	0.1 °C
Measurement error	< ±2°C for thermocouples E, J, K, N, T < ±4°C for thermocouples B, R, S
Sampling frequency	4 Hz for each input
Digital filter	Moving average filter (configurable up to 128 samples) for each input
Signalling and diagnostics	Board diagnostics red LED Yellow LED for each input

8.4.5.2 Electrical connections

The thermocouple must be connected to pins 2 (positive) and 4 (negative) of the M12 or TB connector. Between pins 1 and 3 there is an RTD (PT100) on the circuit, which is needed to perform CJC (Cold Junction Compensation) fully automatically.


Pin	Signal	Description	M12A female connector 5 poles	TB female connector 5 poles
1	CJC	PT100 for cold junction compensation (do not connect)		
2	TC+	Thermocouple positive input		
3	CJC	PT100 for cold junction compensation (do not connect)		
4	TC-	Thermocouple negative input		
5	GND	Earth		

8.4.5.3 Faults

The module is able to detect the following faults:

- Thermocouples sensor disconnected or broken.
- Sensor temperature range exceeded by more than ± 2° C.

NOTE. Detection of thermocouple sensor disconnection may take several seconds.

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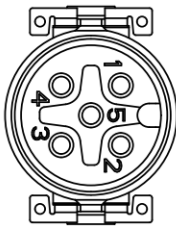
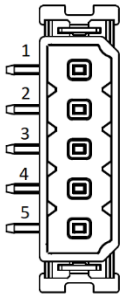
8.4.6 Bridge module

Bridge modules are based on resistive bridge operation with variable sensitivity (e.g. load cells).

8.4.6.1 Technical Data

Key feature	Value
Sensor types	4-wire resistor bridges (e.g. load cells) with variable bridge factor (sensitivity) are supported: from 2 mV/V to 255 mV/V at intervals of 1 mV/V
Number of inputs	2
Sensor connections	M12 A-coded 5 pole female connectors for each input TB 5 pole female connectors for each input
Converter resolution	24 bit
Reading resolution	1 μ V
Measurement error	Dependent on the bridge factor
Sampling frequency	1 kHz for each input
Bridge excitation voltage	5 V
Digital filter	Moving average filter (configurable up to 128 samples) for each input
Signalling and diagnostics	Board diagnostics red LED Yellow LED for each input

8.4.6.2 Electrical connections

Pin	Signal	Description	M12A female connector 5 poles	TB female connector 5 poles
1	ECC1+	Positive excitation voltage of the resistor bridge (+ 5V)		
2	ECC1-	Negative excitation voltage of the resistor bridge (0V)		
3	SBR1+	Positive differential signal of the resistor bridge		
4	SBR1-	Negative differential signal of the resistor bridge		
5	GND	Earth		

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8.4.6.3 Load cells

The load cells can be connected to the Bridge module to measure a force applied to an object by reading the voltage made by the resistor bridge. The voltage to weight conversion formula for load cells is as follows:

$$F = \frac{F_N \cdot U}{C \cdot U_{EXC}}$$

Where:

- F is the force detected by the load cell (Kg)
- F_N is the capacity of the load cell (Kg)
- C is the sensitivity of the load cell (mV/V)
- U_{EXC} is the excitation voltage of the resistor bridge, this value is fixed and equal to 5V
- U is the voltage read by the load cell

Example

A load cell has the following characteristics:

$$C = 2mV/V$$

$$F_N = 5Kg$$

Following the application of a force on the load cell, the module detects a voltage of 100 μ V. Obtain the corresponding weight value:


$$F = \frac{5 Kg \cdot 0.1mV}{2mV/V \cdot 5V} = 0.05 Kg$$

Therefore the weight value read corresponds to 50 grams.

8.4.6.4 Measurement error

The AD converter on the module includes a PGA (Programmable Gain Amplifier) whose gain is optimised according to the bridge factor set. This gain determines the full scale of the measurement and the related noise. The following table shows the full-scale errors for the most common bridge factors.

Bridge factor (mV/V)	Full scale (mV)	Error % (referring to full scale)
< 8	78.1	±0.0243
16	156.3	±0.0128
32	312.5	±0.0067
64	625.0	±0.0062
128	1250.0	±0.0056
256	2500.0	±0.0064

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8.4.6.5 Faults

The module is able to detect the following faults:

- Short circuit between ECC + and ECC- pin (excitation voltage).
- Resistor bridge disconnected.
- Exceeding the full scale value of the resistor bridge ($U_{EXC} \cdot C$) by 1%.


NOTE. the disconnection of the resistor bridge can only be detected at the moment the module is configured and not while in operating mode. The error remains set until a resistor bridge is inserted and a subsequent reconfiguration is performed.

8.4.7 Voltage/Current module

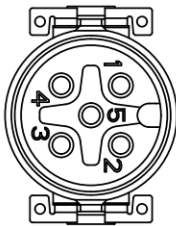
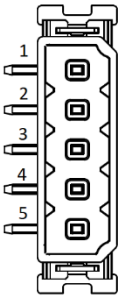
The voltage/current (V/C) modules are analogue input modules that allow both analogue current and voltage measurements.

8.4.7.1 Technical Data

Key feature	Value
Sensor types	<p>The following voltage and current inputs are supported:</p> <p>0÷10 V ±10 V 4÷20 mA 0÷20 mA ±20 mA</p>
Number of inputs	2
Sensor connections	<ul style="list-style-type: none"> ▪ M12 A-coded 5 pole female connectors for each input ▪ TB 5 pole female connectors for each input
Converter resolution	16 bit
Reading resolution	<p>1 mV 1 uA</p>
Measurement error	<ul style="list-style-type: none"> ▪ $<\pm 0.3\%$ (relative to the full scale ± 10 V) ▪ $<\pm 0.3\%$ (relative to the full scale 0÷20mA)
Sampling frequency	100 Hz for each input
Digital filter	Moving average filter (configurable up to 128 samples) for each input
Signalling and diagnostics	<ul style="list-style-type: none"> ▪ Board diagnostics red LED ▪ Yellow LED for each input

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8.4.7.2 Electrical connections


Pin	Signal	Description	M12A female connector 5 poles	TB female connector 5 poles
1	+24EX	24 Vdc auxiliary voltage. Maximum absorption value: 200 mA per channel or 400 mA if there is only one sensor powered by the board		
2	IN+	Positive voltage or current signal differential input		
3	GND	Earth		
4	IN-	Negative voltage or current signal differential input		
5	GND	Earth		

8.4.7.3 Faults

The module is able to detect the following faults:

- Minimum and maximum voltage/current exceeded by $\pm 60\text{mV}$ or $\pm 60\mu\text{A}$.
- Open circuit (if channel configured with voltage).

NOTE. Open circuit detection (voltage configured channel) can take several seconds.

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8.5 Analogue Output Modules

8.5.1 General operation

The analogue output module can control two independent outputs with the following configurations:

- 0÷10 V voltage
- 0÷5 V voltage
- 0÷20 mA current
- 4÷20 mA current

The analogue output module, after being connected to the CX4 module, must be mapped from the island (par. 6.3). If the mapping procedure ends correctly, the module waits for the reception of the configuration parameters from the CX4 module. Once these parameters have been received, the module enters normal operating status and the outputs, if enabled, can be set. Otherwise, if the mapping procedure does not finish correctly, the module remains in an error state by disabling any operational functionality.

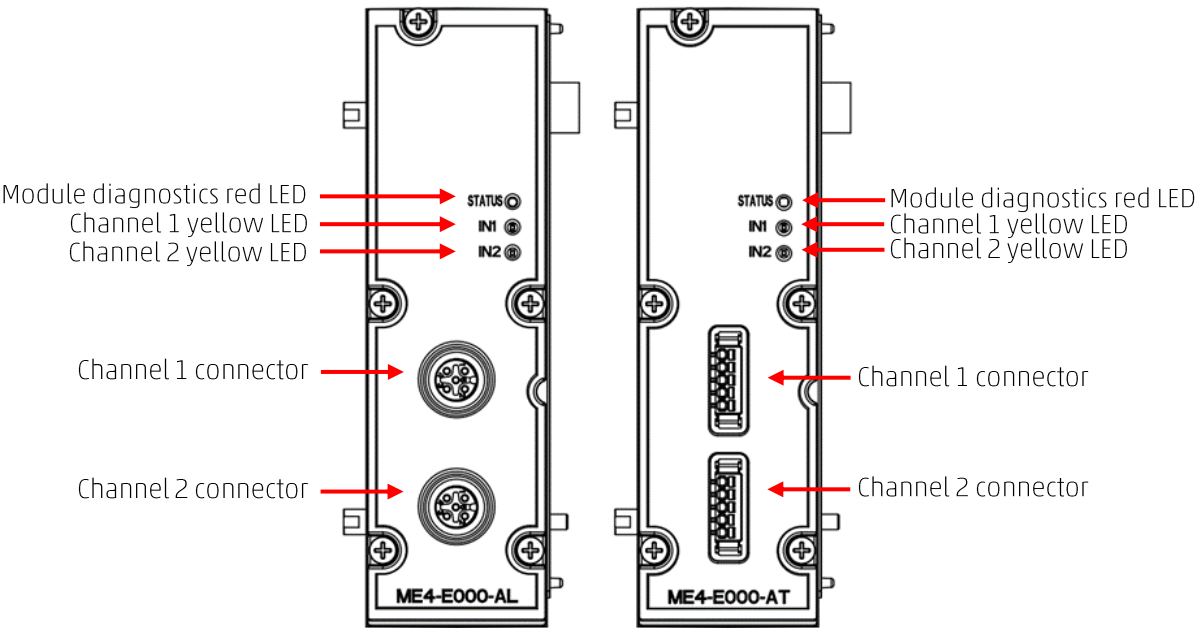
8.5.1.1 Technical Data

Key feature	Value
Sensor types	0÷10 V 0÷5 V 0÷20 mA 4÷20 mA
Number of outputs	2
Sensor connections	<ul style="list-style-type: none"> ▪ M12 A-coded 5 pole female connectors for each input ▪ TB 5 pole female connectors for each input
Converter resolution	16 bits
Reading resolution	1 mV 1 µA
Measurement error	
Signalling and diagnostics	<ul style="list-style-type: none"> ▪ Board diagnostics red LED ▪ Yellow LED for each input


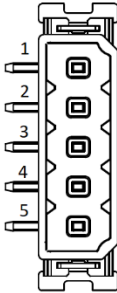
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8.5.2 Connections and signals of the modules

The analogue modules can have two types of connectors for connections with sensors. In the following figure, the left side shows an analogue module with 5-pole coded M12 A female connectors, while the right side shows an analogue module with 5-pole female TB connectors. The different types of analogue output modules have specific pinouts dedicated to their functionality. Visual indication of operation and diagnostics is via three LEDs.

























8.5.2.1 Electrical connections

Pin	Signal	Description	M12A female connector 5 poles	TB female connector 5 poles
1	+24EX	24V auxiliary voltage. Maximum absorption value: 200mA per channel or 400mA if there is only one sensor powered by the board		
2	OUT	Voltage or current signal output		
3	GND	Earth		
4	NC	Not connected		
5	NC	Not connected		

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8.5.3 Module diagnostics

Module status and alarms	LED STATUS	LED IN1	LED IN2	Description of the status and solutions of the alarms
Waiting for configuration parameters	 1 flash RED @100 ms every 2 s	 YELLOW OFF	 YELLOW OFF	The module is waiting for configuration parameters (maximum duration 1 minute).
Output working on channel 1	 RED OFF	 YELLOW ON	 YELLOW OFF	The output to channel 1 is functioning correctly.
Output working on channel 2	 RED OFF	 YELLOW OFF	 YELLOW ON	The output to channel 2 is functioning correctly.
Communication fault	 2 flashes RED @100 ms every 2 s	 2 flashes YELLOW @100 ms every 2 s	 2 flashes YELLOW @100 ms every 2 s	Communication fault between head and module. Solution: Contact support and replace the module.
No load on channel 1	 3 flashes RED @100 ms every 2 s	 3 flashes YELLOW @100 ms every 2 s	 YELLOW OFF	Load on the output 1 not present. (This error is valid only for the current configuration) Solution: Check connections with the load and restart the module.
No load on channel 2	 3 flashes RED @100 ms every 2 s	 YELLOW OFF	 3 flashes YELLOW @100 ms every 2 s	Load on the output 2 not present. (This error is valid only for the current configuration) Solution: Check connections with the load and restart the module.
Module error	 4 flashes RED @100 ms every 2 s	 4 flashes YELLOW @100 ms every 2 s	 4 flashes YELLOW @100 ms every 2 s	Occurs in case of the following problems: <ul style="list-style-type: none"> Overheating Undervoltage power supply Internal DAC error Solution: Contact support and replace the module.

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9 UVIX

Camozzi's proprietary environment, called UVIX, allows the user to monitor and configure all new generation Camozzi devices (*Camozzi Smart Devices*) that support connection to it.

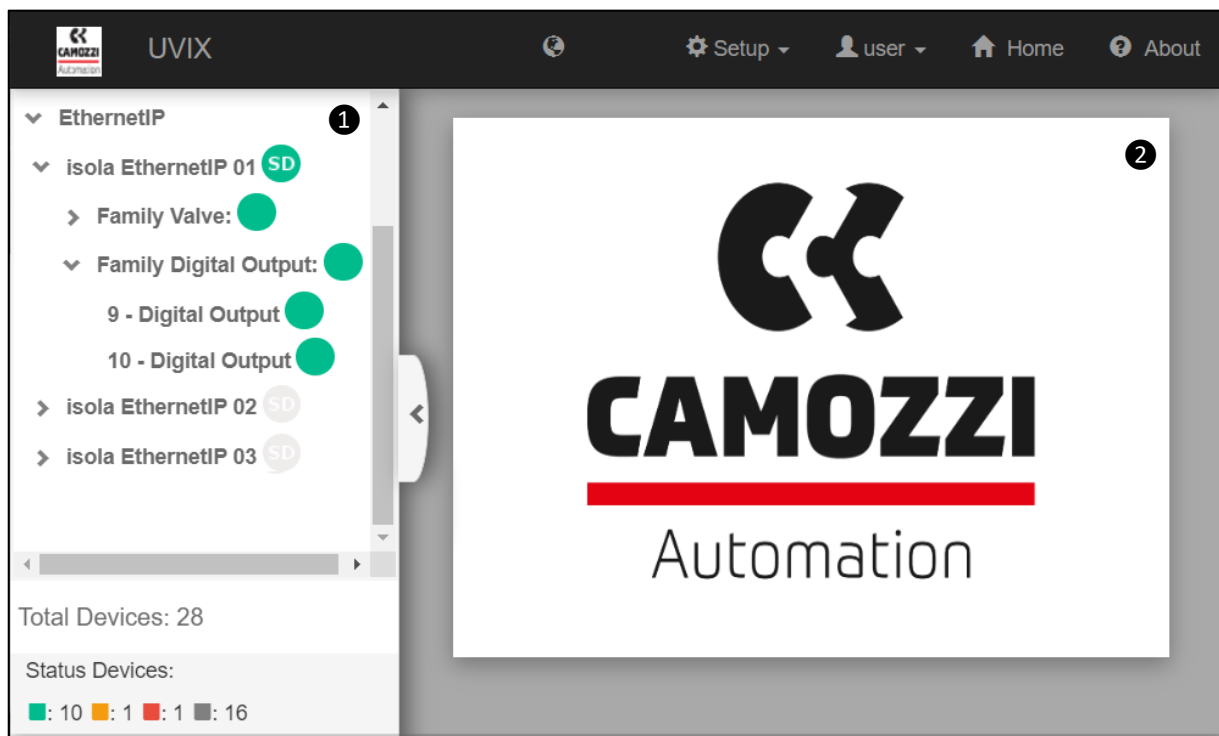
Devices can be connected to UVIX in two ways: wireless or USB. This system has been implemented with a web-based architecture so that information can be accessed straightforwardly using a browser.

Monitoring consists of displaying all the device variables, whether they relate to operation, diagnostics, or parameterization.


For details on the UVIX architecture, its installation, and general operations, see the [UVIX Manual](#).

9.1 General information

The devices connected to the UVIX are displayed in a tree diagram **1** consisting of Device Groups, Family and Devices. Select one of the components to view in the main window **2** all the information on the various devices and perform configuration operations or manual commands.



Select the CX4 module - in Stand-Alone or Valve Island configuration - or the individual accessory modules, Series D solenoid valve sub-bases or I/O modules, to view the general status information and details. The details are divided into variables, alarms, and commands (only for solenoid valves, digital outputs and analogue outputs).


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9.1.1 Status information

Select a Series CX4 module to view the main information.

- ❶ Series CX4 identification image.
- ❷ Device name, assigned when recognized and added in UVIX.
- ❸ Device identification number (17 characters).
- ❹ Device family name: *Series CX4*.
- ❺ Type of Series D Fieldbus according to the connected accessory modules:
 - *Stand-Alone*, with only I/O modules connected.
 - *D1* with at least one Series D1 solenoid valve connected.
 - *D2* with at least one Series D2 solenoid valve connected.
 - *D4* with at least one Series D4 solenoid valve connected.
 - *D5* with at least one Series D1 and one Series D2 solenoid connected.
- ❻ Firmware version.
- ❼ Date and time of the last transmission between CX4 module and UVIX.
- ❽ General status of the module: ● *Not available*, ● *OK*, ● *Alarm*.
- ❾ Operating status of the module:
 - *Init* → initialization of the CX4 module and accessory modules.
 - *Enumeration* → numbering of the accessory modules connected to the CX4 module (required if modules are replaced or moved with respect to the original configuration).
 - *Mapping* → mapping of the accessory modules connected to the CX module (required to check that there have been no changes since the last system configuration).
 - *Work* → normal operation.
 - *Manual* → manual operation.
 - *Configuration* → configuration of the parameters of the CX4 module and the accessory modules.
 - *Fatal error* → fatal error that renders the CX4 module inoperative
- ❿ WiFi connection status: ● *Online*, ● *Offline*.
- ⓫ Fieldbus used by the module: *EtherNet/IP*.
- ⓬ Fieldbus communication status: ● *Online*, ● *Offline*.

Status information:

❶ 

❷ Name: CX4 Profinet

❸ Device number: 01702227754100116

❹ Family name: Series CX4

❺ Subtype: Series D Fieldbus - D1

❻ Firmware: 2.26

❼ Last data transmission: 2022-07-28 15:16:35


❽ Device status: ●

❾ Operational status: Manual

❿ Connection: ●

⓫ FieldBus: ProfiNet

⓬ Link status: ●

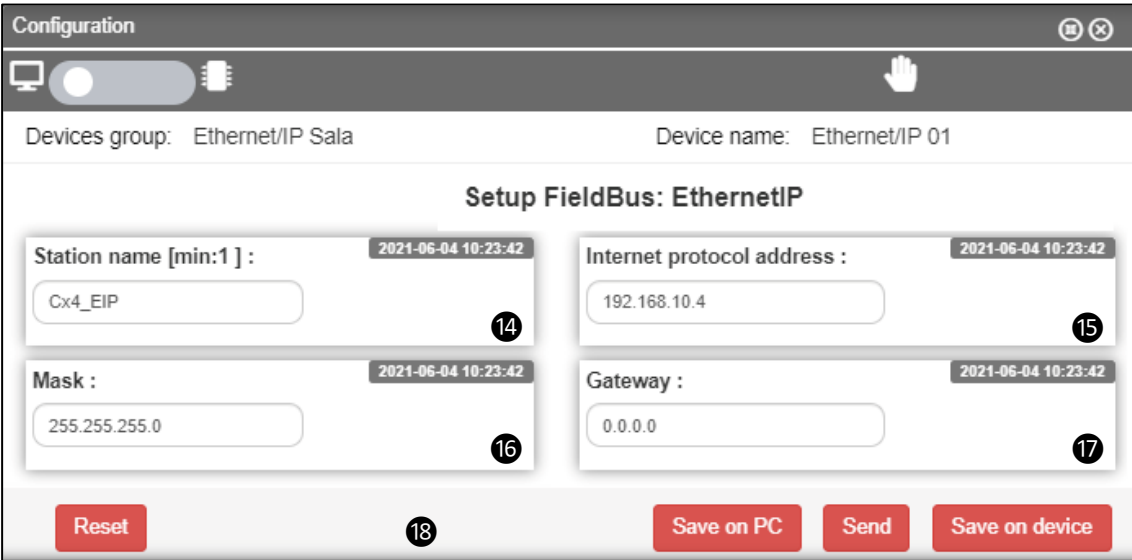
⓭ Configuration: 

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9.1.1.1 EtherNet/IP network configuration

From the status information page, you can access the window for configuring certain fieldbus parameters **13**. In the specific case of EtherNet/IP, you can configure the unique network name **14**, the IP address **15**, the mask **16** and the gateway **17** of the address (par. Error! Reference source not found.).

Using the buttons in the bottom bar of the configuration window **18**, the configured parameters can be sent to the module, saved on the PC, saved on the device, or reset to default values.



Configuration window showing EtherNet/IP setup parameters:

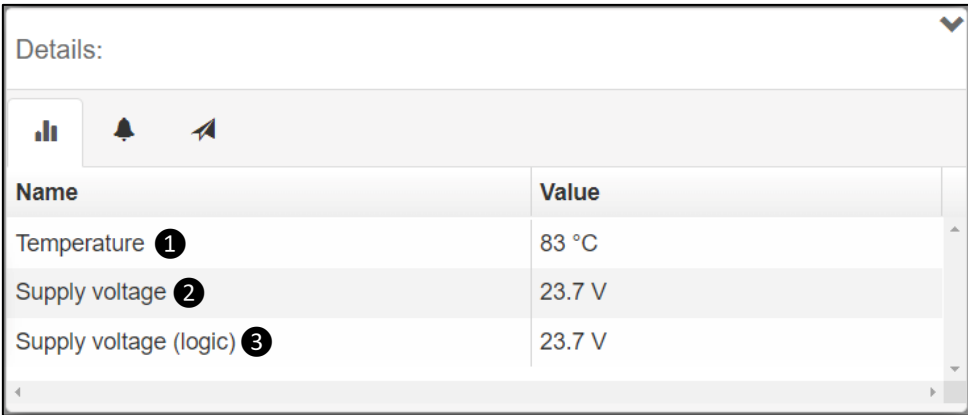
- Devices group: Ethernet/IP Sala
- Device name: Ethernet/IP 01
- Setup FieldBus: EthernetIP
- Station name [min:1] : Cx4_EIP
- Internet protocol address : 192.168.10.4
- Mask : 255.255.255.0
- Gateway : 0.0.0.0
- Buttons: Reset, Save on PC, Send, Save on device

9.1.2 Details

9.1.2.1 Variables

The first tab of the details page deals shows the variables that are monitored by the CX4 module.

- 1 Internal temperature of the module.
- 2 Power voltage that supplies the sub-bases of the solenoid valves: the measurement is made by the first sub-base connected (position 1) and is sent via serial communication. If there are no valves connected, this voltage is not displayed.
- 3 Logic voltage that powers the module circuit board. Without this supply voltage, the entire system is without power and, therefore, turned off.








Details:	
Name	Value
Temperature 1	83 °C
Supply voltage 2	23.7 V
Supply voltage (logic) 3	23.7 V

9.1.2.2 Alarms

The second tab on the details page displays possible CX4 module alarms.

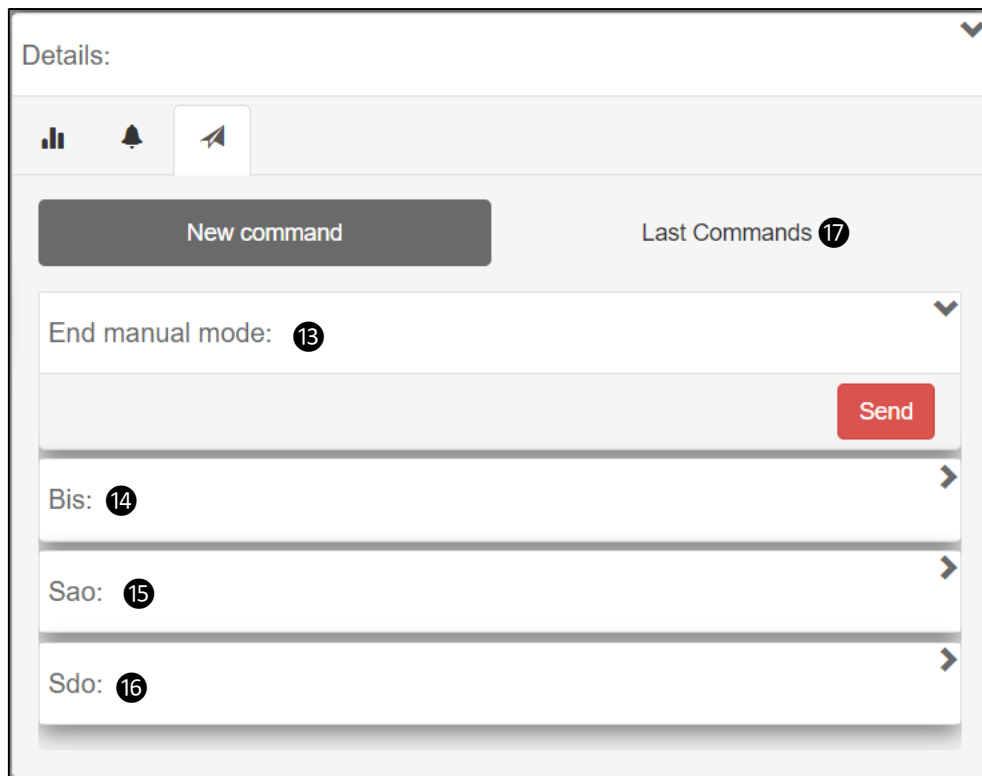
- ④ No mapping: indicates that there are no accessory modules connected to the CX4 module.
- ⑤ Valve mapping error: this can occur if the positions of the sub-bases of the solenoid valves have been changed, moving them from their original position or adding new ones, or if a sub-base fails to respond to the mapping request from the CX4 module.
- ⑥ CX4 module overheating.
- ⑦ Supply voltage of the CX4 module lower than the voltage given in the specifications.
- ⑧ I/O module mapping error: this can occur if the positions of the I/O modules have been changed, moving them from their original position or adding new ones, or if an I/O module fails to respond to the mapping request from the CX4 module.
- ⑨ Fatal error on fieldbus: this occurs if the fieldbus protocol stack is incorrect.
- ⑩ Configuration error
- ⑪ No valve mapping: indicates that there are no solenoid valve sub-bases connected to the CX4 module.
- ⑫ No I/O module mapping: indicates that there are no I/O modules connected to the CX4 module.

Details: 		
  		
Event Name	Status ▾	Event Onset
Mapping absent ④	!	
Mapping valves error ⑤	!	
Overheating CX4 module ⑥	!	
Undervoltage CX4 module ⑦	!	
Mapping I/O modules error ⑧	!	
Fieldbus fatal error ⑨	!	
Configuration error ⑩	⚠	
Valves absent ⑪	!	
I/O modules absent ⑫	!	


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9.1.2.3 Commands

The third tab of details on the CX4 module shows the commands that can be sent via UVIX to the device. The Manual Mode command **13** allows you to control the system manually from UVIX, sending configuration parameters to the CX4 module and to the individual connected accessory modules. In manual mode, you can command the modules that include outputs (if present), such as the solenoid valves **14** (par. 9.2.3), digital outputs **15** (par. 9.4.3) and analogue outputs **16** (par. 9.6.3). The history of the commands sent to the CX4 module from when communication with UVIX was started can be viewed under Last Commands **17**.



NOTE. If there are solenoid valve sub-bases connected to the CX4 module, the valve information can be reset at any time, without activating manual mode.

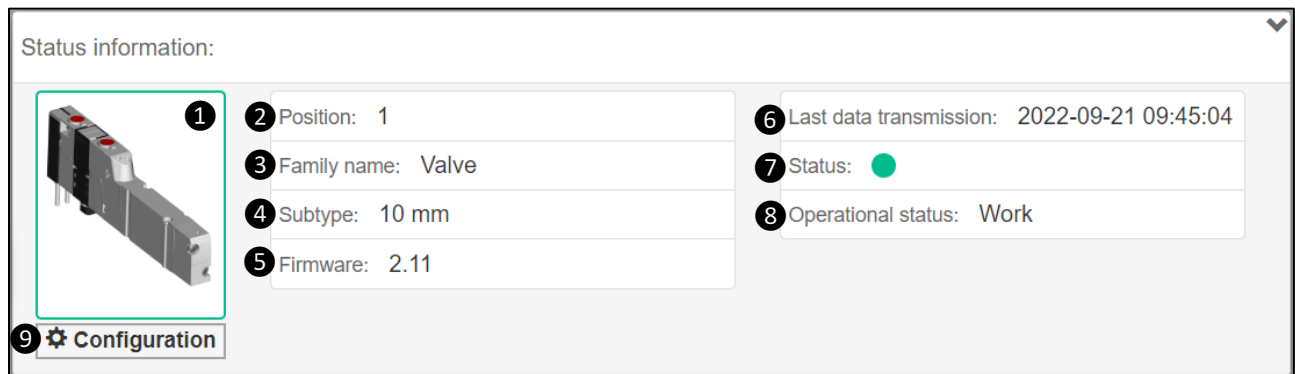
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9.2 Series D coil valves and sub-bases

9.2.1 Status information

On the first page of UVIX, you can select one of the solenoid valves connected to the CX4 module in the configuration of a Series D valve island to view the general information of the individual sub-base.

- ❶ Identification images of the coil valve mounted on the sub-base.
- ❷ Position of the sub-base in the assigned valve island after mapping.
- ❸ Name of the accessory module family: Valve.
- ❹ Solenoid valve family sub-type: 10 mm, 16 mm, 25 mm.
- ❺ Firmware version.
- ❻ Date and time of the last transmission of the variables between the sub-base and UVIX.
- ❼ General status of the solenoid valve: ● *Not available*, ● *OK*, ● *Alarm*.
- ❽ Operating status of the sub-base:
 - *Init* → initialization (mapping and configuration of parameters).
 - *Work* → normal operation.
 - *Error* → sub-base error.



9.2.1.1 Configuration of Series D coil valve sub-base

From the status information page, you can configure certain operating-related parameters of the solenoid valves ❹.

- ❿ Enable/disable the alarms that the valve can generate (default: all alarms enabled).
- ⓫ Enable/disable the Failsafe for each individual pilot: *Yes enabled*, *No disabled* (default).
- ⓬ Set the Failsafe status for each pilot for which the Failsafe has been enabled: *On* pilot activated, *Off* pilot deactivated (default).
- ⓭ Set the behaviour of the valve failure error (Coil Fault): *Latched*, *Not Latched* (default).
- ⓮ The buttons in the bottom bar of the tab allow you to send the configuration parameters to the module, save them on the PC, save them on the device or reset them to default values.

Configuration

Devices group: Camozzi
Device name: Series D fieldbus
Slave: 1 - Valve

Valve alarms enable

2022-01-28 11:32:57

5 selected ▾

10

Failsafe enable

2022-01-28 11:32:57

Pilot 1
No Yes

Pilot 2
No Yes

11

Failsafe status

2022-01-28 11:32:57

Pilot 1
Off On

Pilot 2
Off On

12

? Alarm mode

2022-01-28 11:32:57

☒ Not latched
☐ Latched

13

Reset

14

Save on PC

Send

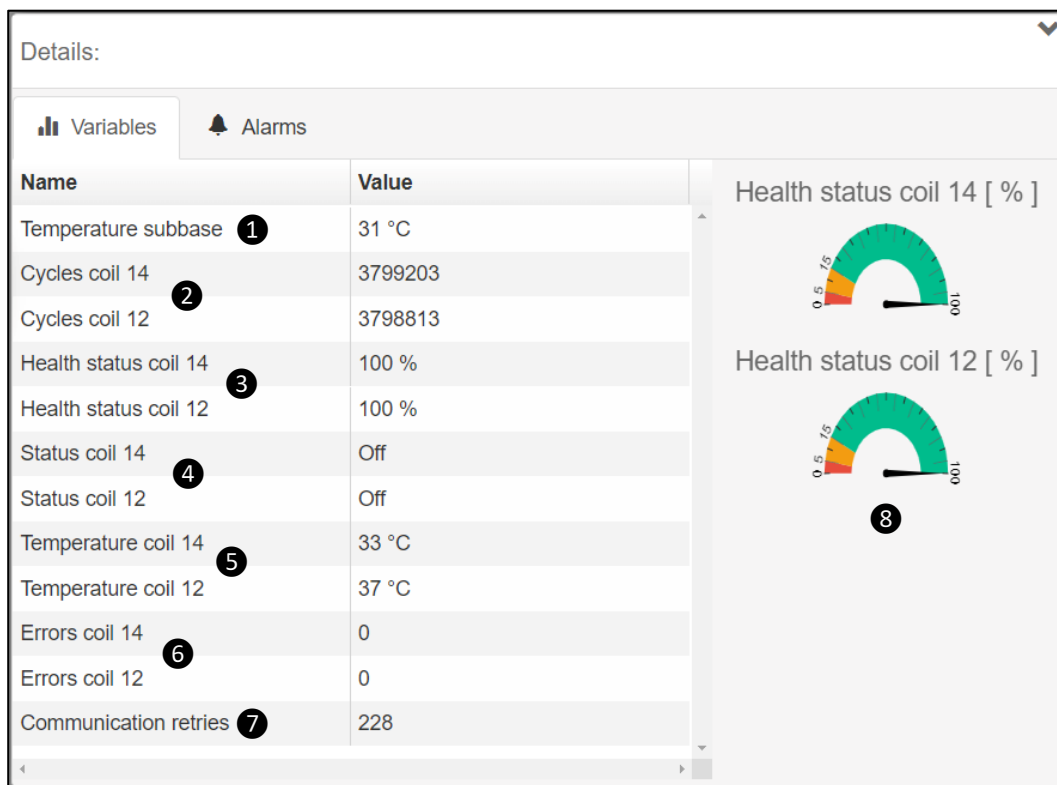
Save on device

9.2.2 Details

9.2.2.1 Variables

The first tab on the details page shows the variables that are monitored by the sub-base of an individual solenoid valve. These variables can be reset using the commands by selecting the CX4 module to which the sub-bases are connected (par. 9.2.3).
















- ❶ Sub-base temperature.
- ❷ Cycles performed by the pilots in position 14 and position 12.
- ❸ Percentage health status of the pilots in position 14 and position 12.
- ❹ Status of the pilots in position 14 and position 12 (*On/Off*).
- ❺ Temperature of the pilots in position 14 and position 12.
- ❻ Errors of the pilots in position 14 and position 12.
- ❼ Communication errors between the CX4 module and the selected sub-base.
- ❽ Gauge indicators that show graphically the percentage health status of the two pilots.



9.2.2.2 Alarms

The second details tab displays the alarms of the sub-base of the selected valve.

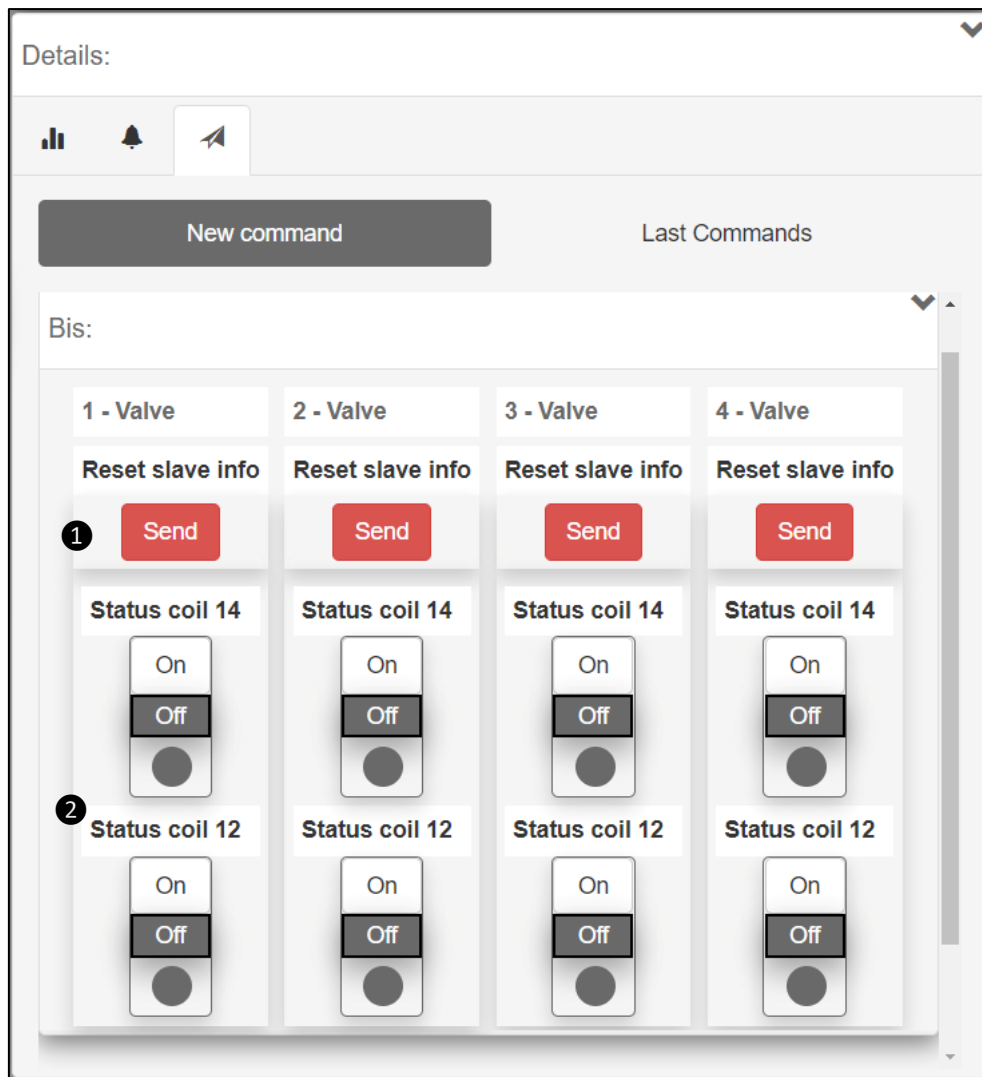
- 8 Communication alarm due to communication failure between CX4 module and sub-base.
- 9 Sub-base overheating.
- 10 Overheating of the pilots in position 14 and position 12.
- 11 Overcurrent of the pilots in position 14 and position 12.
- 12 Alarm - solenoid valves closed in position 14 and position 12.
- 13 Energization malfunction of the solenoid pilots in position 14 and position 12.
- 14 Alarm - configuration of sub-base parameters.
- 15 Replace valve warning.


Details: 		
<div>  Variables  Alarms </div>		
Event Name	Status ▾	Event Onset
Communication alarm 8		
Overheating subbase 9		
Overheating coil 14 10		
Overheating coil 12		
Overcurrent coil 14 11		
Overcurrent coil 12		
Interrupted coil 14 12		
Interrupted coil 12		
Fault coil 14 13		
Fault coil 12		
Configuration alarm 14		
Valve substitution 15		

9.2.3 Commands

On the main page of the CX4 module (par.0), there is a tab showing the commands for the solenoid valves. In particular, you can reset the valve information ❶ (cycles, errors, health status). This operation needs to be performed when the valve connected to the sub-base is replaced and can also be performed in normal working mode.

You can also control the individual pilots (position 12 and 14) of the solenoid valves ❷. For this operation, the island must be in manual mode.



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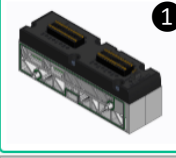
9.3 Digital Input Modules

9.3.1 Status information

On the first page of UVIX, select one of the digital inputs connected to the CX4 module to view the general information of the accessory module.

- ❶ Identification images of the digital input module (8 or 16 channels).
- ❷ Module position assigned after mapping.
- ❸ Name of the accessory module family: *Digital Input*.
- ❹ Subtype of the family of the digital input module: 8 CH, 16 CH.
- ❺ Firmware version.
- ❻ Date and time of the last transmission of the variables between the module and UVIX.
- ❼ General status of the module: ● *Not available*, ● *OK*, ● *Alarm*.
- ❽ Operating status of the module:
 - *Init* → initialization (mapping and configuration of parameters).
 - *Work* → normal operation.
 - *Error* → module error.

Status information: ▼



❶

❷ Position: 12

❸ Family name: Digital Input

❹ Subtype: 16 CH

❺ Firmware: 1.11

❻ Last data transmission: 2022-09-21 09:40:57

❼ Status: ●

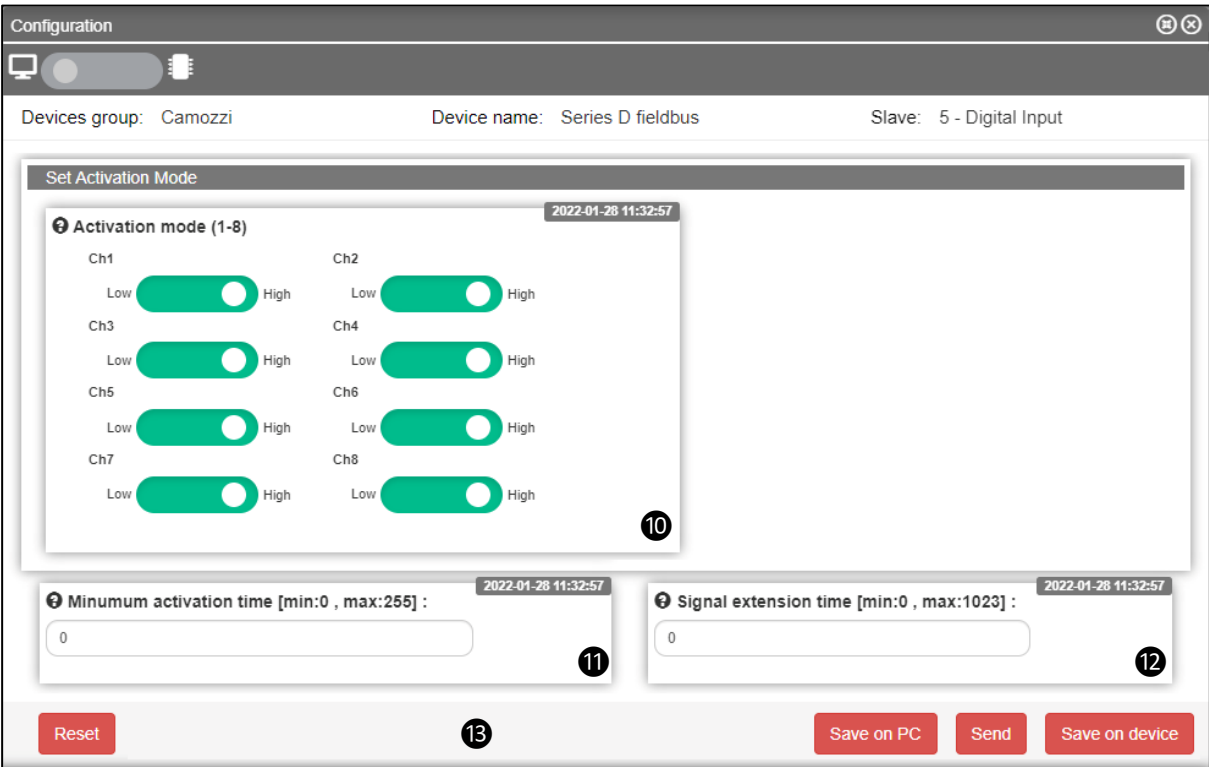
❽ Operational status: Work

❹ ⚙ Configuration

9.3.1.1 Configuration of digital input modules

From the status information page, you can configure certain operating-related parameters of the digital input modules ❹.

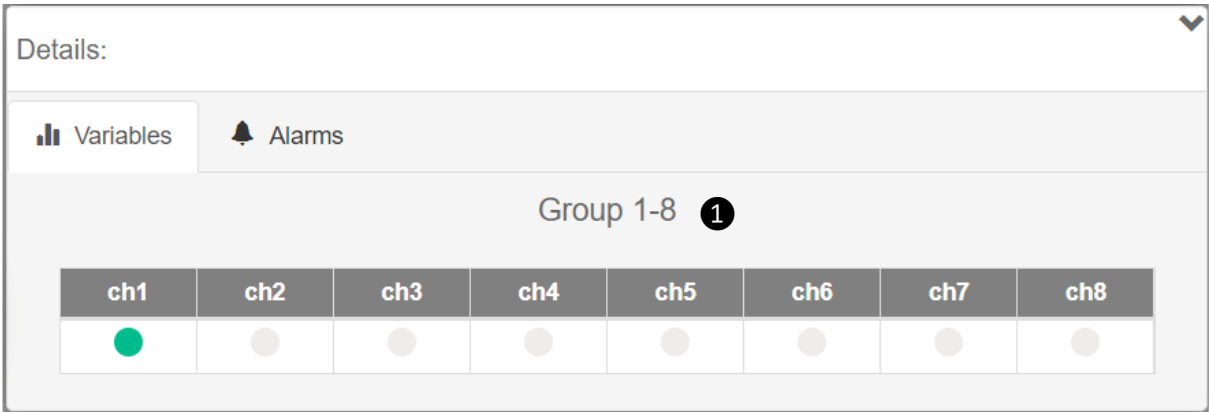
- ❿ Parameter for the polarity of each channel, High or Low (default).
- ⓫ Minimum input level activation time in milliseconds (anti-bounce filter, default: 0).
- ⓬ Minimum input rereading time in milliseconds (default: 0).
- ⓭ Using the buttons in the bottom bar of the configuration window, the configured parameters can be sent to the module, saved on the PC, saved on the device or reset to default values.



9.3.2 Details

9.3.2.1 Variables








The first tab on the details page displays the status of the digital inputs ①: ● active, ● not active.




9.3.2.2 Alarms

The second details tab displays the alarms of the digital input module.

- ② Alarm - communication failure between the digital input module and the CX4 module.
- ③ Alarm - configuration of module parameters.
- ④ Short-circuit of at least one digital input belonging to an input group. This alarm can be divided into two groups for modules with 8 channels or into four groups for modules with 16 channels.

Details: 		
<div>  Variables  Alarms </div>		
Event Name	Status ▾	Event Onset
Communication alarm ②		
Configuration alarm ③		
Short circuit Group 0-3		
Short circuit Group 4-7 ④		

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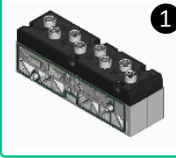
9.4 Digital Output Modules

9.4.1 Status information

On the first page of UVIX, select one of the digital outputs connected to the CX4 module to view the general information of the accessory module.

- ❶ Identification images of the digital output module (8 or 16 channels).
- ❷ Module position assigned after mapping.
- ❸ Name of the accessory module family: *Digital Output*.
- ❹ Subtype of the family of the digital output module: 8 CH, 16 CH.
- ❺ Firmware version.
- ❻ Date and time of the last transmission of the variables between the module and UVIX.
- ❼ General status of the module: ● *Not available*, ● *OK*, ● *Alarm*.
- ❽ Operating status of the module:
 - *Init* → initialization (mapping and configuration of parameters).
 - *Work* → normal operation.
 - *Error* → module error.

Status information: ▼



❶

❷ Position: 14

❸ Family name: Digital Output

❹ Subtype: 8 CH

❺ Firmware: 1.10

❻ Last data transmission: 2022-09-21 09:43:00

❼ Status: ●

❽ Operational status: Work

❾ Configuration

9.4.1.1 Configuration of digital output modules

From the status information page, you can configure certain operating-related parameters of the digital output modules ❾.

- ❿ Enable output: No disabled, Yes enabled (default).
- ⓫ Set the type of individual output channel: type N, type P (default).
- ⓬ Enable the individual functions related to the whole module, see the detection of no load by the power driver.
- ⓭ Set the PWM for individual outputs: Yes enabled, No disabled (default).
- ⓮ Enable the protection failsafe, which can be set for the individual outputs: Yes enabled, No disabled (default).
- ⓯ Failsafe status, which can be set for the individual outputs: *On*, *Off* (default).
- ⓰ Using the buttons in the bottom bar of the configuration window, the configured parameters can be sent to the module, saved on the PC, saved on the device or reset to default values.

Configuration

Devices group: Camozzi
Device name: Series D fieldbus
Slave: 6 - Digital Output

Set enable out channel

Enable channels (1-8)
2022-01-28 11:32:57

Channel 1
No ☒ Yes

Channel 2
No ☒ Yes

Channel 3
No ☒ Yes

Channel 4
No ☒ Yes

Channel 5
No ☒ Yes

Channel 6
No ☒ Yes

Channel 7
No ☒ Yes

Channel 8
No ☒ Yes

Set type out channel

Channel Type (1-8)
2022-01-28 11:32:57

Channel 1
N ☒ P

Channel 2
N ☒ P

Channel 3
N ☒ P

Channel 4
N ☒ P

Channel 5
N ☒ P

Channel 6
N ☒ P

Channel 7
N ☒ P

Channel 8
N ☒ P

Module Settings
2022-01-28 11:32:57

Enable alarm n.c.
No ☐ Yes

Set enable PWM

Enable PWM (1-8)
2022-01-28 11:32:57

Channel 1
No ☐ Yes

Channel 2
No ☐ Yes

Channel 3
No ☐ Yes

Channel 4
No ☐ Yes

Channel 5
No ☐ Yes

Channel 6
No ☐ Yes

Channel 7
No ☐ Yes

Channel 8
No ☐ Yes

Set enable failsafe channel

Enable failsafe (1-8)
2022-01-28 11:32:57

Channel 1
No ☒ Yes

Channel 2
No ☐ Yes

Channel 3
No ☐ Yes

Channel 4
No ☐ Yes

Channel 5
No ☐ Yes

Channel 6
No ☐ Yes

Channel 7
No ☐ Yes

Channel 8
No ☐ Yes

Set state failsafe channel

Failsafe state (1-8)
2022-01-28 11:32:57

Channel 1
Off ☐ On

Channel 2
Off ☐ On

Channel 3
Off ☐ On

Channel 4
Off ☐ On

Channel 5
Off ☐ On

Channel 6
Off ☐ On

Channel 7
Off ☐ On

Channel 8
Off ☐ On

Reset

16

Save on PC

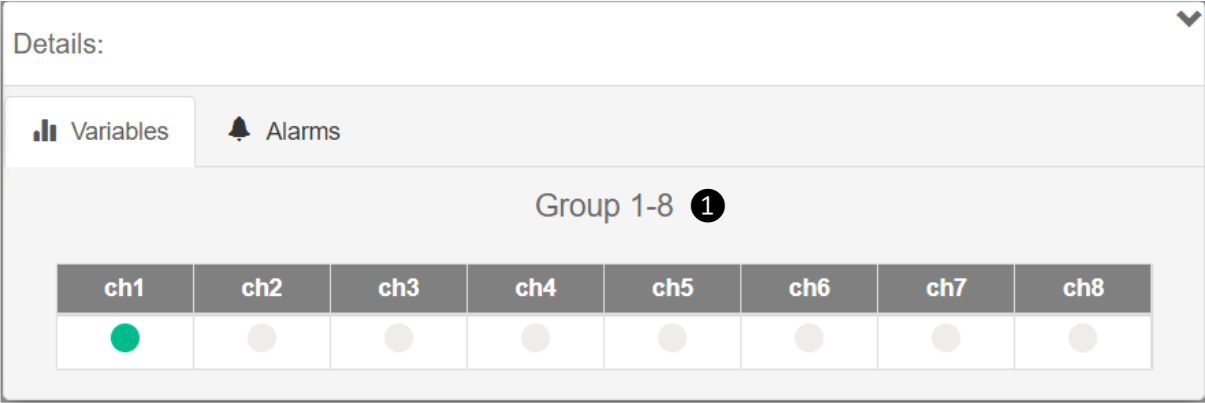
Send

Save on device

9.4.2 Details

9.4.2.1 Variables























The first tab on the details page displays the status of the digital outputs ①: ● active, ● not active.



9.4.2.2 Alarms

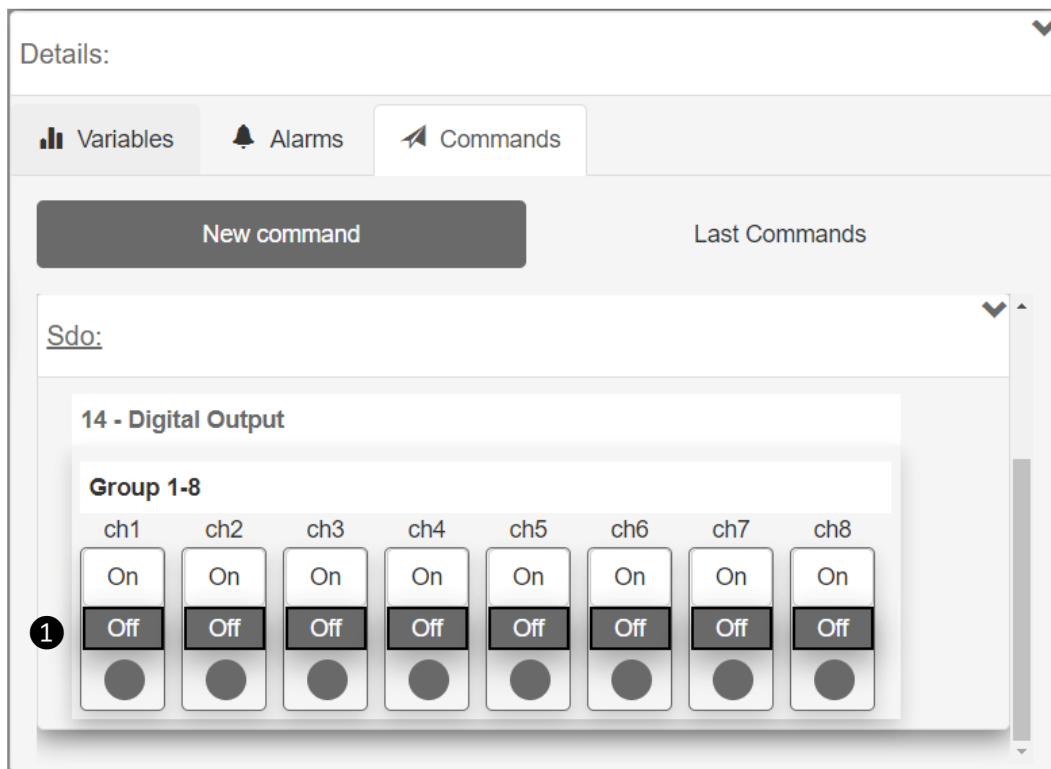
The second details tab displays the alarms of the digital output module.


- **2** Alarm - communication failure between the digital input module and the CX4 module.
- **3** Alarm - configuration of module parameters.
- **4** No external power supply, required to power the digital outputs.
- **5** The supply voltage is less than 4.5V.
- **6** Circuit open on an output channel.
- **7** Short circuit on an output channel.

Details: ▼		
<div> <div> Variables</div> <div> Alarms</div> </div>		
Event Name	Status ▼	Event Onset
Communication alarm 2		
Configuration alarm 3		
Zero Voltage Power Supply 4		
Under Voltage Power Supply 5		
Open Load Channel 1		
Open Load Channel 2		
Open Load Channel 3		
Open Load Channel 4		
Open Load Channel 5 6		
Open Load Channel 6		
Open Load Channel 7		
Open Load Channel 8		
Short Circuit Channel 1		
Short Circuit Channel 2		
Short Circuit Channel 3		
Short Circuit Channel 4		
Short Circuit Channel 5 7		
Short Circuit Channel 6		
Short Circuit Channel 7		
Short Circuit Channel 8		

9.4.3 Commands

On the main page of the CX4 module (par.0) there is a tab showing the commands to pilot the individual channels of the digital outputs **1**. This tab is only visible in manual mode and if it has at least one digital output module.







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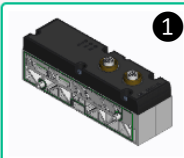
9.5 Analogue Input Modules

9.5.1 Status information

On the first page of UVIX, select one of the analogue inputs connected to the CX4 module to view the general information of the accessory module.

- ❶ Identification images of the analogue input module.
- ❷ Module position assigned after mapping.
- ❸ Name of the accessory module family: *Analogue Input*.
- ❹ Subtype of the family of the analogue input module: RTD, Thermocouple, Bridge, Voltage/Current.
- ❺ Firmware version.
- ❻ Date and time of the last transmission of the variables between the module and UVIX.
- ❼ General status of the module:  *Not available*,  *OK*,  *Alarm*.
- ❽ Operating status of the module:
 - *Init* → initialization (mapping and configuration of parameters).
 - *Work* → normal operation.
 - *Error* → module error.

Status information: 



❶


❷ Position: 8

❸ Family name: Analog Input


❹ Subtype: RTD


❺ Firmware: 1.07

❻ Last data transmission: 2022-09-21 08:59:51

❼ Status: 

❽ Operational status: Work

❾  Configuration

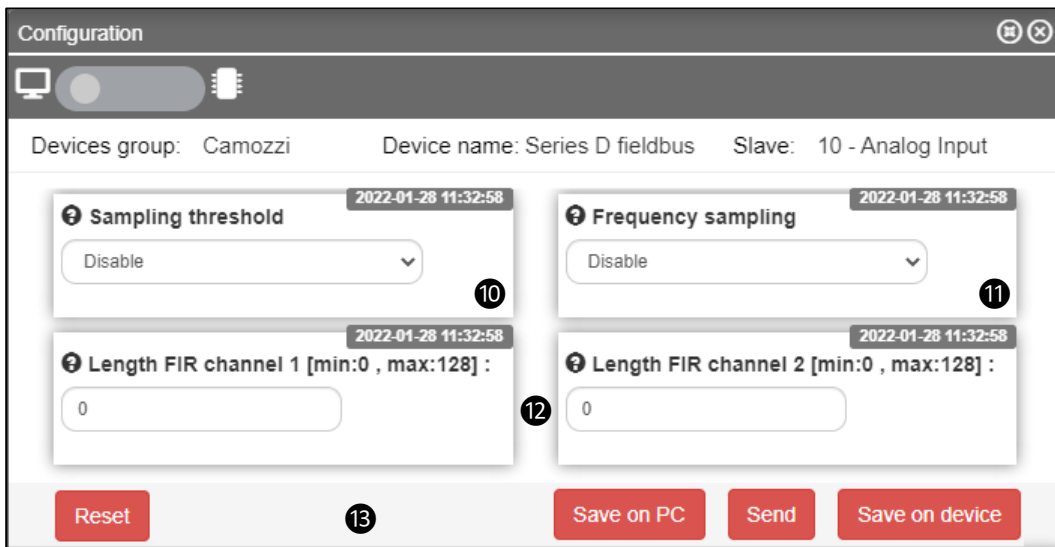
	Series D Valve Island Fieldbus and Series CX4 EtherNet/IP	5000041281
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9.5.1.1 Configuration of analogue input modules

From the status information page, you can configure certain operating-related parameters of the analogue input modules ⑨.

Some of these parameters are specific to individual subtypes, while others are common to all subtypes of the analogue input family.

- ⑩ Enable threshold-based transmission (default: *Disable*).
- ⑪ Enable frequency-based transmission (default: *Disable*).
- ⑫ Length of the impulse response of the FIR filter on channel 1 and channel 2.
- ⑬ Using the buttons in the bottom bar of the configuration window, the configured parameters can be sent to the module, saved on the PC, saved on the device or reset to default values.



The screenshot shows the 'Configuration' window for a CAMOZZI device. At the top, it identifies the 'Devices group' as 'Camozzi', the 'Device name' as 'Series D fieldbus', and the 'Slave' as '10 - Analog Input'. Below this, there are four configuration panels, each with a timestamp of '2022-01-28 11:32:58'. The first panel, 'Sampling threshold' (⑩), has a dropdown menu set to 'Disable'. The second panel, 'Frequency sampling' (⑪), also has a dropdown menu set to 'Disable'. The third panel, 'Length FIR channel 1 [min:0 , max:128] : ' (⑫), has a text input field set to '0'. The fourth panel, 'Length FIR channel 2 [min:0 , max:128] : ' (⑫), also has a text input field set to '0'. At the bottom of the window, there is a bar with four buttons: 'Reset' (⑬), 'Save on PC', 'Send', and 'Save on device'.

- ⑭ Type of RTD for channel 1 and for channel 2
- ⑮ Number of wires for the RTD sensor on channel 1 and channel 1.
- ⑯ Type of Thermocouple for channel 1 and for channel 2.
- ⑰ Type of Bridge for channel 1 and for channel 2.
- ⑱ Type of Voltage/Current module for channel 1 and for channel 2

Configuration

Devices group: Camozzi Device name: Series D fieldbus Slave: 10 - Analog Input

2022-01-28 11:32:58

Sensor Type RTD channel 1

PT1000 (385)

2022-01-28 11:32:58

Sensor Type RTD channel 2

PT100 (385)

2022-01-28 11:32:58

Number of wires RTD channel 1

2 wires

2022-01-28 11:32:58

Number of wires RTD channel 2

4 wires

Reset Save on PC Send Save on device

Configuration

Devices group: Camozzi Device name: Series D fieldbus Slave: 11 - Analog Input

2022-01-28 11:32:58

Sensor Type TH channel 1

K

2022-01-28 11:32:58

Sensor Type TH channel 2

T

Reset Save on PC Send Save on device

Configuration

Devices group: default group Device name: Series D fieldbus Slave: 3 - Analog Input

2022-09-14 13:24:09

Bridge factor channel 1 [min:0 , max:255] :

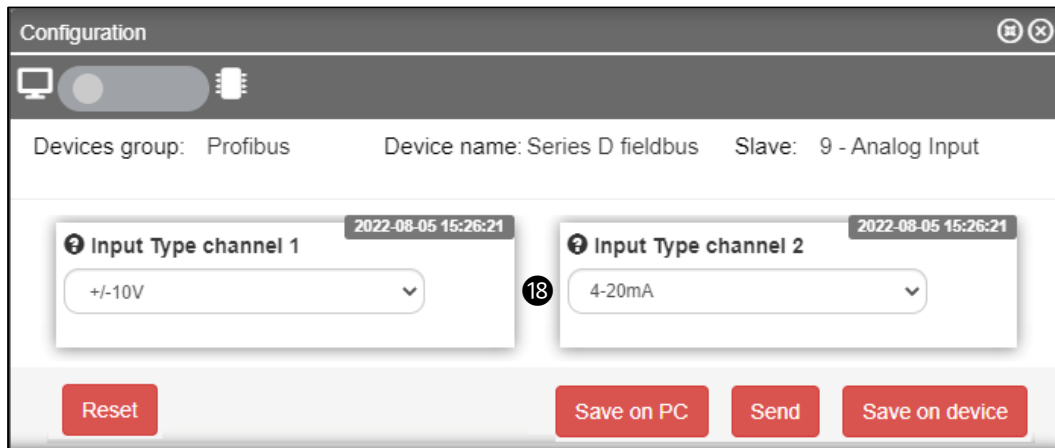
0

2022-09-14 13:24:09

Bridge factor channel 2 [min:0 , max:255] :

0

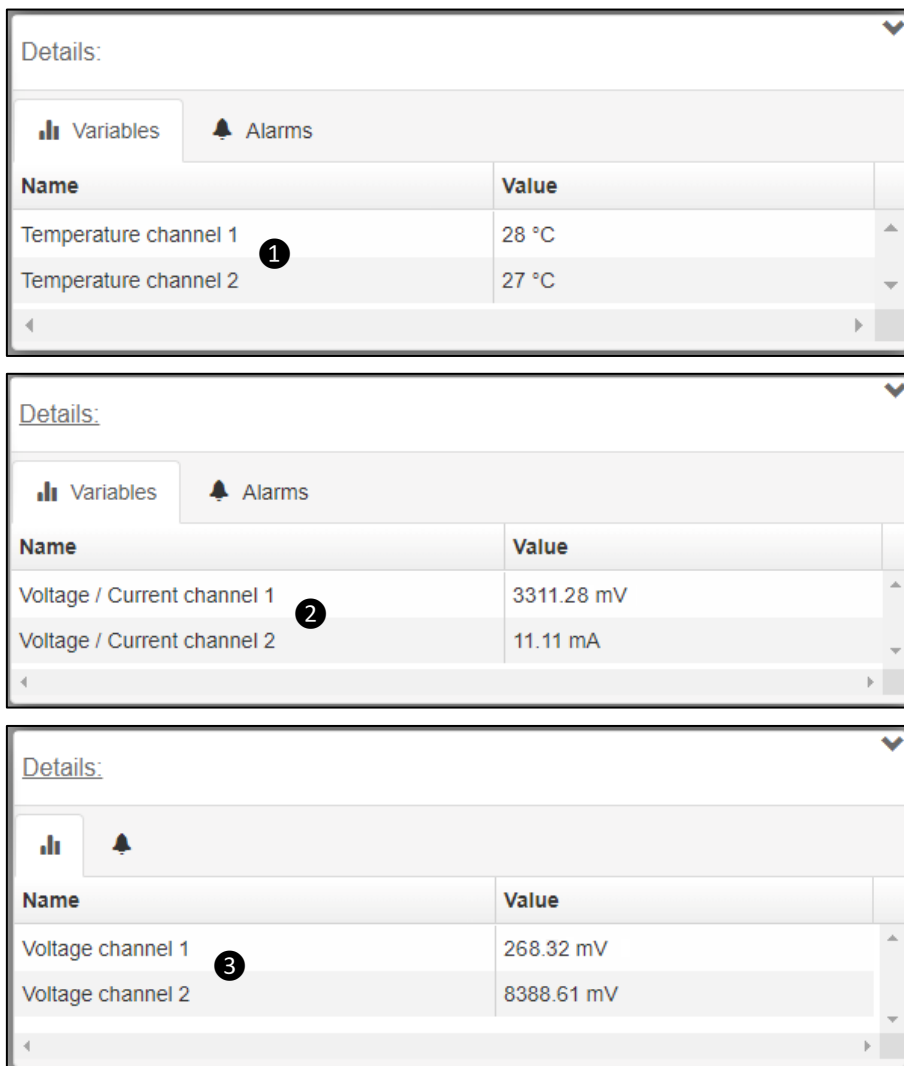
Reset Save on PC Send Save on device



9.5.2 Details

9.5.2.1 Variables

The first tab on the details page displays the variables monitored by the analogue input module for both channels: temperatures **1** for RTD and Thermocouples, currents or voltages **2** for Voltage/Current modules and voltages **3** for the Bridges.




9.5.2.2 Alarms

The second details tab displays the alarms of the analogue input module.

- 4 Malfunction of the sensor connected to channel 1.
- 5 Bridge sensor connected to channel 1 missing or faulty (alarm for bridges only).
- 6 Communication error with the internal ADC converter, which measures the relevant physical quantities.
- 7 Error in 3.3V logic supply voltage.
- 8 Malfunction of the sensor connected to channel 2.
- 9 Bridge sensor connected to channel 2 missing or faulty (alarm for bridges only).
- 10 Alarm of communication between the analogue input module and the CX4 module.
- 11 Alarm - configuration during parameterization.

Details:

<div> Variables Alarms </div>		
Event Name	Status ▾	Event Onset
Sensor fault channel 1 4	!	
Missing bridge channel 1 5	!	
ADC communication error 6	!	
RESDCDC error 7	!	
Sensor fault channel 2 8	!	
Missing bridge channel 2 9	!	
Communication alarm 10	!	
Configuration alarm 11	!	

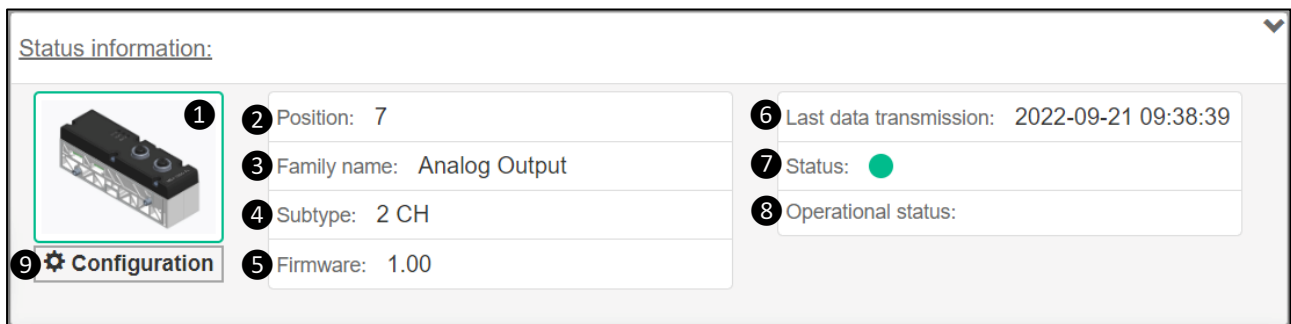
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9.6 Analogue Output Modules

9.6.1 Status information

On the first page of UVIX, select one of the analogue outputs connected to the CX4 module to view the general information of the accessory module.

- ❶ Identification images of the analogue output module.
- ❷ Module position assigned after mapping.
- ❸ Name of the accessory module family: *Analogue Output*.
- ❹ Subtype of the family of the analogue output module: 2 CH.
- ❺ Firmware version.
- ❻ Date and time of the last transmission of the variables between the analogue output module and UVIX.
- ❼ Date and time of the last transmission of the variables between the module and UVIX.
- ❽ General status of the module: ● *Not available*, ● *OK*, ● *Alarm*.
- ❾ Operating status of the module:
 - *Init* → initialization (mapping and configuration of parameters).
 - *Work* → normal operation.
 - *Error* → module error.


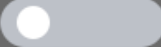




9.6.1.1 Configuration of analogue output modules

From the status information page, you can configure certain operating-related parameters of the digital output modules ❾.

- ❿ Type of analogue output (voltage or current) on channel 1.
- ⓫ Type of analogue output (voltage or current) on channel 2.
- ⓬ Enable Failsafe for channel 1: Yes enabled, No disabled (default).
- ⓭ Enable Failsafe for channel 2: Yes enabled, No disabled (default).
- ⓮ Failsafe value if enabled on the corresponding channel (mV/mA).

Configuration

Devices group: Camozzi
Device name: Series D fieldbus
Slave: 7 - Analog Output

Function channel 1
2022-09-14 08:55:29

☐ Off
☒ 0..10V
☐ 0..5V
☐ 4..20mA
☐ 0..20mA


10

Function channel 2
2022-09-14 08:55:29

☐ Off
☐ 0..10V
☐ 0..5V
☒ 4..20mA
☐ 0..20mA

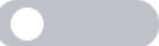
11

Failsafe enable channel 1
2022-09-14 08:55:29

No  Yes


12

Failsafe enable channel 2
2022-09-14 08:55:29

No  Yes

13

Failsafe value channel 1 [min:0 , max:10000] :
2022-09-14 08:55:29

0 4433 10000


14



Reset
Save on PC
Send
Save on device

9.6.2 Details

9.6.2.1 Variables

The first tab on the details page displays the analogue output module variables for both channels depending on how they are configured ①.

Details:

Name	Value
Channel 1 ①	3200.0 mV
Channel 2	11.700 mA

9.6.2.2 Alarms

The second tab on the details page displays the alarms of the analogue input module.

- **2** Alarm of communication between the analogue output module and the CX4 module.
- **3** Alarm - configuration during parameterization.
- **4** Alarm - open circuit on channel 1.
- **5** Alarm - open circuit on channel 2.
- **6** Alarm - overheating of analogue output module.
- **7** Alarm - short circuit of module supply voltage.
- **8** Alarm - module supply voltage too low.
- **9** Internal error.

Details:

Event Name	Status	Event Onset
Communication alarm 2	!	
Configuration alarm 3	!	
Channel 1 Open Load 4	!	
Channel 2 Open Load 5	!	
Board Over Heating 6	!	
Power Supply Short Circuit 7	!	
Power Supply Under Threshold 8	!	
Internal Error 9	!	

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9.6.3 Commands

On the main page of the CX4 module (par.0), there is a tab showing the commands for piloting the analogue output channels (① and ②) by setting the value of the output in the corresponding unit of measurement. This tab is only visible in manual mode and if it has at least one analogue output module.

Details:

Variables

Alarms

Commands

New command

Last Commands

Sao:

7 - Analog Output

Set Voltage / Current Ch1

Current value:

* New value [min: , max:]:

0

Send

①

Set Voltage / Current Ch2

Current value:


* New value [min: , max:]:

0

Send

②

121

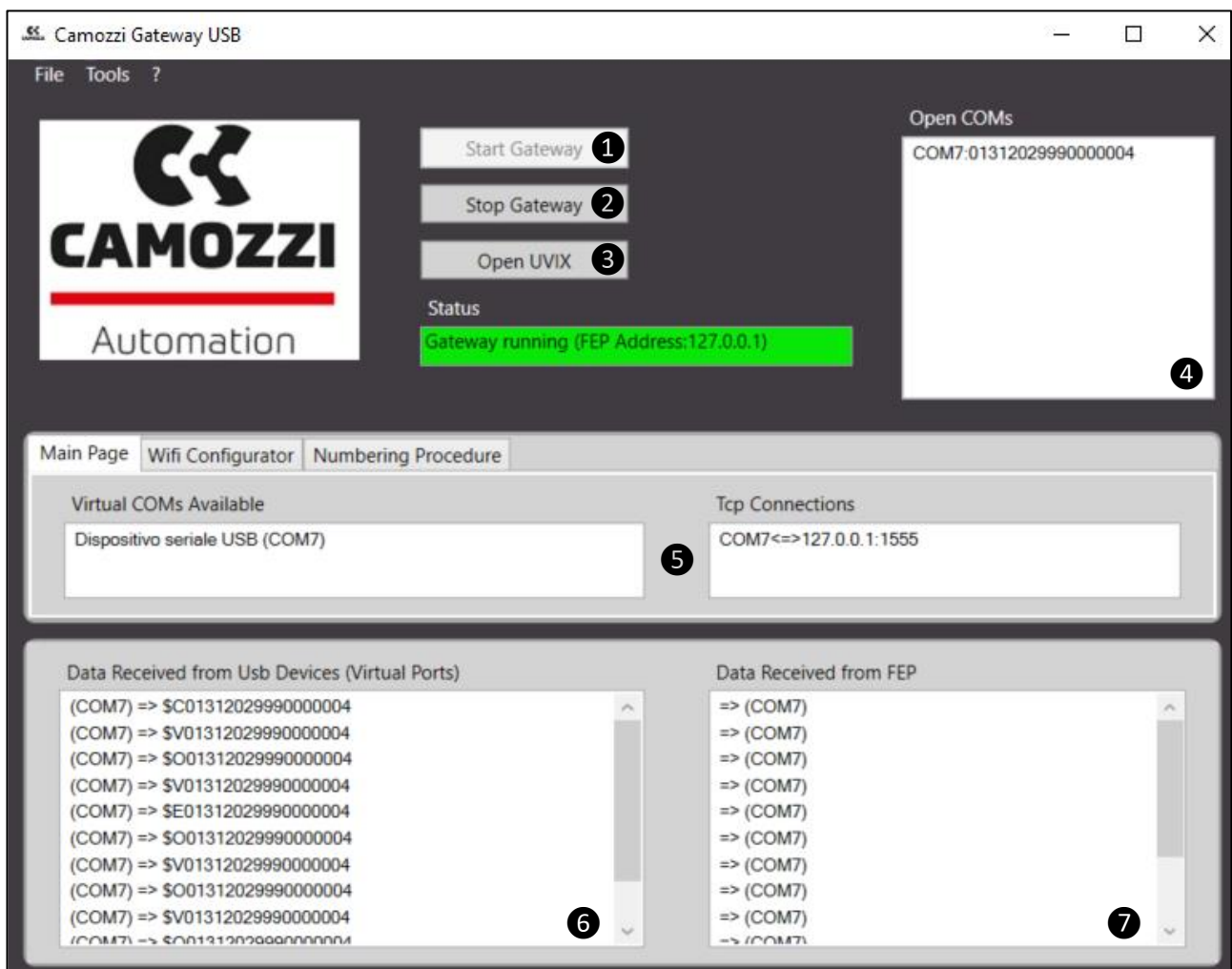
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9.7 UVIX USB Gateway

The CX4 module can be connected to a PC via a USB cable. This connection - subject to prior installation of UVIX on the PC - allows you to communicate with the module through the Camozzi USB Gateway.

9.7.1 Main page

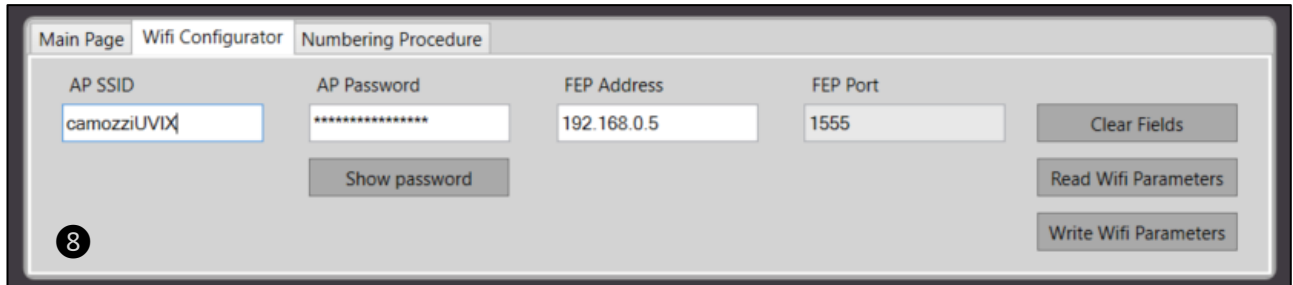
- ❶ Button to start up the USB Gateway and start communicating with the CX4 module.
- ❷ Button to stop communication with the CX4 module.
- ❸ Button to access the UVIX Browser interface (par. 9.1).
- ❹ COM ports connecting the CX4 modules.
- ❺ Virtual COM ports available and addresses of TCP connection for the connected COM ports.
- ❻ Data received from the COM port
- ❼ Data received on the FEP of the UVIX system.



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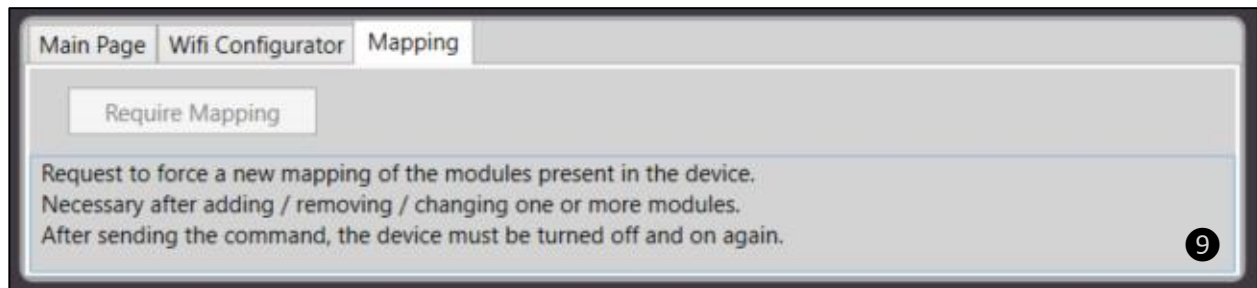
9.7.2 WiFi network configurator

In the tab for configuring the WiFi connection **8** (if available), you can read the parameters of the current connection and write any new ones for a new connection.



9.7.3 Mapping

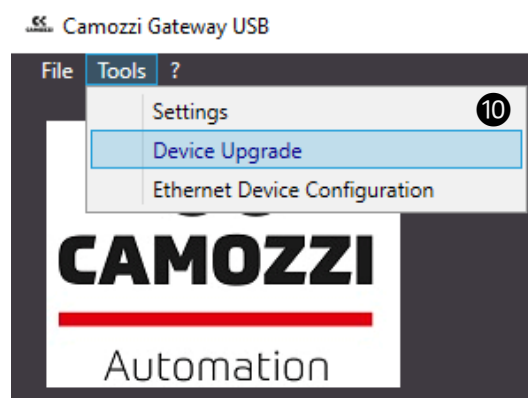
In the last tab that can be consulted via the USB gateway, you can send a mapping request to the CX4 module. The *Require Mapping* button remains pending until the next restart of the CX4 module.




9.7.4 Firmware update

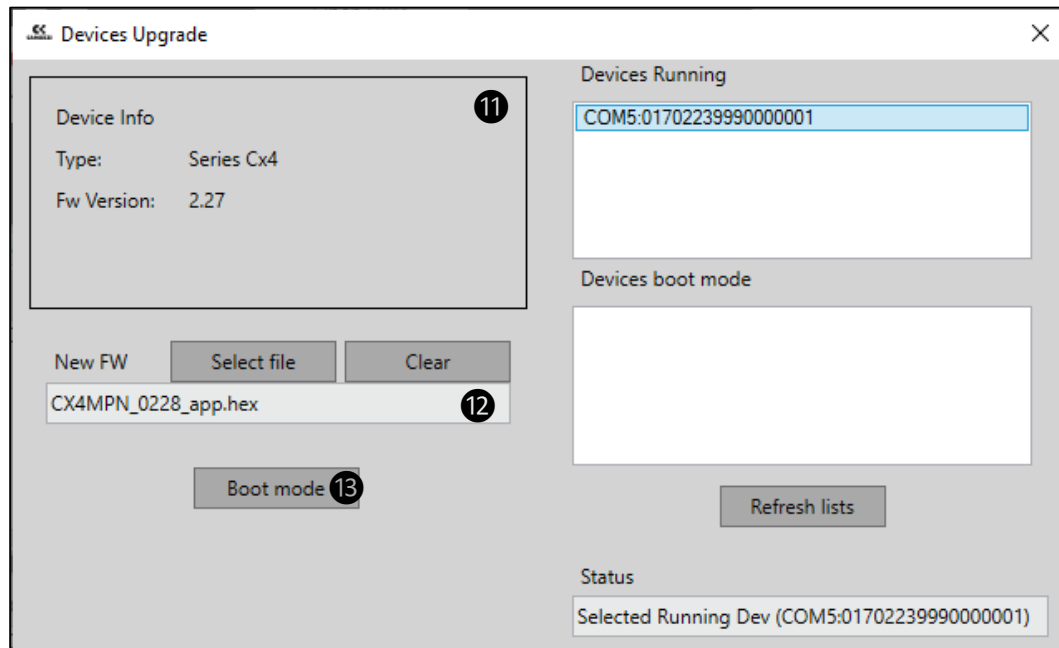
NOTE. Before carrying out this operation, you must contact Camozzi support.

The USB Gateway allows you to update the firmware of the CX4 module through the window found under Tools > Device Upgrade **10**.

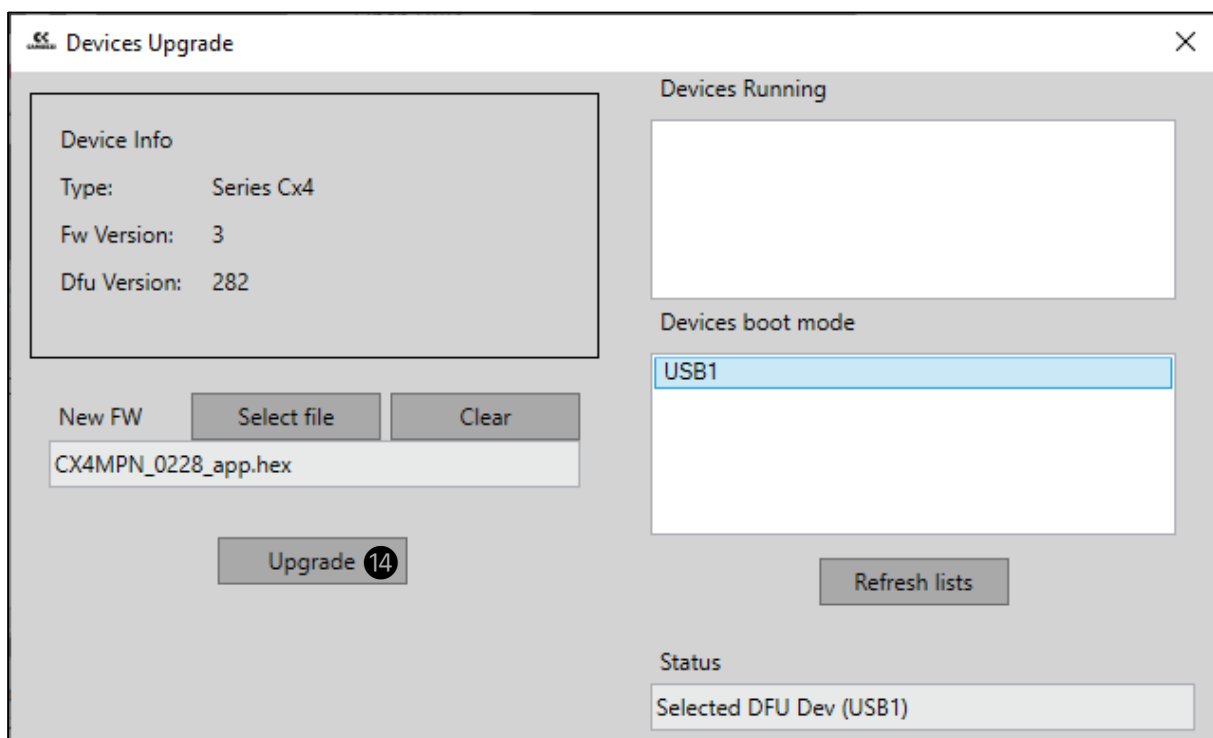



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The firmware update window indicates the current version **11** and allows you to select the new executable to upload to the module **12**. You must then put the device in Boot mode **13**.




Once in Boot mode, the module is ready to load the new firmware into memory **14**.

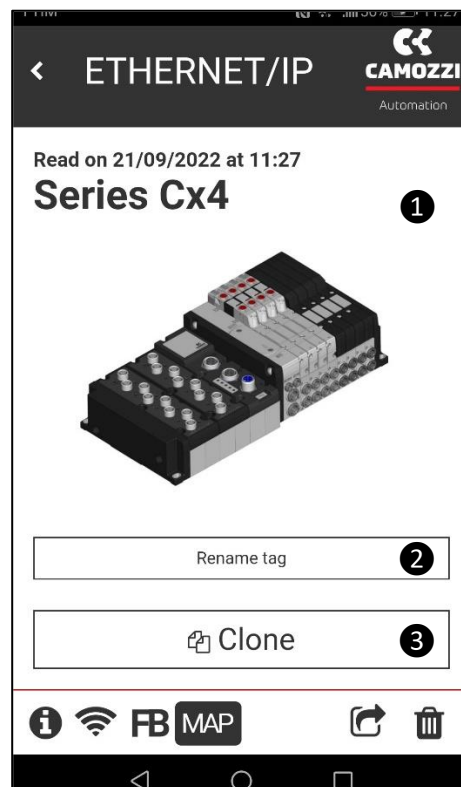


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10 NFCamApp

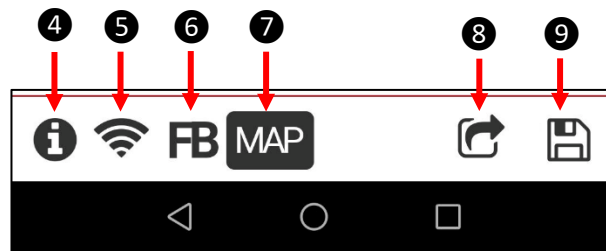
10.1 Main overview

NFCamApp is an app for smartphones (Android and iOS) which allows you to communicate - via NFC technology - with the CX4 module to obtain general information on the module and on the valve island (if configured as such). You can also use the app for module configuration. Once the CX4 module has been scanned, on the homepage, alongside the antenna positioned under the symbol , you can view the Camozzi series of the device **1** (*Series CX4*), assign a name to the device **2** and clone **3** the entire configuration (parameters of the CX4, the IO modules and the solenoid valve sub-bases) of the system, both in Stand Alone mode and as a Valve Island, to another system with a CX4 module compatible with the same fieldbus.



You can also access other pages of the app via the icons at the bottom of the homepage.

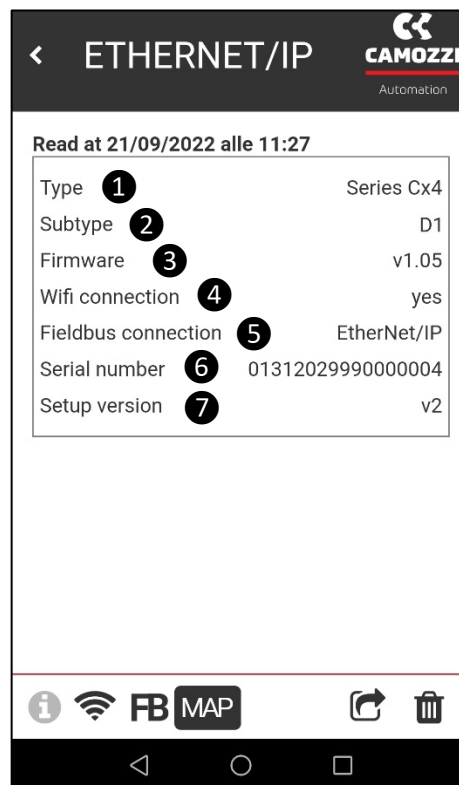
- **4** General module information page.
- **5** WiFi network information page (if available).
- **6** Bus information page.
- **7** Page to request new mapping.
- **8** Share module and/or island configuration.
- **9** Save the configuration of the scanned module or island.




10.2 General information


The first selectable page **i** displays general information about the scanned CX4 module.

- **1** Device family: *Series CX4*.
- **2** Subtype of the CX4 module family: *Stand-alone, D1, D2, D4 e D5*.
- **3** Firmware version.
- **4** Status of the WiFi connection: *Yes - WiFi module present, No - no WiFi module*.
- **5** Type of fieldbus: *EtherNet/IP*.
- **6** The serial number consists of 17 characters.
- **7** Version of the app.

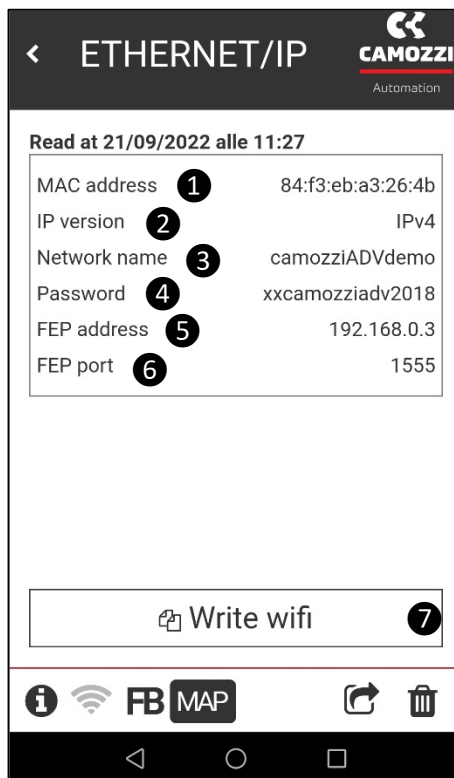



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10.3 WiFi information

The WiFi connection information page  is found only if there is a WiFi module connected inside the CX4 module, otherwise it is not displayed.

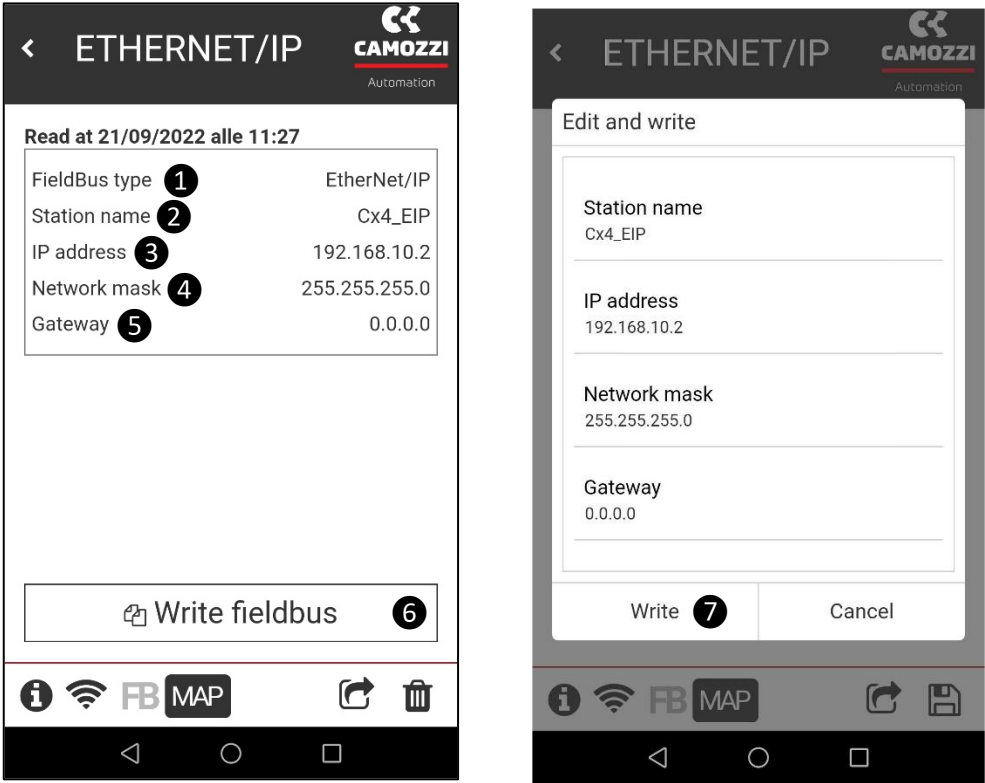
- ① MAC address of the WiFi module.
- ② IP version of the WiFi connection.
- ③ Name of the WiFi network to which the device is connected.
- ④ WiFi network password.
- ⑤ FEP address to which the devices are connected.
- ⑥ FEP port to which the device is connected.
- ⑦ Button for changing the data of the WiFi network to which you want to connect the module.



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10.4 Fieldbus configuration

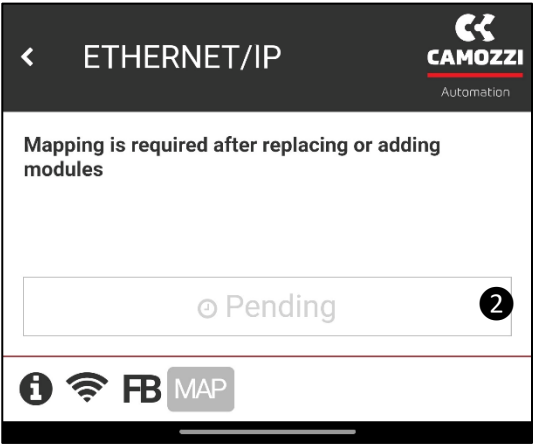
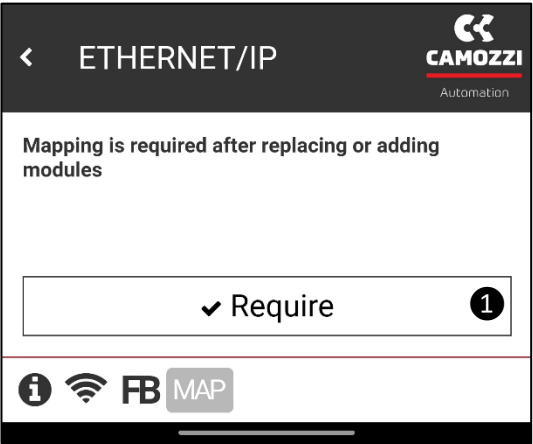
The EtherNet/IP protocol information page **FB** displays the name of the fieldbus **1** and also the name of the device on the network **2**, the IP address **3**, the mask **4** and the gateway **5** of the address. These parameters are configurable (par. Error! Reference source not found.) using the write button **6** and writing an NFC **7** through the app.




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10.5 Mapping request

The last available page  in the app, you can request a new system mapping using the button *Require* **1**. Once the request has been made, it remains pending (the button will change to *Pending* **2**) until the next restart of the CX4 module.



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